

N68-13796  
NASA-CR-91511

Blade Temperature Response of the  
Rotor Entry Vehicle

by

Latif M. Jiji



PREPARED UNDER GRANT NO. NGR 33-013-026  
BY THE CITY COLLEGE OF THE CITY UNIVERSITY  
OF NEW YORK, NEW YORK

FOR

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

AUGUST 1967

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#### **ACKNOWLEDGEMENT**

The author wishes to express his appreciation to the National Aeronautics and Space Administration for its financial support of this study, and to Mr. Allen D. Levin of Ames Research Center for his helpful discussions and comments. Credit is due to Messrs. Robert Kramer, Shashikant Mehta, Kenneth Rathjen and Andrzej Wojtkowski, graduate students at The City College of The City University of New York, for their valuable contributions in computer programming, numerical solution, and computations.

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## NOMENCLATURE

A	defined in equation (45)
$\bar{A}$	defined in equation (25)
a	thickness of refractory layer
B	defined in equation (49)
$\bar{B}$	defined in equation (26)
b	thickness of structural layer
D	defined in equation (51)
E	defined in equation (52)
$E_n$	defined in equation (14)
$F_o$	constant surface heat flux
$F(\xi)$	defined in equation(37)
$G_n(\xi)$	defined in equation (38)
H	defined in equation (53)
K	thermal conductivity
$Q(\tau)$	defined in equation (50)
$q_c(0)$	aerodynamic heat flux for a rotating blade at $t = 0$
$q_c(t)$	aerodynamic heat flux for a rotating blade at any time $t$ , defined in equation (1)
$q_o(0)$	aerodynamic heat flux for a non-rotating blade at $t = 0$
$q_o(t)$	aerodynamic heat flux for a non-rotating blade at any time $t$
$q_R$	re-radiation heat flux
R	scale factor
T	temperature
$T_e$	earth temperature
t	time

$t_a$	time limit of stage I
$t_b$	" " " " II
$t_c$	" " " " III
$t_d$	" " " " IV
$t_m$	time at which maximum aerodynamic heating takes place
$u$	temperature distribution corresponding to a constant heat input, $F_0$
$x$	distance
$\alpha$	thermal diffusivity
$\beta$	defined in equation (15)
$\Gamma$	defined in equation (24)
$\gamma$	defined in equation (27)
$\delta$	amplitude parameter for the aerodynamic heat flux oscillation
$\epsilon$	emissivity
$\eta$	variable of integration
$\theta$	dimensionless temperature, defined in equation (17)
$\Lambda$	defined in equation (23)
$\lambda_n$	eigen-values, roots of equation (13)

$\mu$	dimensionless parameter, defined in equation (15)
$\xi$	dimensionless distance, defined in equation (15)
$\sigma$	dimensionless parameter, defined in equation (15)
$\sigma$	Stefan - Boltzmann constant
$\tau$	dimensionless time, defined in equation (15)
$\zeta_a$	defined in equation (41)
$\zeta_b$	defined in equation (42)
$\zeta_c$	defined in equation (47)
$\zeta_d$	defined in equation (48)
$\zeta_m$	defined in equation (44)
$\Phi$	defined in equation (39)
$\Psi$	constant obtained from the aerodynamic heating curve
$\Omega$	dimensionless rotor angular velocity, defined in equation (18)
$\omega$	rotor angular velocity

**Subscripts**

i	initial
1	refractory material
2	structural material

**Superscripts**

I	stage I
II	stage II
III	stage III
IV	stage IV

## ABSTRACT

An analysis is made of the temperature response of refractory coated blades of the Rotor Entry Vehicle during atmospheric entry. The mathematical model used in the analysis consists of a composite slab insulated on one side and exposed to a time dependent oscillating heat flux on the other side. An exact analytical solution for the temperature response is obtained for a non re-radiating surface. A numerical solution is also obtained which incorporates the effect of re-radiation on the temperature behavior. The effect of re-radiation on the temperature level during entry is found to be significant and favorable.

Oscillation in the aerodynamic heat flux, which is due to blade rotation, results in temperature oscillation during entry. The amplitude of temperature oscillation is negligible for rotor angular velocities which are of practical interest in the Rotor Entry Vehicle.

## I. INTRODUCTION

Figure 1 is a diagram of a Rotor Entry Vehicle in hypersonic flight. Because of blade rotation, the stagnation point moves over the blade surface, alternating between leading edge, tip and trailing edge. The resulting aerodynamic heating at any given point on the blade surface becomes a steady periodic function of time for the case of constant free stream conditions and a transient periodic function of time for variable free stream conditions. The latter case characterizes the aerodynamic heating during entry of the Rotor Entry Vehicle. The heating pattern is further complicated by shock impingement. Furthermore, the location of boundary-layer shock interaction may traverse the blade surface. Depending on vehicle orientation and flight angle, the blades may be free of shock impingement during a portion of the cycle, as illustrated in Figure 1.

Part of the energy which is convected to the rotor is re-radiated to the surroundings while the rest is conducted through the blades. To provide thermal protection, the blades are coated with a thin layer of refractory material. A typical blade cross-section is shown in Figure 2.

This report deals with the theoretical prediction of the temperature response of the blades' composite structure. Of interest is the identification of the various governing parameters involving thermal properties, rotor angular velocity, and structure geometry, as well as the examination of their effects on the temperature behavior.

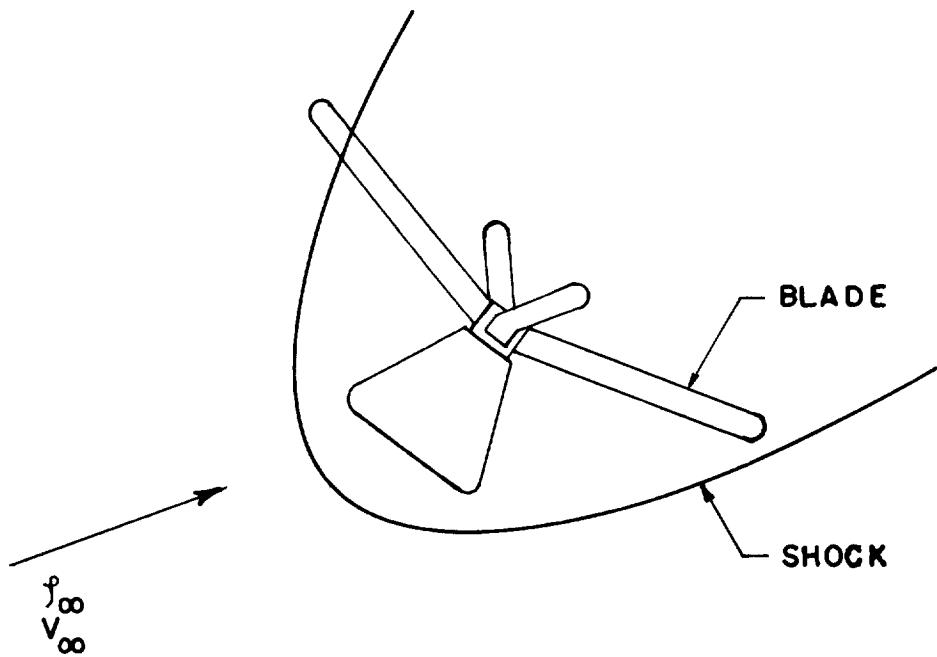


Figure 1.- Rotor Entry Vehicle

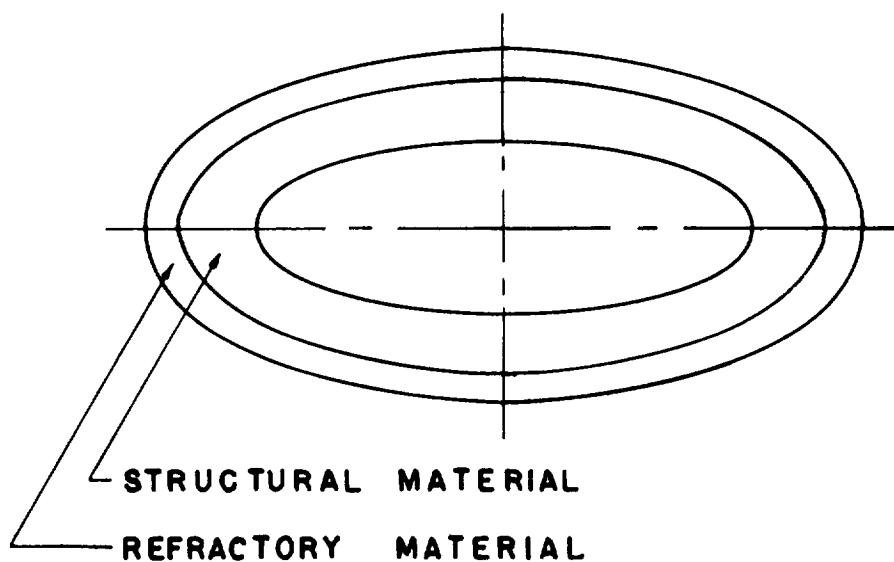


Figure 2.- Cross - sectional area of rotor blade.

The analysis is based on one-dimensional conduction in a composite slab insulated on one side and heated on the other. The convective aerodynamic heat flux,  $q_c(t)$ , is assumed to vary according to

$$q_c(t) = q_o(t) R (1 + \delta \sin \omega t) \quad (1)$$

where  $q_o(t)$  is the heat flux for a non-rotating blade,  $R$  is a scale factor which takes into consideration the change in the mean heat flux as a result of rotation,  $\delta R q_o(t)$  is the amplitude of heat flux oscillation, and  $\omega$  is the rotor angular velocity. Figure 3 is a representation of the model used in the analysis. This simplified model does not take into consideration the effect of shock impingement.

Two cases are of interest:

- (i) Constant free stream conditions (constant vehicle speed and altitude)
- (ii) Variable free stream conditions (entry case)

In case (i) the complications which result from the variations in free stream conditions are eliminated to provide a simplified model which is suitable for a parametric study of the transient response of the blade. Here  $q_o(t)$  in equation (1) is treated as constant.

Of more interest is case (ii) where free stream conditions vary during entry according to vehicle speed and altitude, causing  $q_o(t)$  to be time dependent. Figure 4 shows a typical stagnation point heating curve for a sphere during entry.

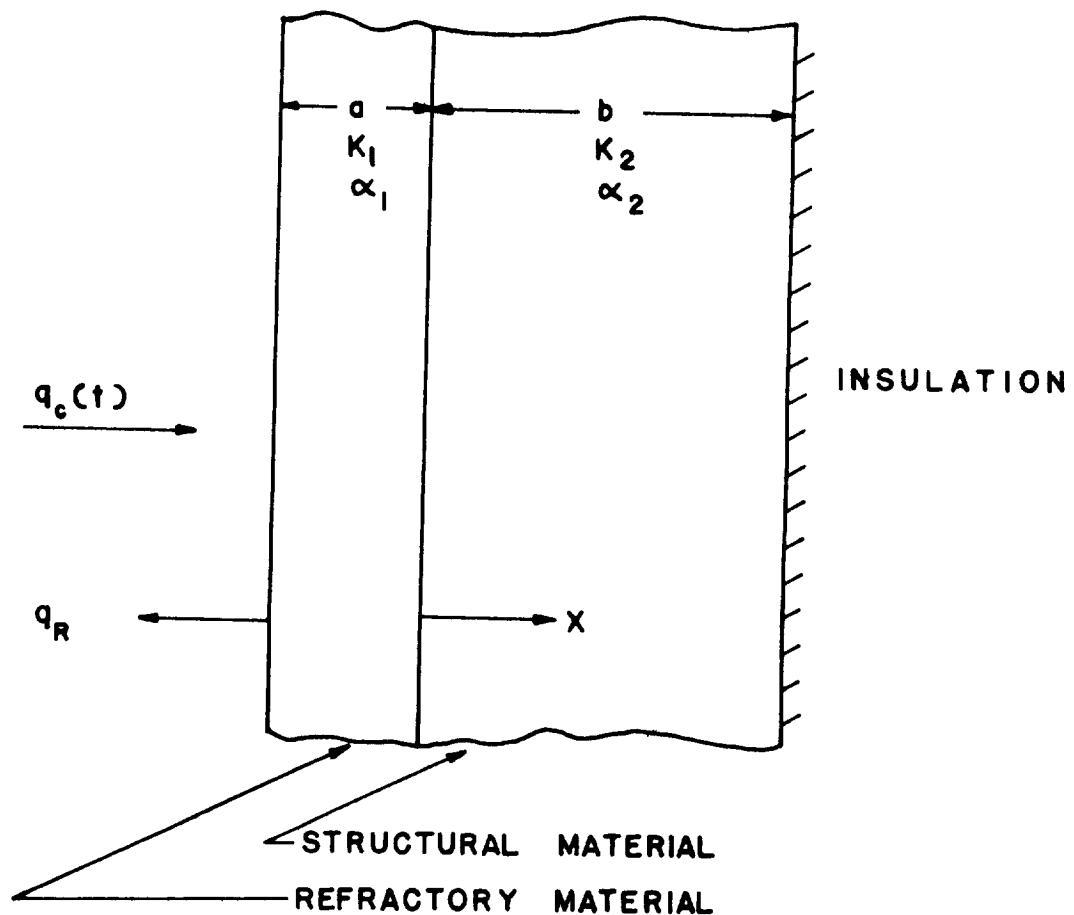


Figure 3.- Analytical model for rotor blade.

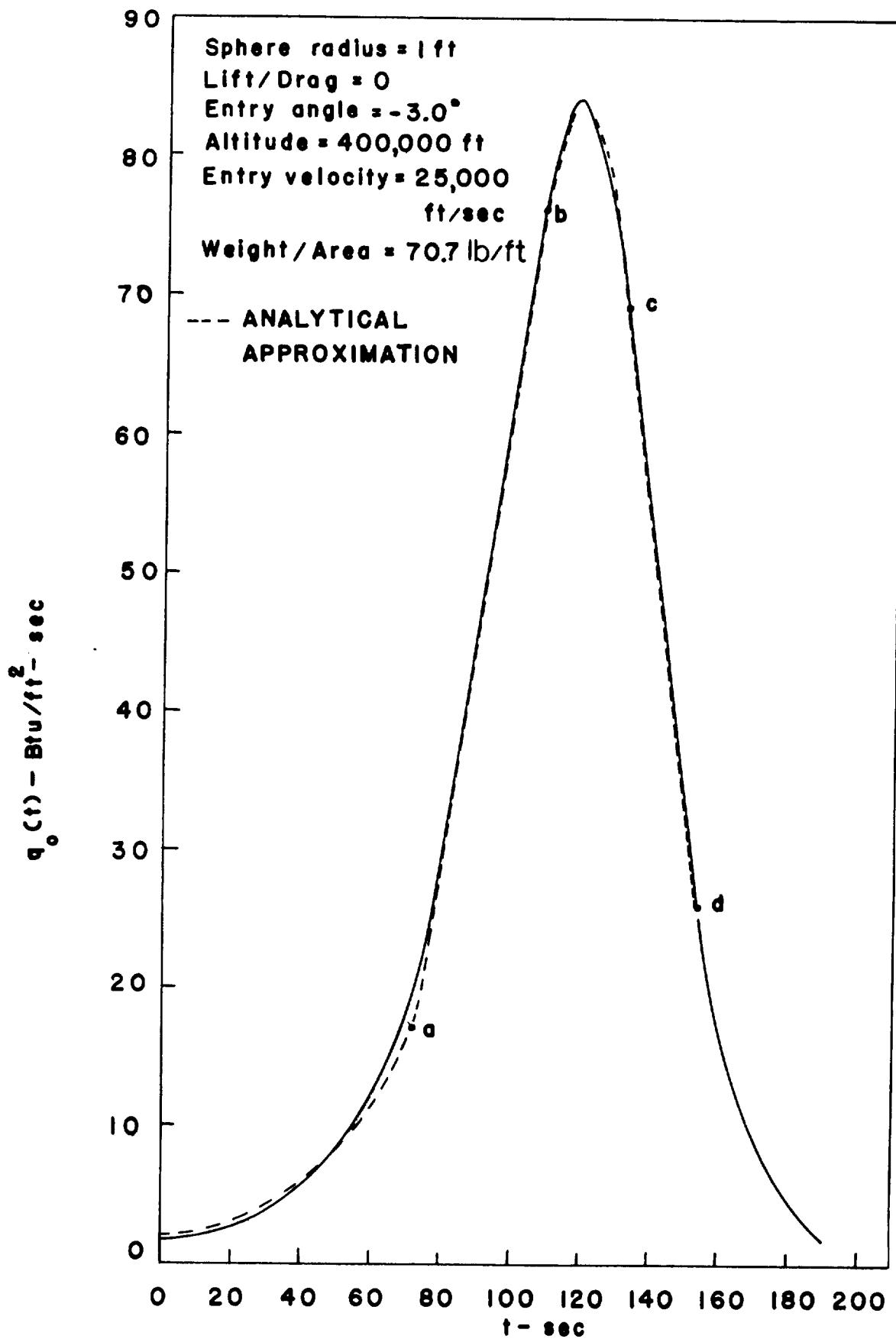


Figure 4.- Typical Stagnation point aerodynamic heating for a sphere during entry.

## II. ANALYSIS

### FORMULATION

The model used in the analysis of the temperature behavior in the composite structure of the blade is shown in figure 3. The governing equations for the temperature distribution, based on constant thermal properties, are

$$\frac{\partial T_1}{\partial t} = \alpha_1 \frac{\partial^2 T_1}{\partial x^2} \quad (2)$$

$$\frac{\partial T_2}{\partial t} = \alpha_2 \frac{\partial^2 T_2}{\partial x^2} \quad (3)$$

where subscripts 1 and 2 refer to the refractory and structural materials respectively.

The initial and boundary conditions are

$$T_1(x,0) = T_2(x,0) = T_i \quad (4)$$

$$T_1(0,t) = T_2(0,t) \quad (5)$$

$$K_1 \frac{\partial T_1(0,t)}{\partial x} = K_2 \frac{\partial T_2(0,t)}{\partial x} \quad (6)$$

$$\frac{\partial T_2(b,t)}{\partial x} = 0 \quad (7)$$

$$-K_1 \frac{\partial T_1(-a,t)}{\partial x} = q_c(t) - q_R \quad (8)$$

In boundary condition (8)  $q_c(t)$  is the aerodynamic heat flux described by equation (1) and  $q_R$  is the re-radiation heat flux given by

$$q_R = \epsilon_1 \bar{\sigma} \left[ T_1^4(-a,t) - T_c^4 \right] \quad (9)$$

## SOLUTION

Because of the non linear nature of boundary condition (8), an analytical solution which takes into consideration the effect of re-radiation is not attempted. However, an analytical solution is presented for cases (i) and (ii) for  $q_R = 0$ . To examine the effect of re-radiation, a numerical solution is obtained.

### Analytical Solution

The solution to equations (2) and (3) for any time dependent heat flux,  $q_c(t)$ , in boundary condition (8) can be obtained from the corresponding solution of constant heat flux by using Duhamel's Integral Equation (Reference 1):

$$T(x,t) - T_i = \frac{q_c(0)}{F_0} \frac{u(x,t) - u_i}{F_0} + \int_0^t \frac{d q_c(\eta)}{d\eta} \frac{u(x, t-\eta) - u_i}{F_0} d\eta \quad , \quad (10)$$

where  $u(x,t)$  is the solution to the corresponding problem with  $q_c(t) = F_0 = \text{constant}$ . Equation (10) is valid for any function  $q_c(t)$  which is piece-wise continuous in the interval  $0 < t < \infty$ . The temperature response of a composite slab under constant surface heat flux,  $F_0$ , is given by (Reference 2)

$$\frac{u_i(x,t) - u_i}{\frac{\alpha F_0}{k_i}} = \frac{1}{6(1+\mu\sigma)} \left[ 6\tau + 3\xi^2 + 2\sigma^2 - 6\mu\sigma\xi - 1 - 2\frac{(\sigma+\mu)}{(1+\mu\sigma)} \right]$$

$$- \sum_{n=1}^{\infty} \left\{ \frac{(1+\mu)\cos[\lambda_n(\sigma-\xi)] + (1-\mu)\cos[\lambda_n(\sigma+\xi)]}{2E_n} \right\} e^{-\lambda_n^2 \tau} \quad (11)$$

and

$$\frac{u_2(x,t) - u_i}{\frac{\alpha F_0}{k_i}} = \frac{1}{6(1+\mu\sigma)} \left[ 6\tau + 3\left(\frac{\sigma}{\beta}\right)^2 \xi^2 + 2\sigma^2 - 6\frac{\sigma^2}{\beta} \xi - 1 - 2\sigma \frac{(\sigma+\mu)}{(1+\mu\sigma)} \right]$$

$$- \sum_{n=1}^{\infty} \frac{\cos[\lambda_n \frac{\sigma}{\beta} (\xi - \beta)]}{E_n} e^{-\lambda_n^2 \tau} \quad (12)$$

where  $\lambda_n$  are the roots of

$$(1+\mu)\sin[\lambda_n(1+\sigma)] + (1-\mu)\sin[\lambda_n(1-\sigma)] = 0 \quad (13)$$

and

$$E_n = \frac{\lambda_n^2}{4} \left\{ (1+\mu)(1+\sigma) \cos[\lambda_n(1+\sigma)] + (1-\mu)(1-\sigma) \cos[\lambda_n(1-\sigma)] \right\} \quad (14)$$

and

$$\left. \begin{aligned} \tau &= \frac{\alpha_1 t}{a^2} \\ \xi &= \frac{x}{a} \\ \mu &= \frac{k_2}{k_1} \sqrt{\frac{\alpha_1}{\alpha_2}} \\ \sigma &= \frac{b}{a} \sqrt{\frac{\alpha_1}{\alpha_2}} \\ \beta &= \frac{b}{a} \end{aligned} \right\} \quad (15)$$

#### Case (i) - Constant Free Stream Conditions:

This case represents a simplified model of a rotating blade under constant free stream flow conditions. The aerodynamic heating,  $q_C(t)$ , in boundary condition (8), is given by equation (1) with  $q_O(t) = q_O(0) = \text{constant}$ . The purpose of examining this model is to obtain a simplified solution which is useful in making a parametric study of the problem.

Substituting equations (1) and (11) into equation (10) and carrying out the integration, the temperature response of the refractory layer for a periodic heat input is obtained.

$$\begin{aligned}
\theta_i(\xi, \tau) = & \frac{1}{1+\mu\tau} \left[ \tau + \frac{\delta}{\Omega} (1 - \cos \Omega \tau) \right] + \frac{1}{6(1+\mu\tau)} \left[ 3\xi^2 \right. \\
& \left. + 2\sigma^2 - 6\mu\sigma\xi - 1 - 2\sigma \frac{\sigma + \mu}{1 + \mu\tau} \right] (1 + \delta \sin \Omega \tau) \\
& - \sum_{n=1}^{\infty} \frac{(1+\mu) \cos[\lambda_n(\sigma-\xi)] + (1-\mu) \cos[\lambda_n(\sigma-\xi)]}{2E_n} \left\{ \right. \\
& \left. 1 + \frac{\delta}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left[ \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau + \sin \Omega \tau \right) e^{\lambda_n^2 \tau} \right. \right. \\
& \left. \left. - \frac{\lambda_n^2}{\Omega} \right] \right\} e^{-\lambda_n^2 \tau} \tag{16}
\end{aligned}$$

where

$$q_i(\xi, \tau) = \frac{T_i(\xi, \tau) - T_i}{\frac{\alpha R q_i(0)}{k_i}} \tag{17}$$

and

$$\Omega = \frac{a^2 \omega}{\alpha_1} \tag{18}$$

Similarly, by substituting equations (1) and (12) into equation (10) the temperature response,  $\theta_i(z,t)$ , of the structural material may be obtained. However, this will not be carried out here since the interface temperature, which is of primary interest, can be obtained from equation (16) by setting  $z = 0$ .

#### Case (ii) - Variable Free Stream Conditions: Entry Case

Because of variations in vehicle speed and altitude, the heat flux,  $q_o(t)$ , in equation (1) is time dependent. A typical plot of  $q_o(t)$  during atmospheric entry is shown in figure 4. To evaluate the integral in equation (10),  $q_c(t)$  must be known. To obtain an analytical solution, the heating curve of figure 4 is divided into four stages in which the heat flux is approximated by exponential, linear, parabolic, and linear functions, respectively, as follows:

$$q_o^I(t) = q_{o(0)} e^{\varphi t} \quad 0 < t < t_a \quad (19)$$

$$q_o^{II}(t) = q_{o(0)} e^{\varphi t_a} \left[ 1 + \frac{t - t_a}{t_b - t_a} (\Lambda - 1) \right] \quad t_a < t < t_b \quad (20)$$

$$q_o^{III}(t) = q_{o(0)} \left[ \Gamma - \bar{A} (t - t_m)^2 \right] \quad t_b < t < t_c \quad (21)$$

$$q_o^{IV}(t) = q_{o(0)} \bar{B} \left[ 1 + \frac{t - t_c}{t_d - t_c} (\gamma - 1) \right] \quad t_c < t < t_d \quad (22)$$

where  $t_a$ ,  $t_b$ ,  $t_c$  and  $t_d$  are the limits of stages I, II, III and IV respectively and

$$\Lambda = \frac{\frac{\pi}{\dot{q}_o(t_b)}}{\frac{\pi}{\dot{q}_o(t_a)}} \quad (23)$$

$$\Gamma = \frac{\dot{q}_o(t_m)}{\dot{q}_o(0)} \quad (24)$$

$$\bar{A} = (\Gamma - \Lambda e^{\varphi t_a}) \frac{1}{(t_b - t_m)^2} \quad (25)$$

$$\bar{B} = T - (\Gamma - \Lambda e^{\varphi t_a}) \frac{(t_c - t_m)^2}{(t_b - t_m)^2} \quad (26)$$

$$\gamma = \frac{\frac{\pi}{\dot{q}_o(t_d)}}{\frac{\pi}{\dot{q}_o(t_c)}} \quad (27)$$

The quantities  $\dot{q}_o(0)$ ,  $t_a$ ,  $t_b$ ,  $t_c$ ,  $t_d$ ,  $t_m$  and  $\varphi$  are known for any given entry heating curve.

Substituting (19), (20), (21) and (22) into equation (1), the aerodynamic heating for a rotating blade during the four stages is obtained.

$$\dot{q}_c^I(t) = \dot{q}_o(0) R (1 + \delta \sin \omega t) e^{\varphi t} \quad 0 < t < t_a \quad (28)$$

$$\dot{q}_c^{II}(t) = \dot{q}_o(0) R (1 + \delta \sin \omega t) e^{\varphi t_a} \left[ 1 + \frac{t - t_a}{t_b - t_a} (\Lambda - 1) \right] \quad t_a < t < t_b \quad (29)$$

$$\dot{q}_c^{III}(t) = \dot{q}_o(0) R (1 + \delta \sin \omega t) \bar{B} \left[ 1 + \frac{t - t_c}{t_d - t_c} (\gamma - 1) \right] \quad t_b < t < t_c \quad (30)$$

$$\dot{q}_c^{IV}(t) = \dot{q}_o(0) R (1 + \delta \sin \omega t) \bar{B} \left[ 1 + \frac{t - t_c}{t_d - t_c} (\gamma - 1) \right] \quad t_c < t < t_d \quad (31)$$

The corresponding solutions  $T^I(x,t)$ ,  $T^{II}(x,t)$ ,  $T^{III}(x,t)$  and  $T^{IV}(x,t)$  are obtained from equation (10) by breaking up the limits of integration into appropriate stages. Thus for the four stages, equation (10) gives:

$$T^I(x,t) - T_i = q_c(0) \frac{u(x,t) - u_i}{F_0} + \int_0^t \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \quad (32)$$

$$\begin{aligned} T^{II}(x,t) - T_i = & q_c(0) \frac{u(x,t) - u_i}{F_0} + \int_0^{t_a} \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \\ & + \int_{t_a}^t \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \end{aligned} \quad (33)$$

$$\begin{aligned} T^{III}(x,t) - T_i = & q_c(0) \frac{u(x,t) - u_i}{F_0} + \int_0^{t_a} \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \\ & + \int_{t_a}^{t_b} \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \\ & + \int_{t_b}^t \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \end{aligned} \quad (34)$$

$$\begin{aligned} T^{IV}(x,t) - T_i = & q_c(0) \frac{u(x,t) - u_i}{F_0} + \int_0^{t_a} \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \\ & + \int_{t_a}^{t_b} \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \\ & + \int_{t_b}^{t_c} \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \\ & + \int_{t_c}^t \frac{dq_c^I(\eta)}{d\eta} \left[ \frac{u(x,t-\eta) - u_i}{F_0} \right] d\eta \end{aligned} \quad (35)$$

Solution for Stage I:  $0 < \tau < \zeta_a$

Substituting equations (11) and (28) into (32), the temperature response  $\theta_i^I(\xi, \tau)$  in the refractory layer is obtained. The result, expressed in dimensionless form, is given by:

$$\theta_i^I(\xi, \tau) = \frac{1}{1+\mu\tau} - \frac{1}{\Phi} [e^{\Phi\tau} - 1] + F(\xi) e^{\Phi\tau} [1 + \delta \sin \Omega\tau]$$

$$- \sum_{n=1}^{\infty} G_n(\xi) \left\{ e^{-\lambda_n^2 \tau} + \frac{\Phi}{(\lambda_n^2 + \Phi)} [e^{\Phi\tau} - e^{-\lambda_n^2 \tau}] \right\}$$

$$+ \frac{1}{1+\mu\tau} \frac{e^{\Phi\tau}}{\left[\left(\frac{\Phi}{\Omega}\right)^2 + 1\right]} \frac{\delta}{\Omega} \left[ \frac{\Phi}{\Omega} \sin \Omega\tau - \cos \Omega\tau \right]$$

$$+ e^{-\Phi\tau}] - \sum_{n=1}^{\infty} G_n(\xi) \frac{\delta e^{\Phi\tau}}{\left[\frac{\lambda_n^2}{\Omega} + \frac{\Phi}{\Omega}\right]^2 + 1} \left\{ \left[ \frac{\Phi}{\Omega} \left( \frac{\lambda_n^2}{\Omega} + \frac{\Phi}{\Omega} \right) + 1 \right] \sin \Omega\tau + \frac{\lambda_n^2}{\Omega} \cos \Omega\tau \right.$$

$$\left. - \frac{\lambda_n^2}{\Omega} e^{-(\lambda_n^2 + \Phi)\tau} \right\} \quad (36)$$

where

$$F(\xi) = \frac{1}{6(1+\mu\sigma)} \left[ 3\xi^2 + 2\sigma^2 - 6\mu\sigma\xi - 1 - 2\sigma \frac{\sigma + \mu}{1 + \mu\sigma} \right] \quad (37)$$

$$G_n(\xi) = \frac{(1+\mu)\cos[\lambda_n(\sigma-\xi)] + (1-\mu)\cos[\lambda_n(\sigma+\xi)]}{2E_n} \quad (38)$$

$$\Phi = \frac{\alpha^2 \psi}{\alpha_1} \quad (39)$$

Solution for Stage II:  $\tau_a < \tau < \tau_b$

Using (11), (29) and (33), the solution for stage II is obtained.

$$\begin{aligned} \Theta_I^{\text{II}}(\xi, \tau) = & \frac{1}{1+\mu\sigma} \left\{ (\tau - \tau_a) e^{\Phi \tau_a} + \frac{1}{\Phi} (e^{\Phi \tau_a} - 1) \right\} \\ & + \frac{1}{1+\mu\sigma} \frac{\delta}{\Omega} \frac{e^{\Phi \tau_a}}{\left(\frac{\Phi}{\Omega}\right)^2 + 1} \left[ \frac{\Phi}{\Omega} \sin \Omega \tau_a - \cos \Omega \tau_a + e^{-\Phi \tau_a} \right] \\ & - \sum_{n=1}^{\infty} \frac{G_n(\xi)}{\left(\frac{\lambda_n^2}{\Phi} + 1\right)} e^{-\lambda_n^2(\tau - \tau_a)} \left[ e^{\Phi \tau_a} + \frac{\lambda_n^2}{\Phi} e^{-\lambda_n^2 \tau_a} \right] \\ & - \delta \sum_{n=1}^{\infty} G_n(\xi) \frac{e^{-\lambda_n^2(\tau - \tau_a)}}{\left(\frac{\Phi}{\Omega} + \frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \left[ \frac{\Phi}{\Omega} \left( \frac{\Phi}{\Omega} + \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau_a \right. \right. \\ & \left. \left. + \sin \Omega \tau_a + \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_a \right] e^{\Phi \tau_a} - \frac{\lambda_n^2}{\Omega} e^{-\lambda_n^2 \tau_a} \right\} \end{aligned}$$

$$\frac{1}{1+\mu\tau} e^{\Phi\tau_a} \left\{ \frac{\delta}{\Omega} (\cos \Omega \tau_a - \cos \Omega \tau) + \frac{\delta (\Lambda-1)}{\Omega^2 (\tau_b - \tau_a)} [ -\Omega (\tau - \tau_a) \cos \Omega \tau \right.$$

$$+ \sin \Omega \tau - \sin \Omega \tau_a ] + \frac{(\Lambda-1)}{(\tau_b - \tau_a)} \frac{(\tau - \tau_a)^2}{2} \right\} + e^{\Phi\tau_a} F(z) (1$$

$$+ \delta \sin \Omega \tau) \left[ 1 + \frac{(\Lambda-1)}{(\tau_b - \tau_a)} (\tau - \tau_a) \right] - e^{\Phi\tau_a} \sum_{n=1}^{\infty} G_n(z) \Bigg]$$

$$\frac{\delta}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \cos \Omega \tau + \sin \Omega \tau - \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_a \right. \right.$$

$$+ \sin \Omega \tau_a) e^{-\lambda_n^2 (\tau - \tau_a)} \Big\} + \frac{(\Lambda-1)}{(\tau_b - \tau_a)} \delta \left\{ \frac{(\tau - \tau_a)}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau \right. \right.$$

$$+ \sin \Omega \tau) - \frac{1}{\Omega} \frac{1}{\left[\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1\right]^2} \left[ \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau + 2 \frac{\lambda_n^2}{\Omega} \sin \Omega \tau \right]$$

$$- \cos \Omega \tau - \left\langle \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau_a + 2 \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_a \right\rangle$$

$$- \cos \Omega \tau_a \Big] \Big\} + \frac{(\Lambda-1)}{(\tau_b - \tau_a)} \frac{1}{\lambda_n^2} \left\{ 1 \right.$$

$$- e^{-\lambda_n^2 (\tau - \tau_a)} \Big\} + \frac{(\Lambda-1)}{(\tau_b - \tau_a)} \frac{\delta}{\Omega} \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left[ \frac{\lambda_n^2}{\Omega} \sin \Omega \tau \right.$$

$$- \cos \Omega \tau - \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_a - \cos \Omega \tau_a \right) e^{-\lambda_n^2 (\tau - \tau_a)} \Big] \Big]$$

(40)

where

$$\zeta_a = \frac{\alpha_1 t_a}{\alpha^2} \quad (41)$$

$$\zeta_b = \frac{\alpha_1 t_b}{\alpha^2} \quad (42)$$

Solution for Stage III:  $\zeta_b < \zeta < \zeta_c$

Substituting equations (11) and (30) into (34), the solution for stage III is obtained

$$\begin{aligned} \theta_1^{III}(\xi, \tau) = & \frac{1}{1+\mu\sigma} \left\{ (\tau - \zeta_a)(1 + \delta \sin \Omega \zeta_a) e^{\Phi \zeta_a} + \frac{1}{\Phi} (e^{\Phi \zeta_a} - 1) \right\} \\ & + \frac{1}{1+\mu\sigma} \frac{\delta}{\Omega} \frac{e^{\Phi \zeta_a}}{\left(\frac{\Phi}{\Omega}\right)^2 + 1} \left[ \frac{\Phi}{\Omega} \sin \Omega \zeta_a - \cos \Omega \zeta_a + e^{-\Phi \zeta_a} \right] \\ & + F(\xi)(1 + \delta \sin \Omega \zeta_a) e^{\Phi \zeta_a} - \sum_{n=1}^{\infty} \frac{G_n(\xi)}{\left(\frac{\lambda_n^2}{\Phi} + 1\right)} e^{-\lambda_n^2(\tau - \zeta_a)} \left[ \right. \\ & \left. e^{\Phi \zeta_a} + \frac{\lambda_n^2}{\Phi} e^{-\lambda_n^2 \zeta_a} \right] - \delta \sum_{n=1}^{\infty} \frac{G_n(\xi)}{\left(\frac{\Phi}{\Omega} + \frac{\lambda_n^2}{\Omega}\right)^2 + 1} e^{-\lambda_n^2(\tau - \zeta_a)} \left\{ \right[ \\ & \left. \frac{\Phi}{\Omega} \left( \frac{\Phi}{\Omega} + \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \zeta_a + \sin \Omega \zeta_a + \frac{\lambda_n^2}{\Omega} \cos \Omega \zeta_a \right] e^{\Phi \zeta_a} \right. \\ & \left. - \frac{\lambda_n^2}{\Omega} e^{-\lambda_n^2 \zeta_a} \right\} + \frac{e^{\Phi \zeta_a}}{1+\mu\sigma} \left[ \frac{\delta}{\Omega} (\Omega \zeta_b \sin \Omega \zeta_b - \cos \Omega \zeta_b \right. \\ & \left. - \Omega \zeta_a \sin \Omega \zeta_a - \Omega \zeta_a \sin \Omega \zeta_a + \cos \Omega \zeta_a + \Omega \zeta_a \sin \Omega \zeta_a) \right] \end{aligned}$$

$$+ \frac{(\lambda-1)}{(\tau_b - \tau_a)} \frac{\delta}{\Omega} (\sin \Omega \tau_b - \sin \Omega \tau_a) - (\lambda-1) \frac{\delta}{\Omega} (\cos \Omega \tau_b$$

$$+ \Omega \tau_b \sin \Omega \tau_b - \Omega \tau \sin \Omega \tau_b) + (\lambda-1) \left[ \tau - \frac{1}{2} (\tau_b + \tau_a) \right] \Big]$$

$$+ e^{\Phi \tau_a} F(\zeta) \left[ \delta (\sin \Omega \tau_b - \sin \Omega \tau_a) + (\lambda-1)(1 + \delta \sin \Omega \tau_b) \right]$$

$$- e^{\Phi \tau_a} \sum_{n=1}^{\infty} G_n(\zeta) e^{-\lambda_n^2(\tau - \tau_b)} \left[ \frac{\delta}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b \right. \right.$$

$$\left. \left. + \sin \Omega \tau_b - \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_a + \sin \Omega \tau_a \right) e^{-\lambda_n^2(\tau_b - \tau_a)} \right\} \right]$$

$$+ \frac{(\lambda-1)}{(\tau_b - \tau_a)} \delta \left\{ \frac{\tau_b - \tau_a}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b + \sin \Omega \tau_b \right) \right.$$

$$- \frac{1}{\pi} \frac{1}{\left[\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1\right]^2} \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau_b + 2 \left(\frac{\lambda_n^2}{\Omega}\right) \sin \Omega \tau_b - \cos \Omega \tau_b \right.$$

$$\left. \left. - \left[ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau_a + 2 \left(\frac{\lambda_n^2}{\Omega}\right) \sin \Omega \tau_a - \cos \Omega \tau_a \right] e^{-\lambda_n^2(\tau_b - \tau_a)} \right\} \right]$$

$$+ \frac{(\lambda-1)}{\tau_b - \tau_a} \frac{1}{\lambda_n^2} \left( 1 - e^{-\lambda_n^2(\tau_b - \tau_a)} \right) + \frac{(\lambda-1)}{\tau_b - \tau_a} \frac{\delta}{\Omega} \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_b \right.$$

$$\left. - \cos \Omega \tau_b - \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_a - \cos \Omega \tau_a \right) e^{-\lambda_n^2(\tau_b - \tau_a)} \right\} \Big]$$

$$+ \frac{1}{1+\mu\sigma} \left[ -\Delta \left\{ \frac{1}{3} \tau^3 - \tau \tau_b^2 + \frac{2}{3} \tau_b^3 - \tau_m (\tau - \tau_b)^2 \right\} \right]$$

$$\begin{aligned}
& + \frac{\delta}{\Omega} (\tau - A \tau_m^2) \left[ -\cos \Omega \tau - \Omega \tau \sin \Omega \tau_b + \cos \Omega \tau_b + \Omega \tau_b \sin \Omega \tau_b \right] \\
& - 2A \frac{\delta}{\Omega^3} \left[ -\Omega \tau \sin \Omega \tau - 2 \cos \Omega \tau - \Omega \tau \sin \Omega \tau_b + \Omega^2 \tau \tau_b \cos \Omega \tau_b \right. \\
& \left. + 2 \Omega \tau_b \sin \Omega \tau_b - (\Omega^2 \tau_b^2 - 2) \cos \Omega \tau_b \right] + 2A \tau_m \frac{\delta}{\Omega^2} \left[ -\sin \Omega \tau \right. \\
& \left. + \sin \Omega \tau_b + \Omega (\tau - \tau_b) \cos \Omega \tau_b \right] + 2A \tau_m \frac{\delta}{\Omega^2} \left[ -\Omega \tau \cos \Omega \tau \right. \\
& \left. + 2 \sin \Omega \tau - \Omega \tau \cos \Omega \tau_b - \Omega^2 \tau \tau_b \sin \Omega \tau_b + 2 \Omega \tau_b \cos \Omega \tau_b \right. \\
& \left. + \Omega^2 \tau_b^2 \sin \Omega \tau_b - 2 \sin \Omega \tau_b \right] - A \frac{\delta}{\Omega^3} \left\{ -\Omega^2 \tau^2 \cos \Omega \tau \right. \\
& \left. - 2 \Omega \tau \sin \Omega \tau + 6 \cos \Omega \tau + 6 \Omega \tau \sin \Omega \tau - 2 \Omega^2 \tau \tau_b \cos \Omega \tau_b \right. \\
& \left. - \Omega \tau (\Omega^2 \tau_b^2 - 2) \sin \Omega \tau_b + (3 \Omega^2 \tau_b^2 - 6) \cos \Omega \tau_b + \Omega^3 \tau_b^3 \sin \Omega \tau_b \right. \\
& \left. - 6 \Omega \tau_b \sin \Omega \tau_b \right\} \Big] + F(\$) \left\{ -A (\tau^2 - \tau_b^2) + 2A \tau_m (\tau - \tau_b) \right. \\
& \left. + \delta (\tau - A \tau_m^2) (\sin \Omega \tau - \sin \Omega \tau_b) - 2A \frac{\delta}{\Omega^2} (\sin \Omega \tau - \Omega \tau \cos \Omega \tau \right. \\
& \left. - \sin \Omega \tau_b + \Omega \tau_b \cos \Omega \tau_b) + 2A \frac{\delta}{\Omega} \tau_m (\cos \Omega \tau_b + \Omega \tau \sin \Omega \tau \right. \\
& \left. - \cos \Omega \tau_b - \Omega \tau_b \sin \Omega \tau_b) - A \frac{\delta}{\Omega^2} (2 \Omega \tau \cos \Omega \tau + \Omega^2 \tau^2 \sin \Omega \tau
\right\}
\end{aligned}$$

$$- 2 \sin \Omega \tau - 2 \Omega \tau_b \cos \Omega \tau_b - \Omega^2 \tau_b^2 \sin \Omega \tau_b + 2 \sin \Omega \tau_b \} \}$$

$$+ \sum_{n=1}^{\infty} G_n(\xi) \left[ 2 \Delta \left( \frac{1}{\lambda_n^2} \right)^2 \left\{ (\lambda_n^2 \tau - 1) - (\lambda_n^2 \tau_b - 1) e^{-\lambda_n^2 (\tau - \tau_b)} \right\} \right]$$

$$- 2 \Delta \frac{\tau_m}{\lambda_n^2} \left( 1 - e^{-\lambda_n^2 (\tau - \tau_b)} \right) - S(\tau - A \tau_m^2) \frac{1}{\left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \cos \Omega \tau \right.$$

$$\left. + \sin \Omega \tau - \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b + \sin \Omega \tau_b \right) e^{-\lambda_n^2 (\tau - \tau_b)} \right\}$$

$$+ 2 \Delta \delta \left[ \frac{1}{\Omega} \frac{1}{\left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1} \left\{ \tau \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau - \cos \Omega \tau \right) - \tau_b \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_b \right. \right. \right.$$

$$\left. \left. \left. - \cos \Omega \tau_b \right) e^{-\lambda_n^2 (\tau - \tau_b)} \right\} - \frac{1}{\Omega^2} \frac{1}{\left[ \left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1 \right]^2} \left\{ \left( \frac{\lambda_n^2}{\Omega} \right)^2 \sin \Omega \tau \right.$$

$$\left. \left. - 2 \left( \frac{\lambda_n^2}{\Omega} \right) \cos \Omega \tau - \sin \Omega \tau - \left\{ \left( \frac{\lambda_n^2}{\Omega} \right)^2 \sin \Omega \tau_b - 2 \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b \right. \right. \right.$$

$$\left. \left. \left. - \sin \Omega \tau_b \right\} e^{-\lambda_n^2 (\tau - \tau_b)} \right\} \right] - 2 \Delta \delta \tau_m \left[ \frac{1}{\Omega} \frac{1}{\left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \sin \Omega \tau \right. \right.$$

$$\left. \left. \left. - \cos \Omega \tau - \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_b - \cos \Omega \tau_b \right) e^{-\lambda_n^2 (\tau - \tau_b)} \right\} \right]$$

$$- 2 \Delta \tau_m \delta \left[ \frac{1}{\left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1} \left\{ \tau \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau + \sin \Omega \tau \right) - \tau_b \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b \right. \right. \right.$$

$$\left. \left. \left. + \sin \Omega \tau_b \right) e^{-\lambda_n^2 (\tau - \tau_b)} \right\} - \frac{1}{\Omega} \frac{1}{\left[ \left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1 \right]^2} \left\{ \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau \right. \right. \right.$$

$$\left. \left. \left. + 2 \left( \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau - \cos \Omega \tau - \left\{ \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau_b + 2 \left( \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau_b \right. \right. \right\}$$

$$\begin{aligned}
& - \cos \Omega \tau_0 \} e^{-\lambda_n^2(\tau-\tau_0)} \} \Big] + 8 \delta \left[ \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \tau^2 \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau \right. \right. \right. \\
& \left. \left. \left. + \sin \Omega \tau \right) - \tau_0^2 \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_0 + \sin \Omega \tau_0 \right) e^{-\lambda_n^2(\tau-\tau_0)} \right\} \right. \\
& \left. - \frac{1}{\Omega} \frac{1}{\left[\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1\right]^2} \left\{ \tau \left\{ 2 \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau + 4 \left(\frac{\lambda_n^2}{\Omega}\right) \sin \Omega \tau \right. \right. \right. \\
& \left. \left. \left. - 2 \cos \Omega \tau \right\} - \tau_0 \left\{ 2 \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau_0 + 4 \left(\frac{\lambda_n^2}{\Omega}\right) \sin \Omega \tau_0 \right. \right. \right. \\
& \left. \left. \left. - 2 \cos \Omega \tau_0 \right\} e^{-\lambda_n^2(\tau-\tau_0)} \right\} + \frac{1}{\Omega^2} \frac{2}{\left[\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1\right]^3} \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^3 \cos \Omega \tau \right. \\
& \left. + 3 \left(\frac{\lambda_n^2}{\Omega}\right)^2 \sin \Omega \tau - 3 \left(\frac{\lambda_n^2}{\Omega}\right) \cos \Omega \tau - \sin \Omega \tau - \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^3 \cos \Omega \tau_0 \right. \right. \\
& \left. \left. + 3 \left(\frac{\lambda_n^2}{\Omega}\right)^2 \sin \Omega \tau_0 - 3 \left(\frac{\lambda_n^2}{\Omega}\right) \cos \Omega \tau_0 \right\} \right. \\
& \left. - \sin \Omega \tau_0 \} e^{-\lambda_n^2(\tau-\tau_0)} \} \Big] \Big] \quad (43)
\end{aligned}$$

where

$$\tau_m = \frac{\alpha_i t_m}{\alpha^2} \quad (44)$$

$$A = \tilde{\lambda} \left( \frac{\alpha^2}{\alpha_i} \right)^2 = (\Gamma - \lambda e^{\Phi \tau_a}) \frac{1}{(\tau_b - \tau_m)^2} \quad (45)$$

Solution for Stage IV:  $\tau_c < \tau < \tau_d$

Using (11), (31) and (35), the solution for stage IV is obtained

$$\begin{aligned} \theta_i^{IV}(\xi, \tau) = & \frac{1}{1 + \mu \sigma} \left\{ (\tau - \tau_a) (1 + \delta \sin \Omega \tau_a) e^{\Phi \tau_a} + \frac{1}{\Phi} (e^{\Phi \tau_a} - 1) \right\} \\ & + \frac{1}{1 + \mu \sigma} \frac{\delta}{\pi} e^{\Phi \tau_a} \frac{1}{\left(\frac{\Phi}{\pi}\right)^2 + 1} \left[ \frac{\Phi}{\pi} \sin \Omega \tau_a - \cos \Omega \tau_a + e^{-\Phi \tau_a} \right] + F(\xi) (1 \\ & + \delta \sin \Omega \tau_a) e^{\Phi \tau_a} - \sum_{n=1}^{\infty} \frac{G_n(\xi)}{\left(\frac{\lambda_n^2}{\Phi} + 1\right)} e^{-\lambda_n^2(\tau - \tau_a)} \left[ e^{\Phi \tau_a} + \frac{\lambda_n^2}{\Phi} e^{\lambda_n^2 \tau_a} \right] \\ & - \delta \sum_{n=1}^{\infty} \frac{G_n(\xi)}{\left(\frac{\Phi}{\pi} + \frac{\lambda_n^2}{\Omega}\right)^2 + 1} e^{-\lambda_n^2(\tau - \tau_a)} \left[ \left\{ \frac{\Phi}{\pi} \left( \frac{\Phi}{\pi} + \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau_a \right. \right. \\ & \left. \left. + \sin \Omega \tau_a + \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_a \right\} e^{\Phi \tau_a} - \frac{\lambda_n^2}{\Omega} e^{-\lambda_n^2 \tau_a} \right] \\ & + e^{\Phi \tau_a} \frac{1}{1 + \mu \sigma} \left\{ \frac{\delta}{\pi} (\Omega \tau \sin \Omega \tau_b - \cos \Omega \tau_b - \Omega \tau_b \sin \Omega \tau_b \right. \\ & \left. - \Omega \tau \sin \Omega \tau_a + \cos \Omega \tau_a + \Omega \tau_a \sin \Omega \tau_a) + \frac{(1-1)}{\tau_b - \tau_a} \frac{\delta}{\pi^2} (\sin \Omega \tau_b \right. \end{aligned}$$

$$-\sin \Omega \tau_a) - (\Lambda - 1) \frac{\delta}{\Omega} (\cos \Omega \tau_b + \Omega \tau_b \sin \Omega \tau_b - \Omega \tau \sin \Omega \tau_b)$$

$$+ (\Lambda - 1) \left[ \tau_b + \tau_a \right] \} + e^{\Phi \tau_a} F(\xi) \left\{ \delta (\sin \Omega \tau_b - \sin \Omega \tau_a) \right.$$

$$\left. + (\Lambda - 1) (1 + \delta \sin \Omega \tau_a) \right\} - e^{\Phi \tau_a} \sum_{n=1}^{\infty} G_n(\xi) e^{-\lambda_n^2 (\tau - \tau_b)} \left[ \right.$$

$$\frac{\delta}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b + \sin \Omega \tau_b - \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_a + \sin \Omega \tau_a \right) e^{-\lambda_n^2 (\tau_b - \tau_a)} \right\}$$

$$+ \frac{(\Lambda - 1)}{\tau_b - \tau_a} \delta \left\{ \frac{\tau_b - \tau_a}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b + \sin \Omega \tau_b \right) \right.$$

$$- \frac{1}{\Omega} \frac{1}{\left[\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1\right]^2} \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau_b + 2 \left(\frac{\lambda_n^2}{\Omega}\right) \sin \Omega \tau_b - \cos \Omega \tau_b \right.$$

$$\left. - \left[ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau_a + 2 \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_a - \cos \Omega \tau_a \right] e^{-\lambda_n^2 (\tau_b - \tau_a)} \right\} \}$$

$$+ \frac{(\Lambda - 1)}{(\tau_b - \tau_a)} \frac{1}{\lambda_n^2} (1 - e^{-\lambda_n^2 (\tau_b - \tau_a)}) + \frac{(\Lambda - 1)}{(\tau_b - \tau_a)} \frac{\delta}{\Omega} \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_b \right.$$

$$\left. - \cos \Omega \tau_b - \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_a - \cos \Omega \tau_a \right) e^{-\lambda_n^2 (\tau_b - \tau_a)} \right\} \]$$

$$+ \frac{1}{1 + \mu \Gamma} \left[ -A \tau \bar{\tau}_c^2 + \frac{2}{3} A \bar{\tau}_c^3 + A \tau \bar{\tau}_b^2 - \frac{2}{3} A \bar{\tau}_b^3 + 2 A \bar{\tau}_m (\bar{\tau} \bar{\tau}_c \right.$$

$$\left. - \frac{1}{2} \bar{\tau}_c^2 - \bar{\tau} \bar{\tau}_b + \frac{1}{2} \bar{\tau}_b^2) + \frac{\delta}{\Omega} (\Gamma - A \bar{\tau}_m^2) (\bar{\tau} \sin \Omega \tau_c - \cos \Omega \tau_c \right.$$

$$\begin{aligned}
& -\Omega \tau_c \sin \Omega \tau_c - \Omega \tau \sin \Omega \tau_b + \cos \Omega \tau_b + \Omega \tau_b \sin \Omega \tau_b) - 2A \frac{\delta}{\Omega^2} \left\{ \Omega \tau \sin \Omega \tau_c \right. \\
& - \Omega^2 \tau \tau_c \cos \Omega \tau_c - 2\Omega \tau_c \sin \Omega \tau_c + (\Omega^2 \tau_c^2 - 2) \cos \Omega \tau_c - \Omega \tau \sin \Omega \tau_b \\
& \left. + \Omega^2 \tau \tau_b \cos \Omega \tau_b + 2\Omega \tau_b \sin \Omega \tau_b - (\Omega^2 \tau_b^2 - 2) \cos \Omega \tau_b \right\} \\
& + 2A \delta \tau_m \frac{1}{\Omega^2} (-\Omega \tau \cos \Omega \tau_c - \sin \Omega \tau_c + \Omega \tau_c \cos \Omega \tau_c + \Omega \tau \cos \Omega \tau_b \\
& + \sin \Omega \tau_b - \Omega \tau_b \cos \Omega \tau_b) + 2A \tau_m \delta \frac{1}{\Omega^2} \left\{ \Omega \tau \cos \Omega \tau_c \right. \\
& + \Omega^2 \tau \tau_c \sin \Omega \tau_c - 2\Omega \tau_c \cos \Omega \tau_c - (\Omega^2 \tau_c^2 - 2) \sin \Omega \tau_c \\
& - \Omega \tau \cos \Omega \tau_b - \Omega^2 \tau \tau_b \sin \Omega \tau_b + 2\Omega \tau_b \cos \Omega \tau_b + (\Omega^2 \tau_b^2 - 2) \sin \Omega \tau_b \left. \right\} \\
& - A \delta \frac{1}{\Omega^2} \left\{ 2\Omega^2 \tau \tau_c \cos \Omega \tau_c + \Omega \tau (\Omega^2 \tau_c^2 - 2) \sin \Omega \tau_c \right. \\
& - (3\Omega^2 \tau_c^2 - 6) \cos \Omega \tau_c - (\Omega^3 \tau_c^3 - 6\Omega \tau_c) \sin \Omega \tau_c - 2\Omega^2 \tau \tau_b \cos \Omega \tau_b \\
& \left. - \Omega \tau (\Omega^2 \tau_b^2 - 2) \sin \Omega \tau_b + (3\Omega^2 \tau_b^2 - 6) \cos \Omega \tau_b + (\Omega^3 \tau_b^3 - 6\Omega \tau_b) \sin \Omega \tau_b \right\} \\
& + F(\delta) \left[ -A(\tau_c^2 - \tau_b^2) + 2A \tau_m (\tau_c - \tau_b) + \delta(\Gamma - A \tau_m^2)(\sin \Omega \tau_c - \sin \Omega \tau_b) \right] \\
& - 2A \frac{\delta}{\Omega^2} \left\{ \sin \Omega \tau_c - \Omega \tau_c \cos \Omega \tau_c - \sin \Omega \tau_b + \Omega \tau_b \cos \Omega \tau_b \right\} \\
& + 2A \tau_m \frac{\delta}{\Omega} (\cos \Omega \tau_b - \cos \Omega \tau_c) + 2A \tau_m \frac{\delta}{\Omega} (\cos \Omega \tau_c + \Omega \tau_c \sin \Omega \tau_c \\
& - \cos \Omega \tau_b - \Omega \tau_b \sin \Omega \tau_b) - A \frac{\delta}{\Omega^2} (2\Omega \tau_c \cos \Omega \tau_c + \Omega^2 \tau_c^2 \sin \Omega \tau_c \\
& - 2 \sin \Omega \tau_c - 2\Omega \tau_b \cos \Omega \tau_b - \Omega^2 \tau_b^2 \sin \Omega \tau_b + 2 \sin \Omega \tau_b) \]
\end{aligned}$$

$$\begin{aligned}
& + \sum_{n=1}^{\infty} C_n(\zeta) e^{-\lambda_n^2(\tau_c - \tau_b)} \left[ 2A \frac{1}{(\lambda_n^2)^2} \left\{ (\lambda_n^2 \tau_c - 1) - (\lambda_n^2 \tau_b - 1) e^{-\lambda_n^2(\tau_c - \tau_b)} \right\} \right. \\
& - 2A \tau_m \frac{1}{\lambda_n^2} (1 - e^{-\lambda_n^2(\tau_c - \tau_b)}) - \delta(\Gamma - A \tau_m) \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left[ \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_c \right. \\
& \left. + \sin \Omega \tau_c - \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b + \sin \Omega \tau_b \right) e^{-\lambda_n^2(\tau_c - \tau_b)} \right] \\
& + 2A \delta \left[ \frac{1}{\Omega} \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \tau_c \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_c - \cos \Omega \tau_c \right) - \tau_b \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_b \right. \right. \right. \\
& \left. \left. \left. - \cos \Omega \tau_b \right) e^{-\lambda_n^2(\tau_c - \tau_b)} \right\} \right] - \frac{1}{\Omega^2} \frac{1}{\left[\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1\right]^2} \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \sin \Omega \tau_c \right. \\
& - 2\left(\frac{\lambda_n^2}{\Omega}\right) \cos \Omega \tau_c - \sin \Omega \tau_c - \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \sin \Omega \tau_b - 2\left(\frac{\lambda_n^2}{\Omega}\right) \cos \Omega \tau_b \right. \\
& \left. - \sin \Omega \tau_b \right\} e^{-\lambda_n^2(\tau_c - \tau_b)} \Big] \Big] - 2A \delta \tau_m \left[ \frac{1}{\Omega} \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_c \right. \right. \\
& \left. \left. - \cos \Omega \tau_c - \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_b - \cos \Omega \tau_b \right) e^{-\lambda_n^2(\tau_c - \tau_b)} \right\} \right] \\
& - 2A \tau_m \delta \left[ \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \tau_c \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_c + \sin \Omega \tau_c \right) - \tau_b \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b \right. \right. \right. \\
& \left. \left. \left. + \sin \Omega \tau_b \right) e^{-\lambda_n^2(\tau_c - \tau_b)} \right\} \right] - \frac{1}{\Omega^2} \frac{1}{\left[\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1\right]^2} \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau_c \right. \\
& + 2\left(\frac{\lambda_n^2}{\Omega}\right) \sin \Omega \tau_c - \cos \Omega \tau_c - \left\{ \left(\frac{\lambda_n^2}{\Omega}\right)^2 \cos \Omega \tau_b + 2\left(\frac{\lambda_n^2}{\Omega}\right) \sin \Omega \tau_b \right. \\
& \left. - \cos \Omega \tau_b \right\} e^{-\lambda_n^2(\tau_c - \tau_b)} \Big] \Big] + A \delta \left[ \frac{1}{\left(\frac{\lambda_n^2}{\Omega}\right)^2 + 1} \left\{ \tau_c \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_c \right. \right. \right. \\
\end{aligned}$$

$$+ \sin \Omega \tau_c) - \tau_b^2 \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_b + \sin \Omega \tau_b \right) e^{-\lambda_n^2(\tau_c - \tau_b)} \Big\}$$

$$- \frac{1}{\Omega} \frac{1}{\left[ \left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1 \right]^2} \left\{ \tau_c \left\{ 2 \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau_c + 4 \left( \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau_c - 2 \cos \Omega \tau_c \right\} \right.$$

$$\left. - \tau_b \left\{ 2 \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau_b + 4 \left( \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau_b - 2 \cos \Omega \tau_b \right\} e^{-\lambda_n^2(\tau_c - \tau_b)} \right\}$$

$$+ \frac{1}{\Omega^2} \frac{2}{\left[ \left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1 \right]^3} \left\{ \left( \frac{\lambda_n^2}{\Omega} \right)^3 \cos \Omega \tau_c + 3 \left( \frac{\lambda_n^2}{\Omega} \right)^2 \sin \Omega \tau_c - 3 \left( \frac{\lambda_n^2}{\Omega} \right) \cos \Omega \tau_c \right.$$

$$- \sin \Omega \tau_c - \left\{ \left( \frac{\lambda_n^2}{\Omega} \right)^3 \cos \Omega \tau_b + 3 \left( \frac{\lambda_n^2}{\Omega} \right)^2 \sin \Omega \tau_b - 3 \left( \frac{\lambda_n^2}{\Omega} \right) \cos \Omega \tau_b \right.$$

$$\left. - \sin \Omega \tau_b \right\} e^{-\lambda_n^2(\tau_c - \tau_b)} \Big\} \Big\} \Big\} + \frac{1}{1 + \mu \sigma} B \left[ \frac{(Y-1)}{\Omega(\tau_c - \tau_e)^2} (\tau - \tau_c)^2 \right.$$

$$+ \delta \frac{(Y-1)}{\Omega(\tau_c - \tau_e)} \left\{ \frac{1}{\Omega^2} (\sin \Omega \tau_c - \sin \Omega \tau) + \frac{1}{\Omega} (\tau - \tau_c) \cos \Omega \tau_c \right\}$$

$$+ \delta \left\{ \frac{1}{\Omega} (\cos \Omega \tau_c - \cos \Omega \tau) - (\tau - \tau_c) \sin \Omega \tau_c \right\} + \frac{Y-1}{\Omega(\tau_c - \tau_e)} \frac{\delta}{\Omega} \left\{ \Omega(\tau + \tau_c) (\cos \Omega \tau \right.$$

$$+ \Omega \tau \sin \Omega \tau - \cos \Omega \tau_c - \Omega \tau_c \sin \Omega \tau_c) - 2 \Omega \tau \cos \Omega \tau - (\Omega^2 \tau^2$$

$$- \tau) \sin \Omega \tau + 2 \Omega \tau_c \cos \Omega \tau_c + (\Omega^2 \tau_c^2 - \tau) \sin \Omega \tau_c - \Omega^2 \tau \tau_c (\sin \Omega \tau - \sin \Omega \tau_c) \Big\} \Big]$$

$$+ F(\xi) B \left[ \frac{Y-1}{\Omega(\tau_c - \tau_e)} (\tau - \tau_c) (1 + \delta \sin \Omega \tau) + \delta (\sin \Omega \tau - \sin \Omega \tau_c) \right]$$

$$- \sum_{n=1}^{\infty} G_n(\xi) B \left[ \left[ \frac{(Y-1)}{\Omega(\tau_c - \tau_e)} - \frac{1}{\lambda_n^2} \left( 1 - e^{-\lambda_n^2(\tau_c - \tau_e)} \right) + \frac{\delta}{\Omega} \frac{(Y-1)}{\Omega(\tau_c - \tau_e)} \frac{1}{\left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \sin \Omega \tau \right. \right. \right.$$

$$\begin{aligned}
& - \cos \Omega \tau - \left( \frac{\lambda_n^2}{\Omega} \sin \Omega \tau_c - \cos \Omega \tau_c \right) e^{-\lambda_n^2(\tau-\tau_c)} \} + \frac{\delta}{\left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1} \left\{ \frac{\lambda_n^2}{\Omega} \cos \Omega \tau \right. \\
& + \sin \Omega \tau - \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau_c + \sin \Omega \tau_c \right) e^{-\lambda_n^2(\tau-\tau_c)} \} \\
& + \frac{(Y-1)}{(\tau_d - \tau_c)} \delta \left[ \frac{(\tau - \tau_c)}{\left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1} \left( \frac{\lambda_n^2}{\Omega} \cos \Omega \tau + \sin \Omega \tau \right) - \frac{1}{\Omega} \frac{1}{\left[ \left( \frac{\lambda_n^2}{\Omega} \right)^2 + 1 \right]^2} \right. \\
& \left. \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau + 2 \left( \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau - \cos \Omega \tau - \left< \left( \frac{\lambda_n^2}{\Omega} \right)^2 \cos \Omega \tau_c \right. \right. \\
& \left. \left. + 2 \left( \frac{\lambda_n^2}{\Omega} \right) \sin \Omega \tau_c - \cos \Omega \tau_c \right> e^{-\lambda_n^2(\tau-\tau_c)} \right] \} \quad (46)
\end{aligned}$$

where

$$\tau_c = \frac{\alpha_1 t_c}{a^2} \quad (47)$$

$$\tau_d = \frac{\alpha_1 t_d}{a^2} \quad (48)$$

$$B = T - (T - \Delta e^{\Phi \tau_a}) \frac{(\tau_c - \tau_m)^2}{(\tau_d - \tau_m)^2} \quad (49)$$

Numerical Solution:

Since the analytical solution is limited to the case of a non re-radiating surface, a numerical solution is presented which takes into consideration the re-radiation effect.

The governing equations and boundary conditions are first non-dimensionalized by introducing the following dimensionless parameters:

$$Q(\tau) = \frac{q_0(t)}{q_0(0)} \quad (50)$$

$$D = \frac{\epsilon_i \sigma T_i^4}{q_0(0) R} \quad (51)$$

$$E = \frac{q_0(0) R \alpha}{K_i T_i} \quad (52)$$

$$H = \left( \frac{T_e}{T_i} \right)^4 \quad (53)$$

The complete governing equations and boundary conditions written in dimensionless form become:

$$\frac{\partial \theta_1(\xi, \tau)}{\partial \xi} = \frac{\partial^2 \theta_1(\xi, \tau)}{\partial \xi^2} \quad (54)$$

$$\frac{\partial \theta_2(\xi, \tau)}{\partial \xi} = \left( \frac{A}{\sigma} \right)^2 \frac{\partial^2 \theta_2(\xi, \tau)}{\partial \xi^2} \quad (55)$$

$$\theta_1(\xi, 0) = \theta_2(\xi, 0) = 0 \quad (56)$$

$$\theta_1(0, \tau) = \theta_2(0, \tau) \quad (57)$$

$$\frac{\partial \theta_1(0, \tau)}{\partial \xi} = \mu \frac{\beta}{\sigma} \frac{\partial \theta_2(0, \tau)}{\partial \xi} \quad (58)$$

$$\frac{\partial \theta_2(\beta, \tau)}{\partial \xi} = 0 \quad (59)$$

$$-\frac{\partial \theta_1(-1, \tau)}{\partial \xi} = Q(\tau) [1 + \delta \sin \omega \tau] - D \left\{ [1 + E \theta_1(-1, \tau)]^4 - H \right\} \quad (60)$$

By setting  $D = 0$ , the numerical solution gives the case of a non re-radiating surface. By setting  $Q(\tau) = 1$  the solution to case (i) is obtained.

Details of the formulation of the numerical solution is given in Appendix A. The computer programs of the numerical solution for cases (i) and (ii) are presented in Appendices B and C respectively.

### III. RESULTS

#### Case (i) - Constant Free Stream Conditions

The transient temperature behavior in the refractory material,  $\theta_1(\xi, \tau)$ , for a non re-radiating surface under constant free stream condition is described by equation (16). This simple analytical solution of the idealized model is obtained for the purpose of making a parametric study of the problem. Equation (16) contains four parameters,  $\mu$ ,  $\sigma$ ,  $\delta$  and  $\Omega$ , which govern the temperature behavior. The eigenvalues,  $\lambda_n$ , are obtained from equation (13). Computer programs for determining  $\lambda_n$  and for evaluating  $\theta_1(\xi, \tau)$  are presented in Appendices D and E respectively.

Figure 5 gives the temperature response at the exposed surface of the refractory material,  $\xi = 1$ , and at the interface,  $\xi = 0$ , for various values of the governing parameters. The effect of  $\Omega$  on the temperature behavior during the initial period is shown in figure 5(a). At the exposed surface, values of  $\Omega$  greater than 100 have a negligible effect on the temperature level. For low values of  $\Omega$  the effect is significant. However, at the interface, temperature oscillation is damped out for  $\Omega \geq 100$  and negligible for  $\Omega = 10$ .

A long time solution is presented in figure 5(b). Temperature oscillation at the interface,  $\xi = 0$ , is not observable, while at the exposed surface,  $\xi = 1$ , the temperature oscillates about the curve  $\Omega = 0$ . Because of the time scale used in figure 5(b), individual cycles are not distinguishable. Instead, the locus of amplitudes of temperature oscillation for  $\Omega = 10$  is shown.

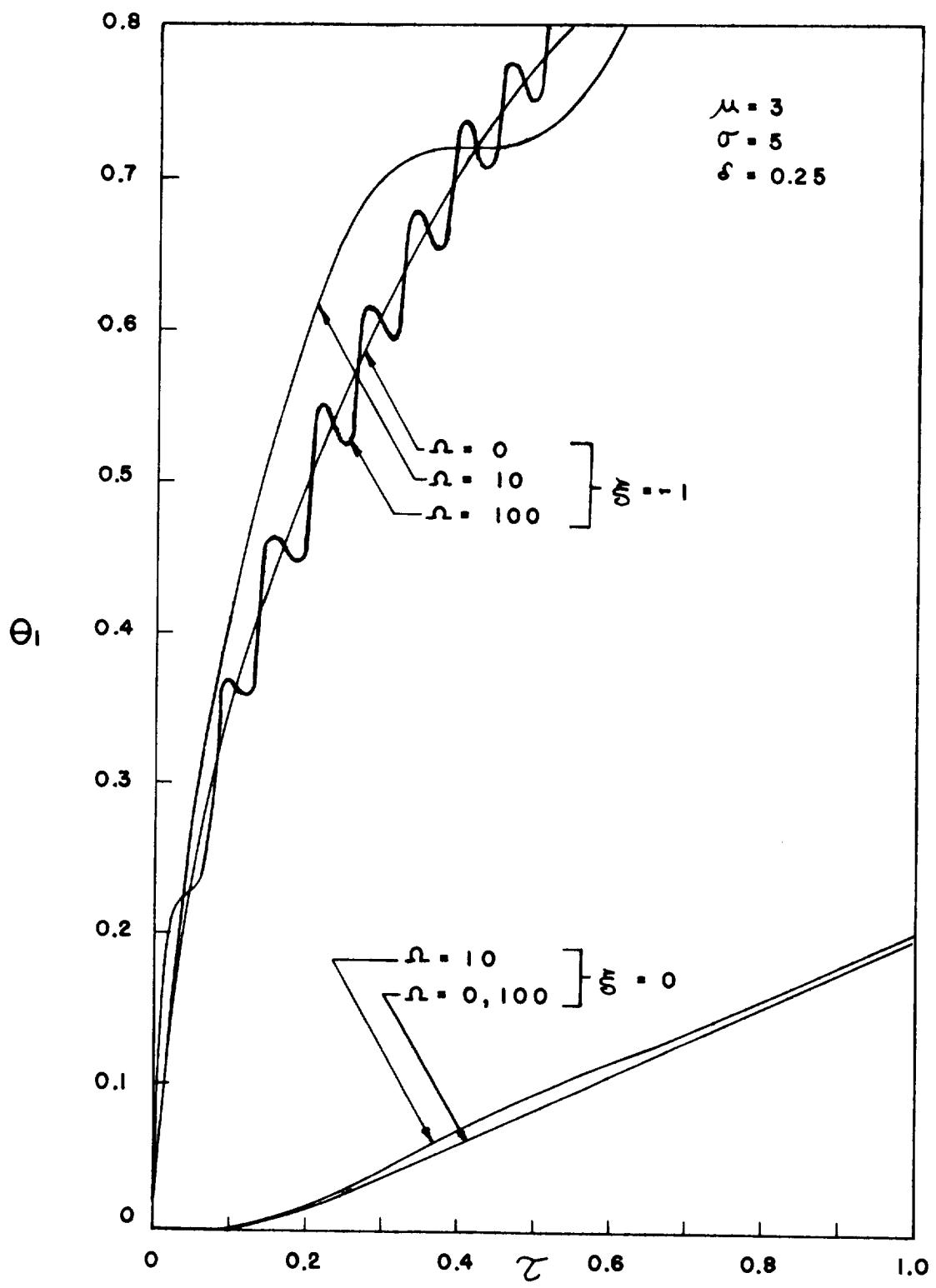
Since  $\delta$  is a measure of the amplitude of heat flux oscillation at the exposed surface, figures 5(c) and 5(d) are presented to illustrate its effect on the temperature behavior. For values of  $\delta$  as high as 0.75, no effect is observed at the interface for  $\Omega = 100$ . At the exposed surface a short time solution, figure 5(c), shows that the amplitude of temperature oscillation increases with increasing  $\delta$ .

The parameter  $\mu$ , which is defined as  $\frac{k_2}{k_1} \sqrt{\frac{\alpha_1}{\alpha_2}}$

has a significant effect on the temperature level. While this effect is not pronounced at small values of  $\tau$  (figure 5(e)), it becomes appreciable at large values of  $\tau$  (figure 5(f)).

Figures 5(g) and 5(h) give the temperature response for two values of  $\sigma$ . The temperature level is observed to decrease as  $\sigma$  is increased.

Figure 5(g), which gives a short time solution, indicates that for  $\sigma = 50$  the solution does not converge to the initial value, i.e.  $\theta_1(\xi, 0) = 0$ , for  $\tau = 0$ . This indicates that additional terms in the series appearing in equation (16) should be taken. In constructing the charts for figure 5 the series was truncated at  $n = 32$ .



(a) Effect of  $\Omega$ - short time

Figure 5.- Temperature response for case Ci): Constant free stream conditions.

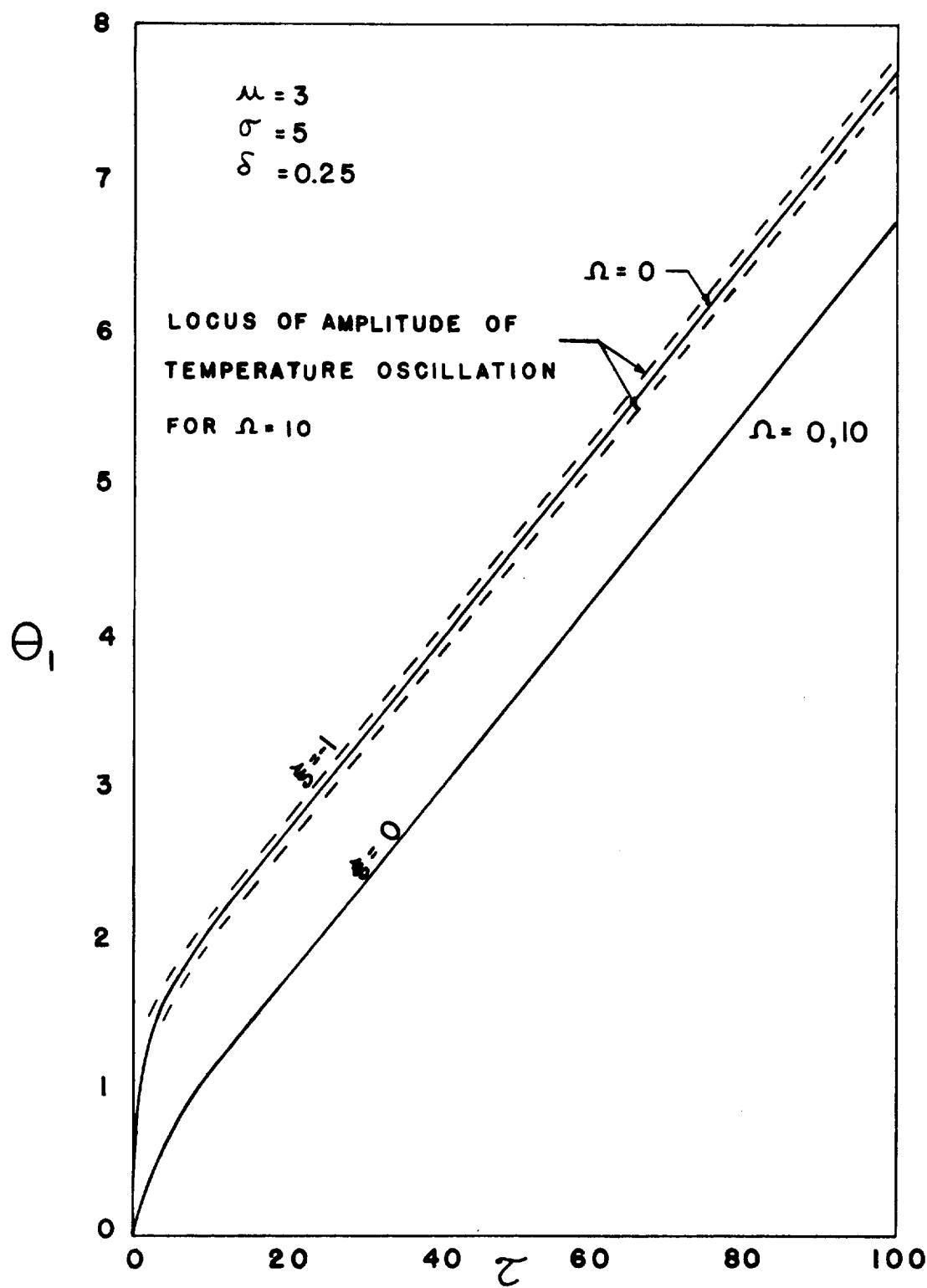
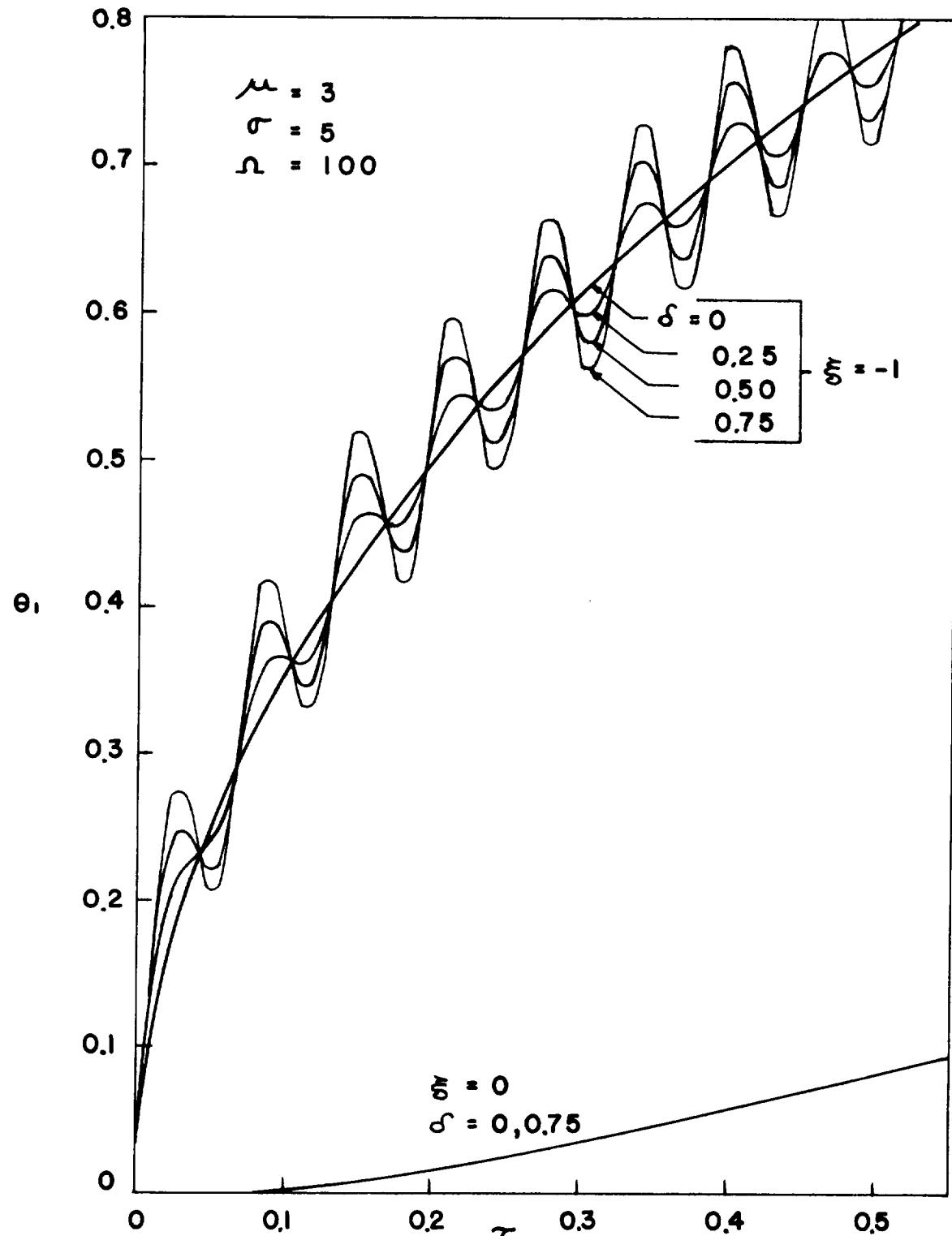
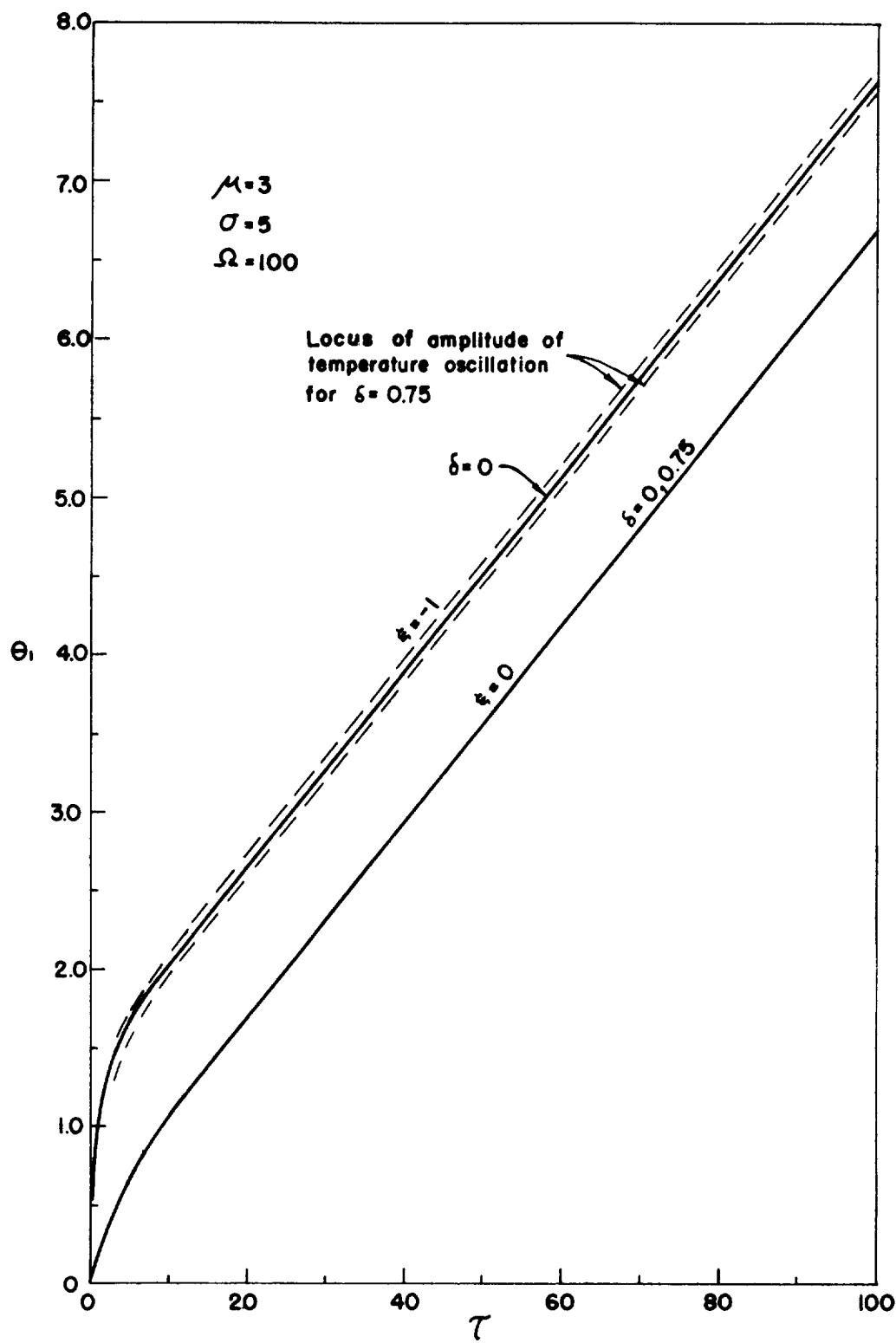


Figure 5.- Continued.



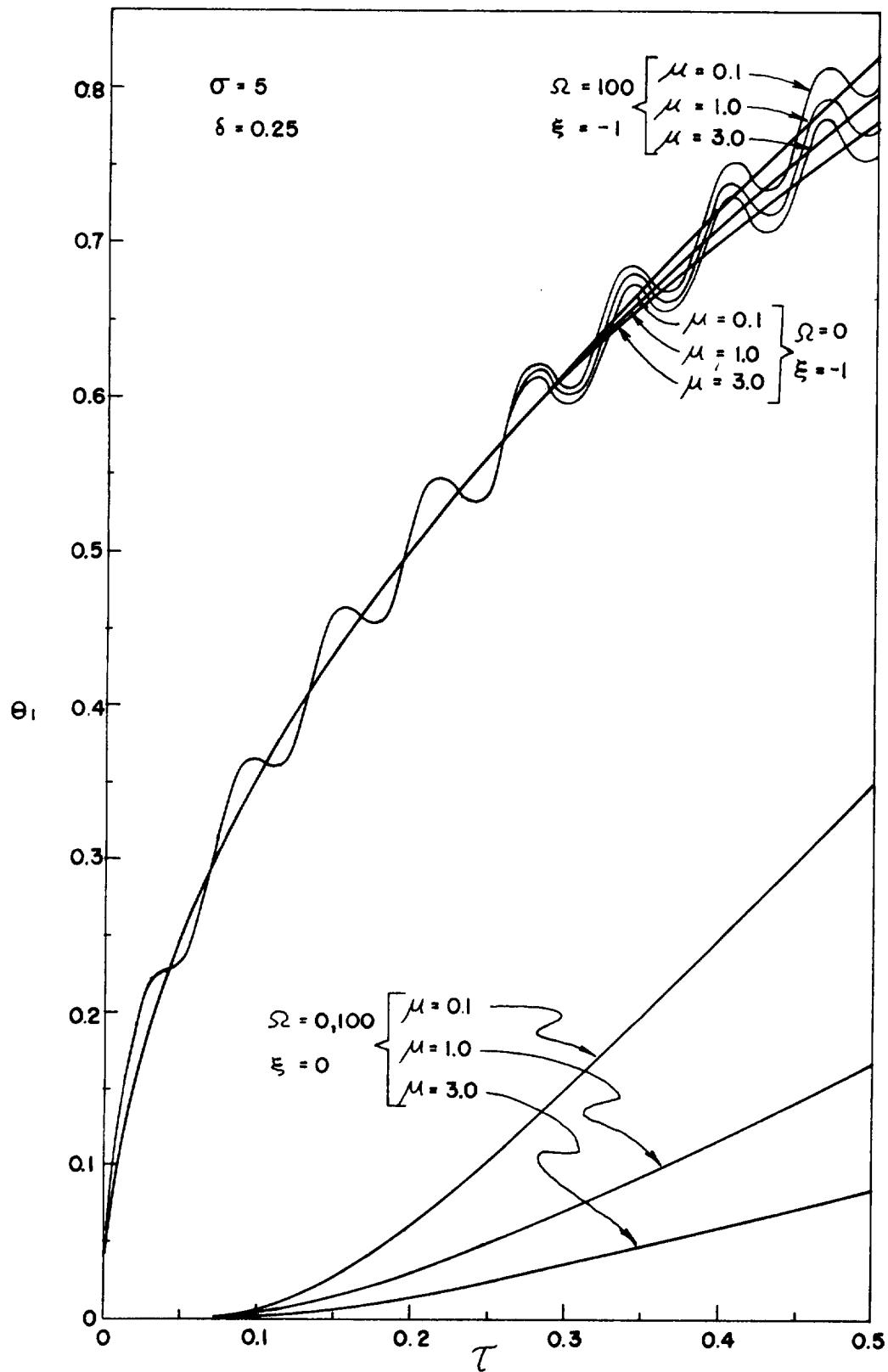
(c) Effect of  $\delta$  - Short time

Figure 5.- Continued.



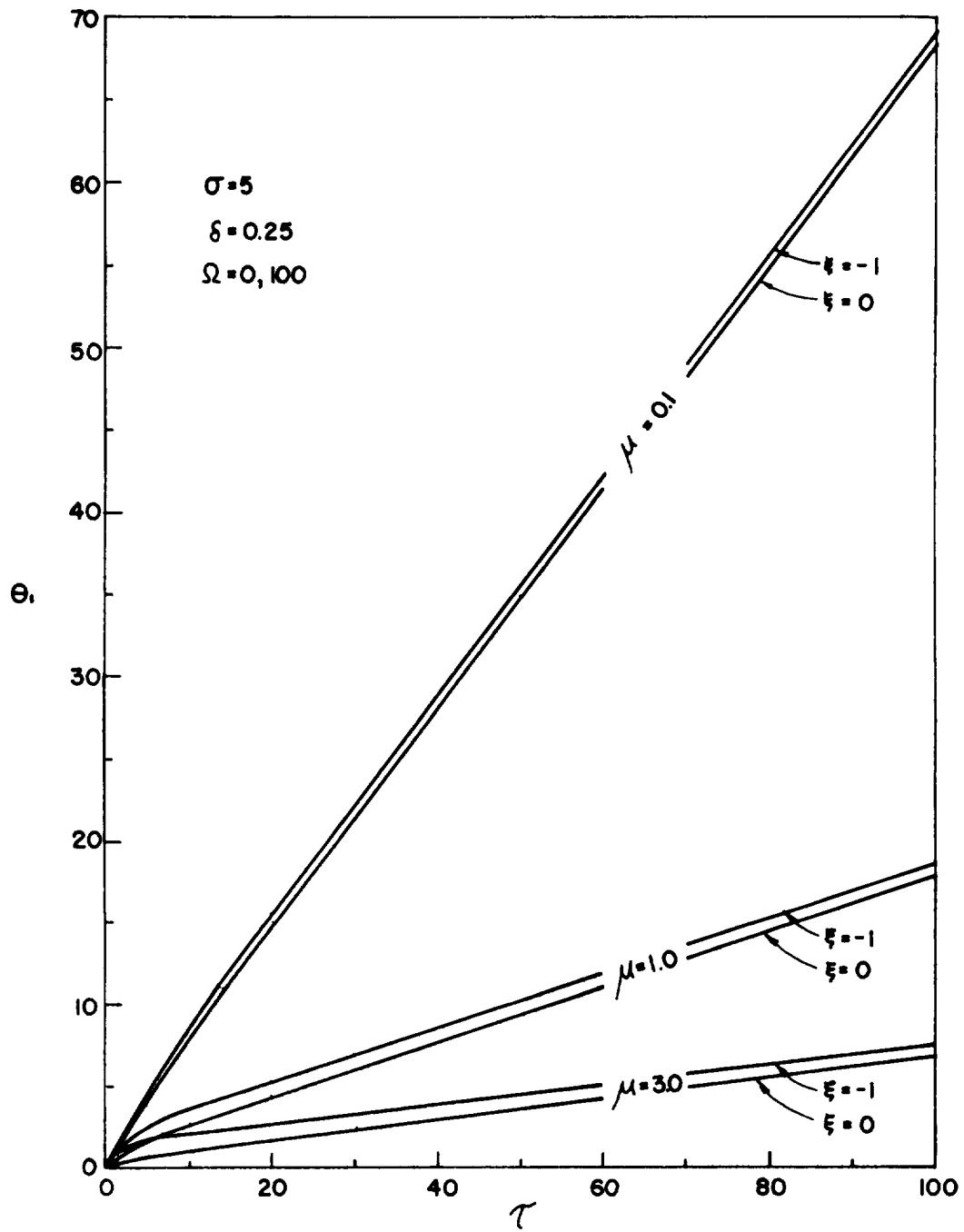
(d) Effect of  $\delta$  - long time

Figure 5. - continued.

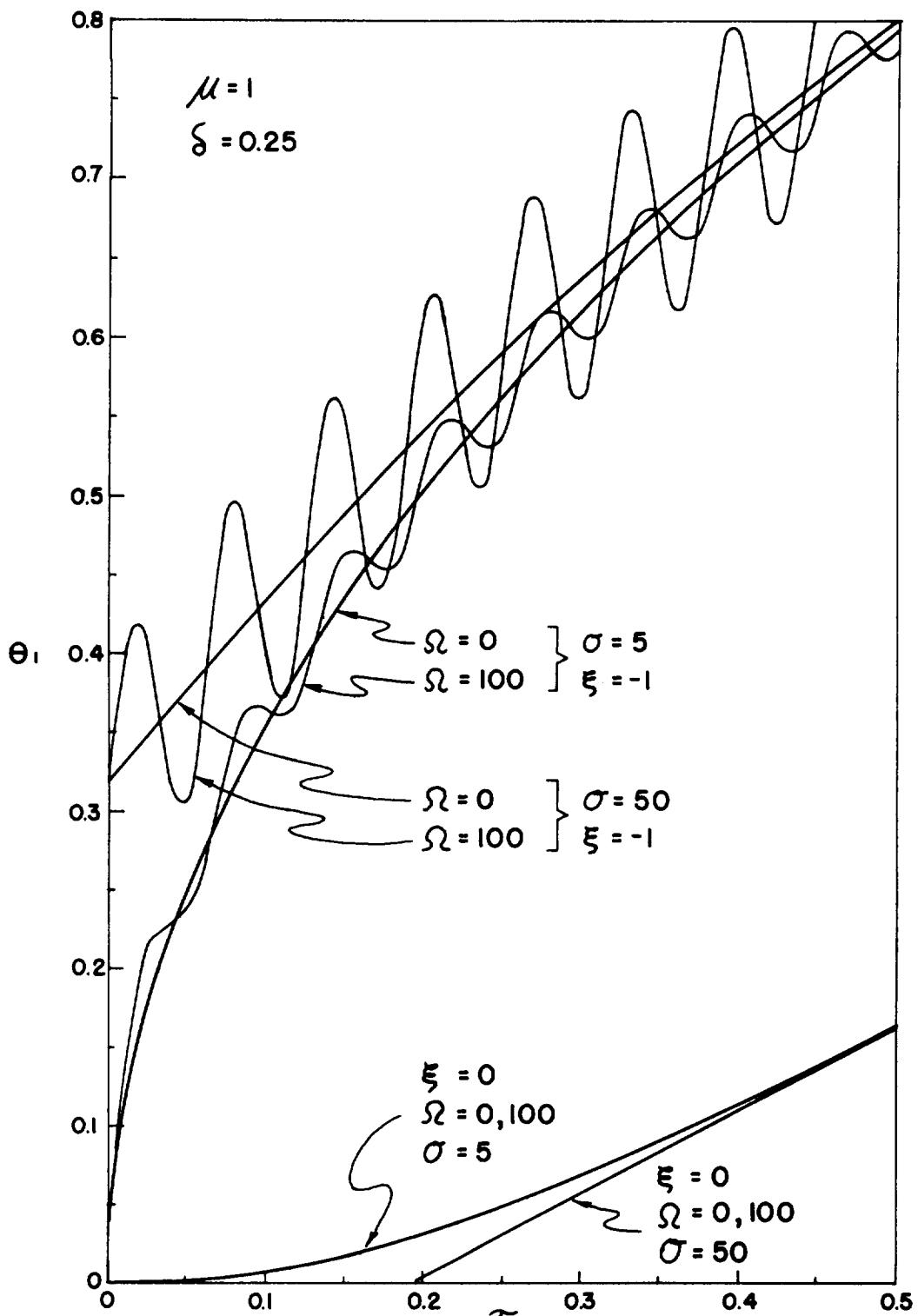


(e) Effect of  $\mu$  — short time

Figure 5.— continued.

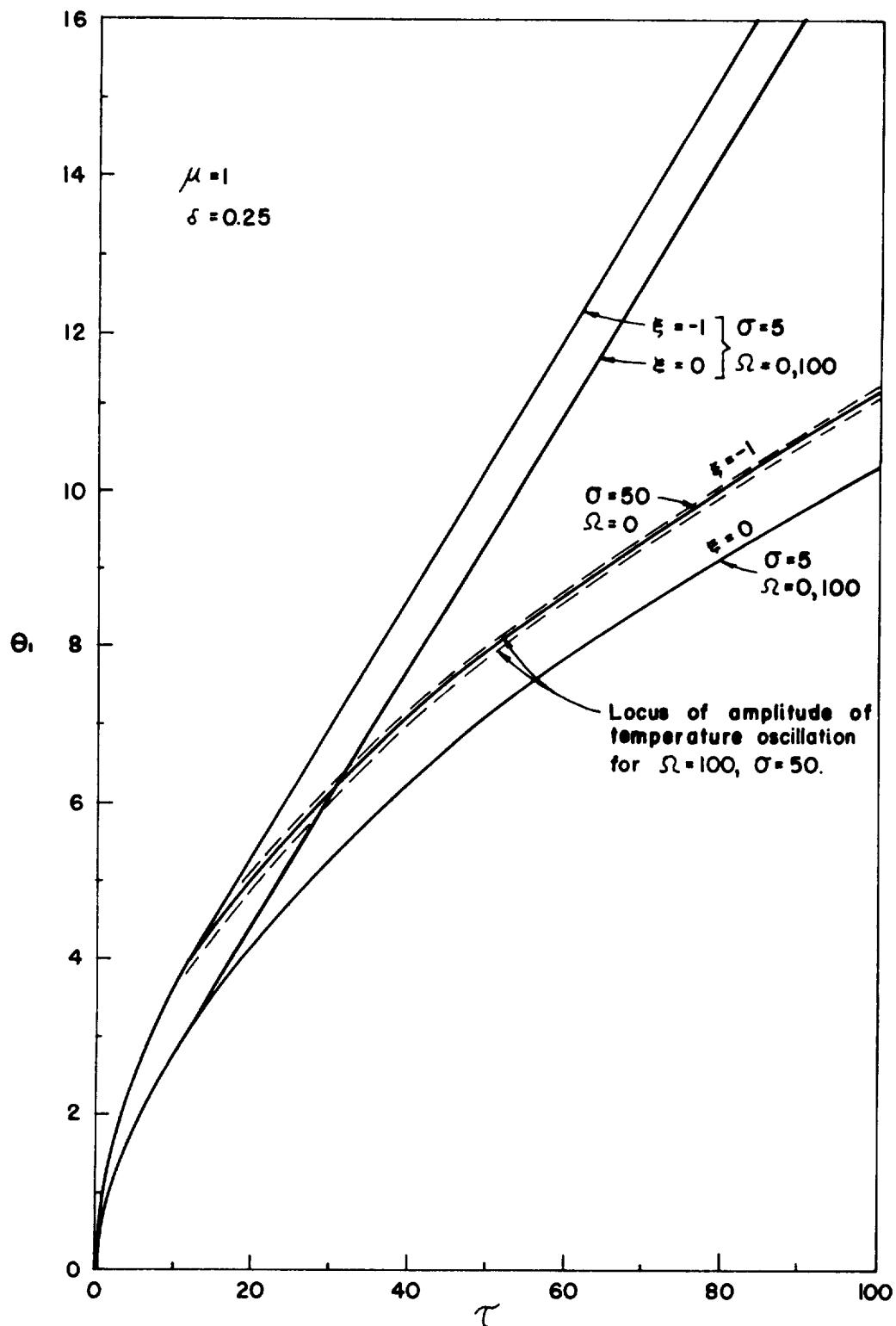


(f) Effect of  $\mu$  - long time  
 Figure 5. - Continued.



(g) Effect of  $\sigma$  - short time

Figure 5.- Continued.



(h) Effect of  $\sigma$  - long time

Figure 5. - Concluded.

Case (ii) - Variable Free Stream Conditions: Entry Case:

The temperature response of the blade's composite structure during entry is determined analytically and numerically for a non re-radiating surface, and numerically for a re-radiating surface. The computer program for the analytical solution for the four stages (equations (36), (40), (43), and (46)) is presented in Appendix F. The program for the numerical solution is given in Appendix C.

To obtain the temperature response for this case the aerodynamic heating curve during entry must be specified. A heating curve for a sphere of one foot radius in a non-lifting trajectory is selected as an example (figure 4). The following data is obtained from this curve and is used to evaluate analytically the temperature response during the four stages of this trajectory:

$\bar{A}$	=	0.0506	$\frac{1}{\text{sec}^2}$
B	=	44.576	
$t_a$	=	72.5	sec
$t_b$	=	108.5	sec
$t_c$	=	133	sec
$t_d$	=	154	sec
$t_m$	=	119	sec
$q_o(0)$	=	1.5451	$\text{Btu}/\text{ft}^2\text{-sec}$
$\Gamma$	=	54.494	
$\Upsilon$	=	0.3775	
$\Lambda$	=	4.471	
$\Psi$	=	0.033	1/sec

The blade construction is assumed to consist of 0.07 inch of stainless steel slab covered with 0.02 inch alumina. The thermal properties for the structural and refractory materials, evaluated at  $2000^{\circ}\text{F}$ , are

$$K_1 = 0.903 \times 10^{-3} \text{ Btu/sec-ft-}^{\circ}\text{F}$$

$$K_2 = 0.458 \times 10^{-2} \text{ Btu/sec-ft-}^{\circ}\text{F}$$

$$\alpha_1 = 1.18 \times 10^{-5} \text{ ft}^2/\text{sec}$$

$$\alpha_2 = 5.7 \times 10^{-5} \text{ ft}^2/\text{sec}$$

For such a structure the dimensionless parameters  $\mu$  and  $\sigma$  are 2.31 and 1.59 respectively. For a rotor angular velocity  $\omega = 4000$  RPM the dimensionless angular velocity,  $\Omega$ , is 100.

Using the above input data, the computer program (Appendix F) for equations (36), (40), (43), and (46) was used to calculate the temperature response at the exposed surface,  $\xi = -1$ , and at the interface,  $\xi = 0$ , during the four stages. Figure 6(a) gives the variation of the dimensionless temperature with dimensionless time. The heating curve of figure 4 is non dimensionalized and plotted on the same graph. The temperature at the exposed surface is seen to continue to rise even after the aerodynamic heating decreases during entry. This is expected for a non re-radiating model which is insulated at the back side.

To check this analytical solution, the same problem is solved numerically using the computer program given in Appendix C. The result is plotted in figure 6(a). Excellent agreement is indicated between the analytical and numerical solutions.

To examine the effect of re-radiation, a numerical solution is obtained using the following re-radiation data:

$$D = 0.0126$$

$$E = 0.01355$$

$$H = 0.397$$

which is based on  $\epsilon_i = 0.78$ ,  $T_i = 630^{\circ}\text{R}$ ,  $T_e = 500^{\circ}\text{R}$  and  $R = 3$ . The result plotted in figure 6(a) indicates that the maximum surface temperature peaks at approximately the time the maximum heat flux takes place. It is noted that re-radiation has a significant effect on the temperature level during entry. For the example selected, re-radiation decreases the maximum temperature by a factor of six.

The dimensionless temperature curve of figure 6(a) is presented in a dimensional form in figure 6(b). The non re-radiating model results in a maximum temperature of  $28,200^{\circ}\text{R}$  while the re-radiating solution gives a maximum temperature of  $5000^{\circ}\text{R}$ .

Figure 6(c) shows the temperature drop across the refractory material during entry for a re-radiating and a non re-radiating surface. For the re-radiating surface the temperature drop becomes negative after the maximum aerodynamic heating has been reached. That is, as the aerodynamic heating begins to decrease during entry, the interface temperature becomes higher than the exposed surface temperature.

Because of the scale chosen for figure 6(a), the temperature oscillation is not detectable on the graph. Figures 7 and 8 show enlarged portions of figure 6(a) at the four stages of the heating curve during entry for non re-radiating and re-radiating surfaces respectively. No temperature oscillation is detected at the interface for  $\Omega = 100$ . Temperature oscillation becomes quasi-periodic soon after entry with an amplitude which is small

compared to the temperature level for a non-rotating blade ( $\Omega = 0$ ). The analytical solution for a non-rotating blade is obtained by setting  $\delta = 0$  rather than  $\Omega = 0$ . This is necessary because some terms in the solution are divided by  $\Omega$ .

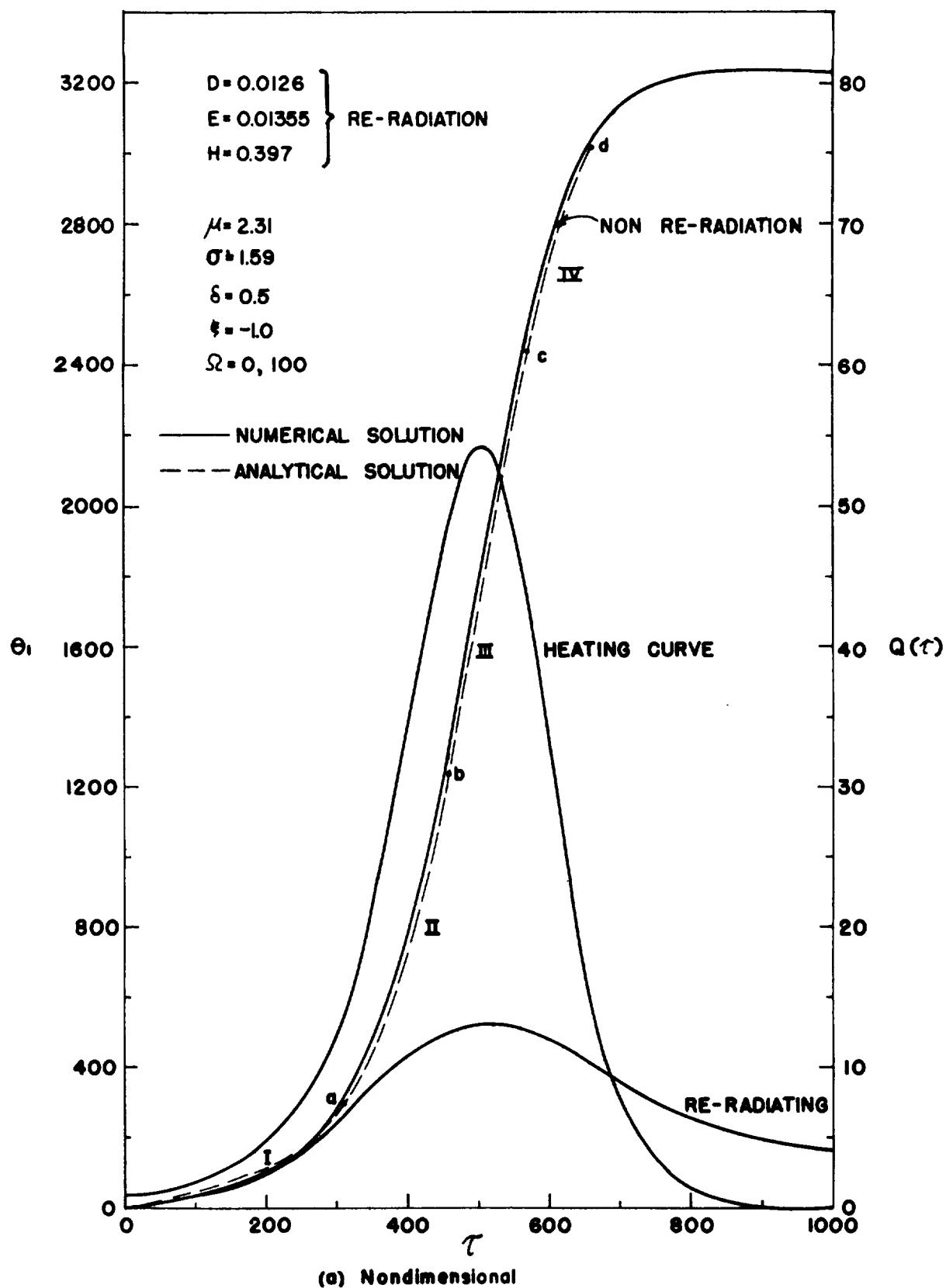
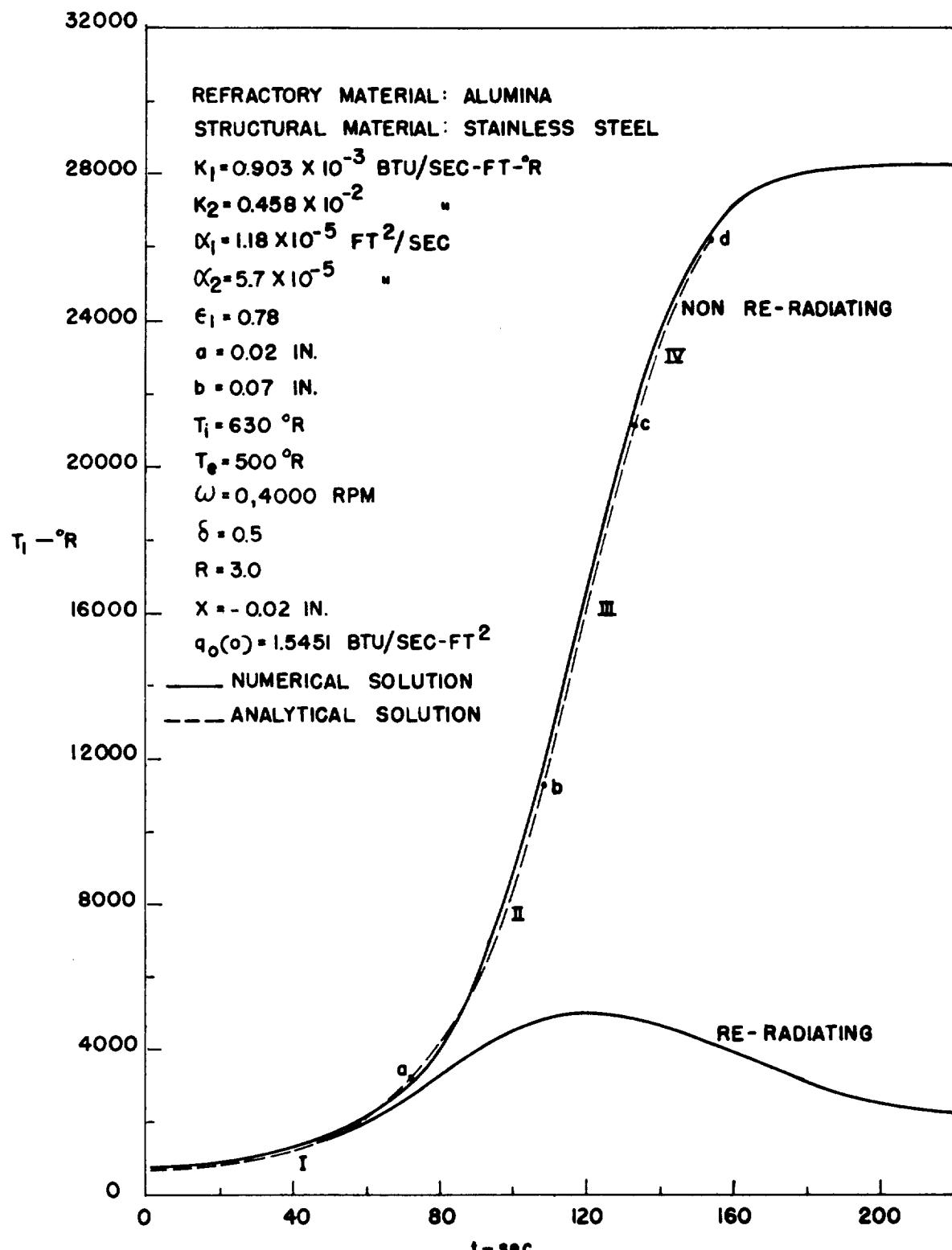
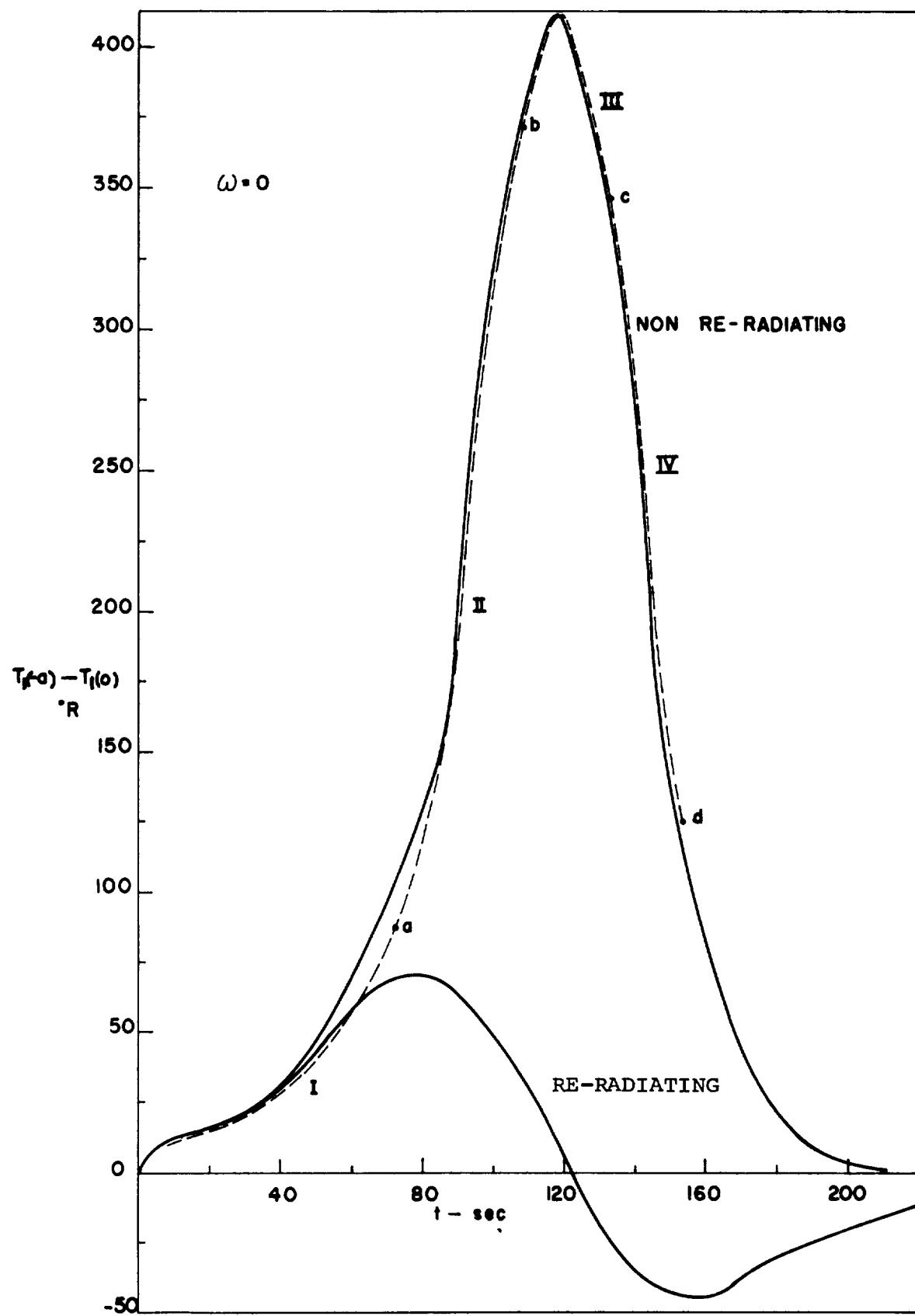


Figure 6.— Temperature response during entry. Case (ii): Variable free stream conditions.



(b) Dimensional  
Figure 6.- Continued.



(c) Refractory temperature drop  
Figure 6.- Concluded.

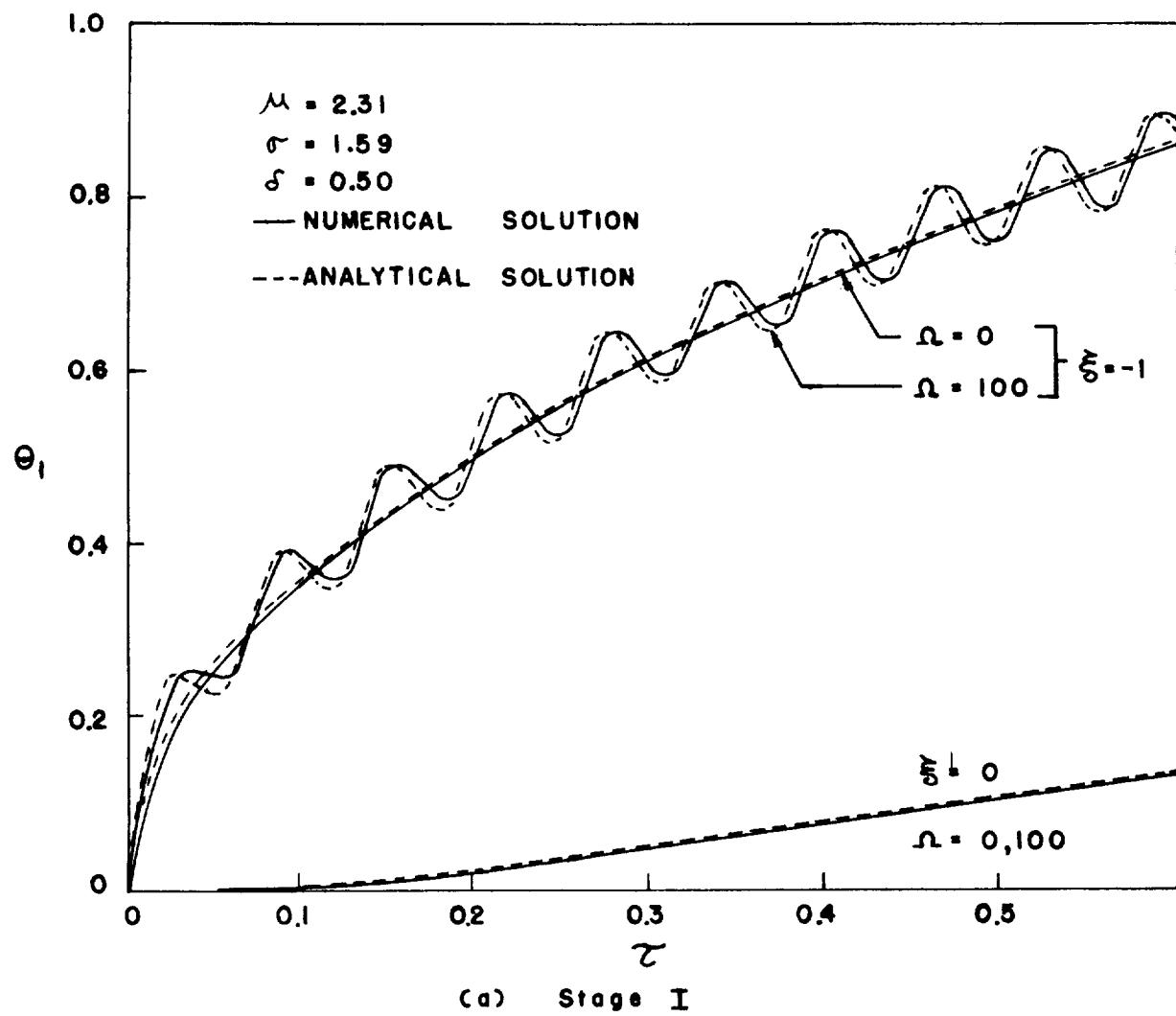
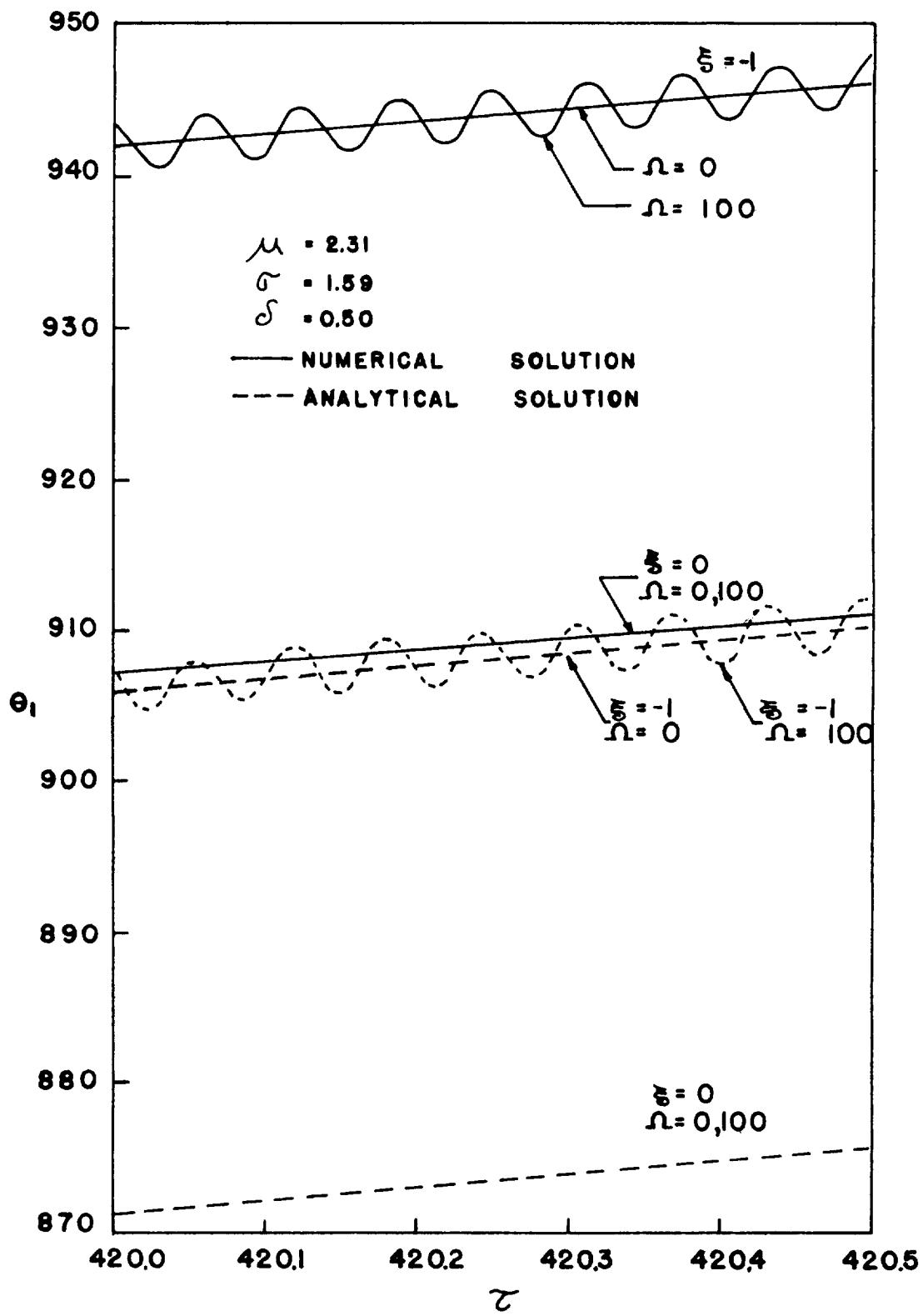


Figure 7.- Temperature oscillation during entry for a non re-radiating surface  
Case Cii): Variable free stream conditions.



(b) Stage II  
Figure 7.- Continued.

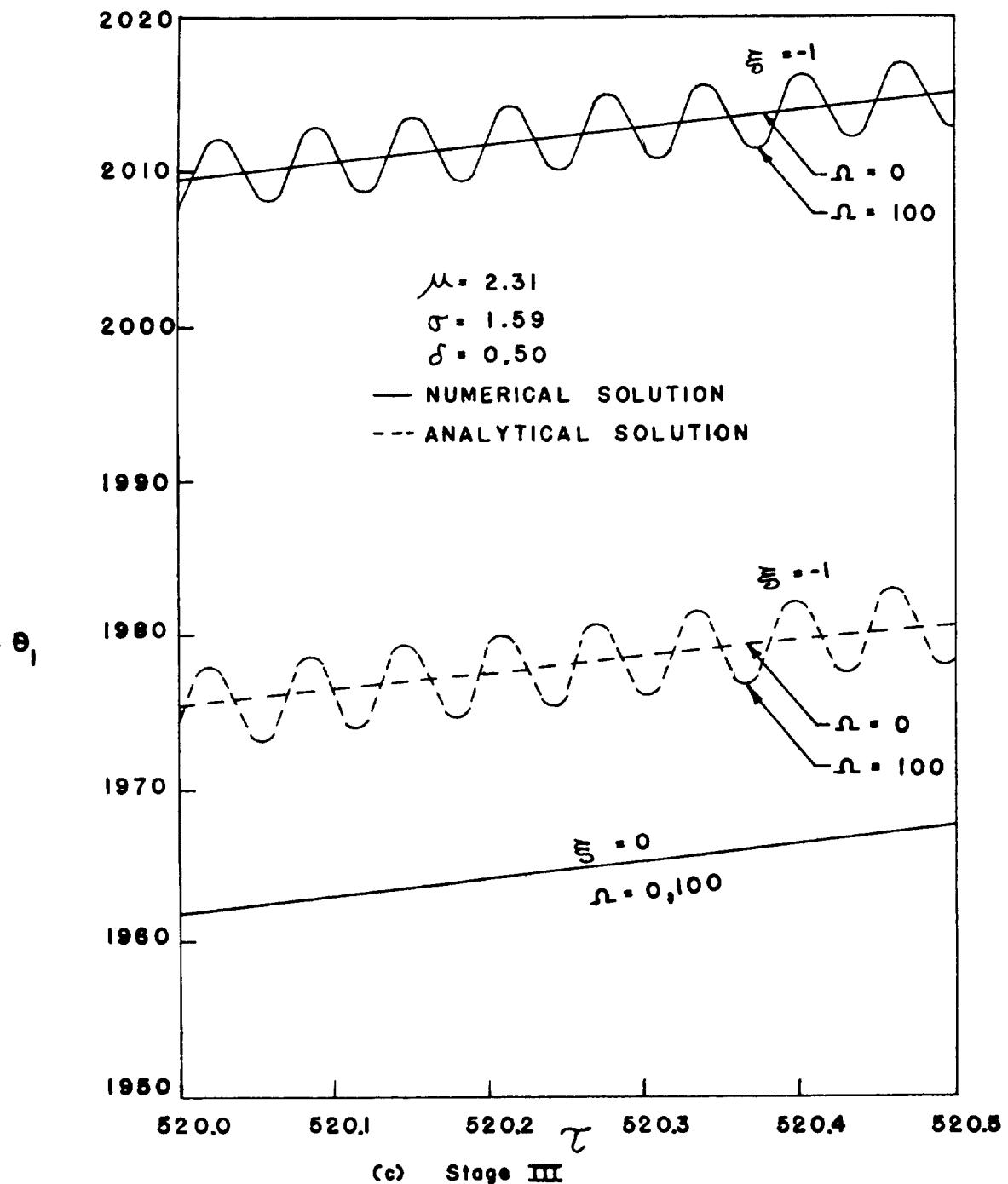
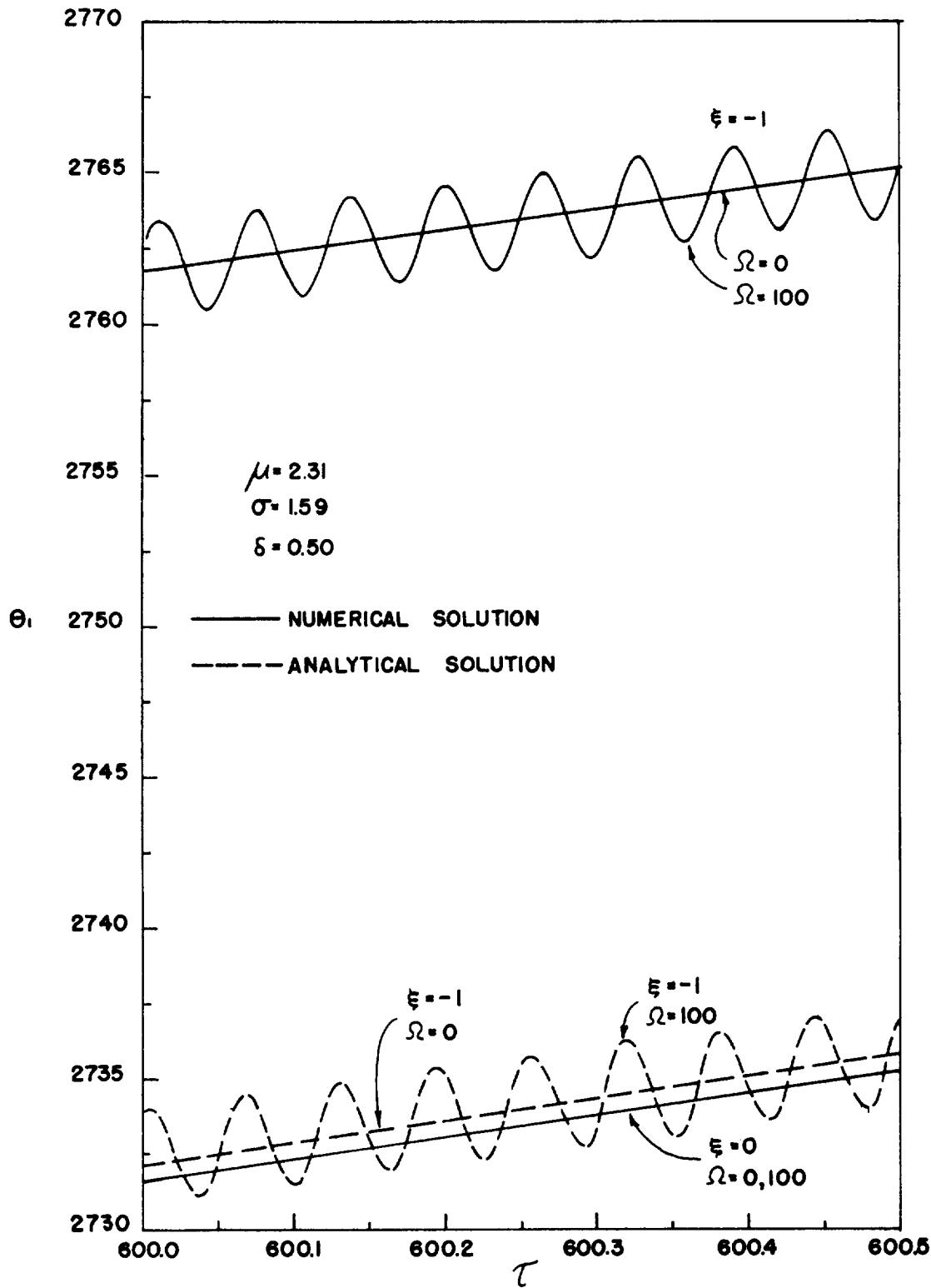
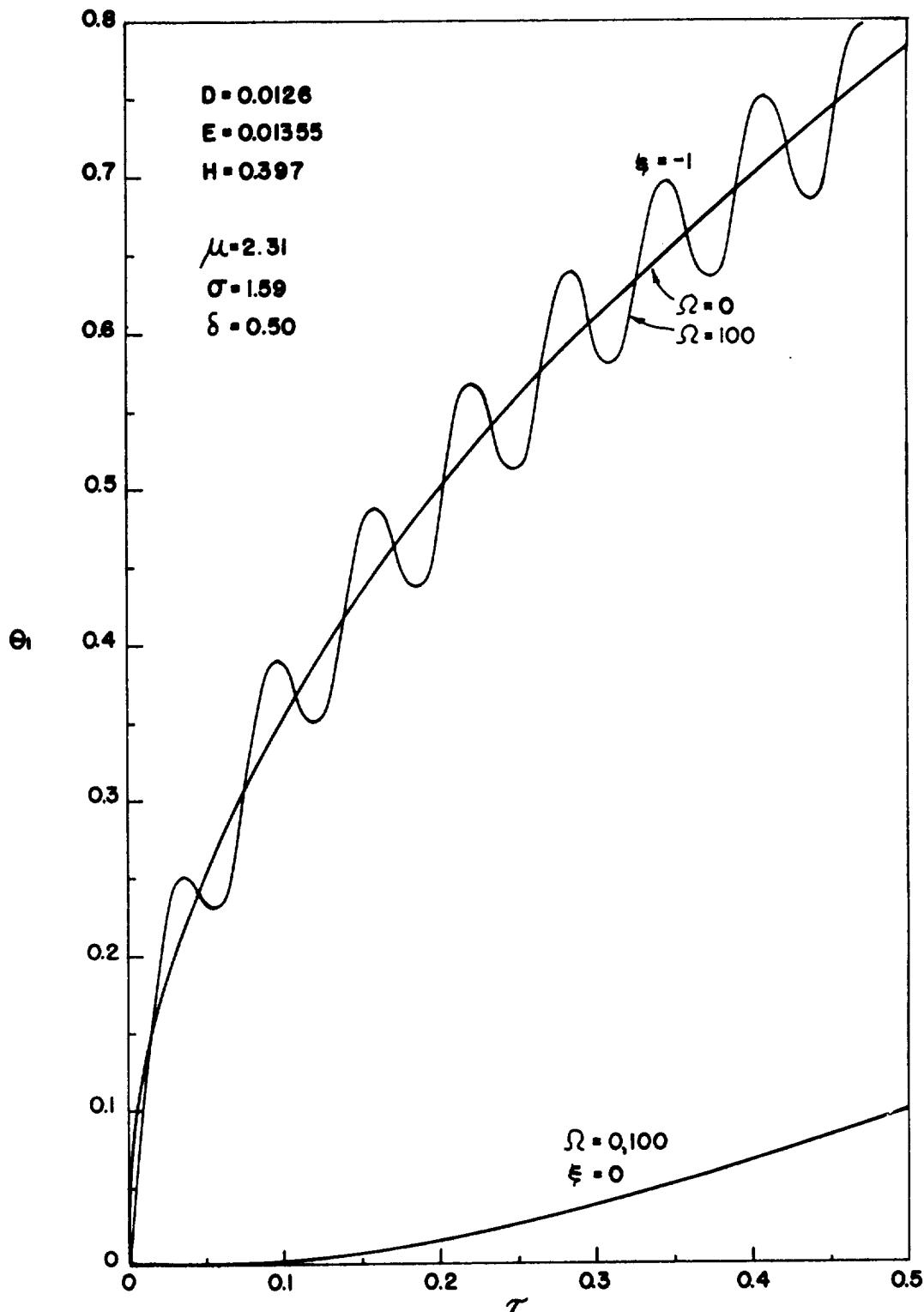


Figure 7. — Continued.

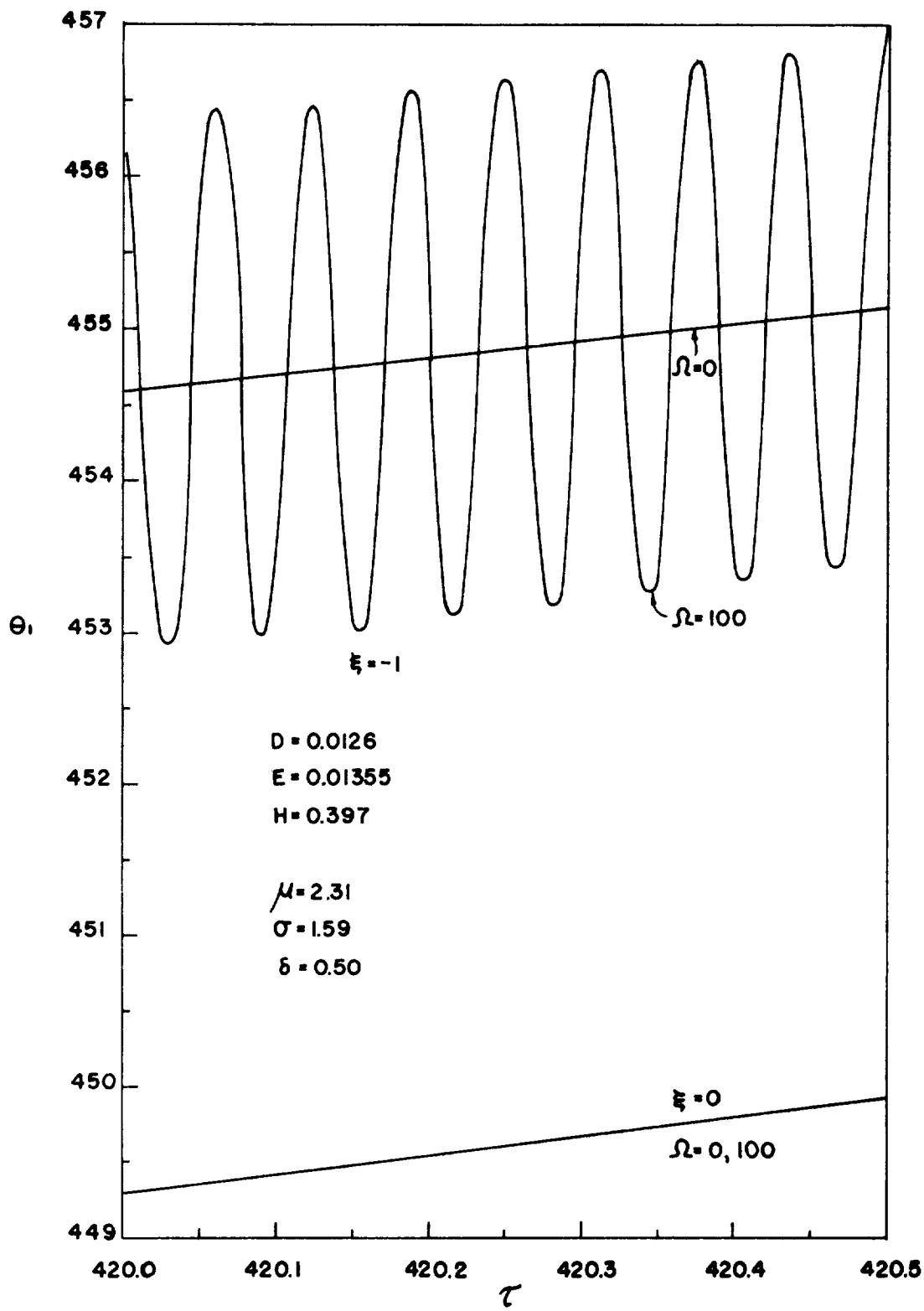


(d) Stage IV  
Figure 7.— Concluded.

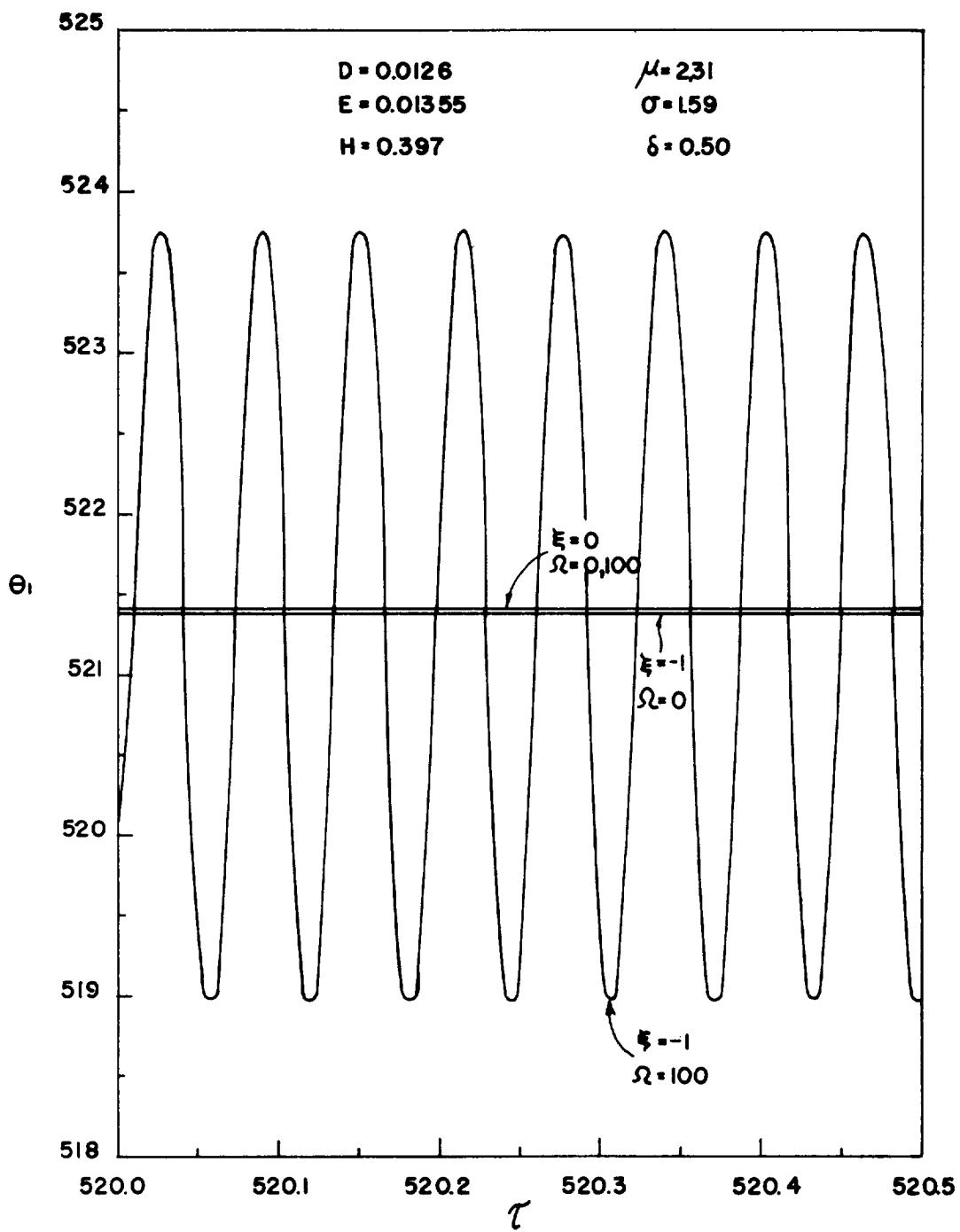


(a) Stage I

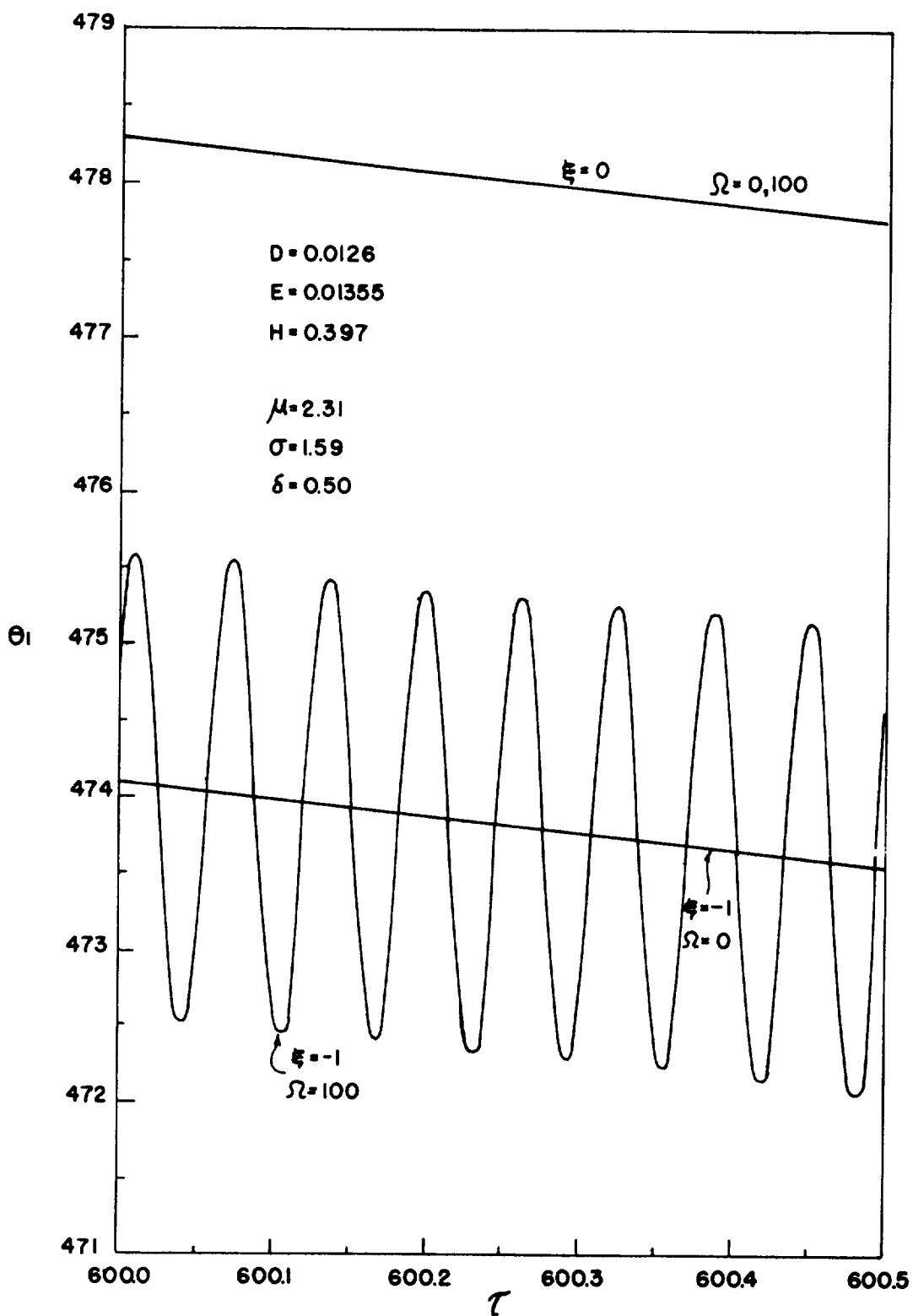
Figure 8.- Temperature oscillation during entry for a re-radiating surface.  
Case (ii): Variable free stream conditions.



(b) Stage II  
 Figure 8. — Continued.



(c) Stage III  
Figure 8.—Continued.



(d) Stage IV  
Figure 8.- Concluded.

#### IV. CONCLUDING REMARKS

1. While blade rotation may have an appreciable effect on the aerodynamic heat flux, oscillation in this flux due to rotation results in temperature amplitudes which are small compared to the temperature level for an equal but non oscillating flux ( $\Omega = 0$  or  $\delta = 0$ ). This is particularly true for high angular velocities and after the initial transient time. In the entry example considered, an angular velocity of 4000 RPM results in a negligible effect on the temperature level at the exposed surface, while a velocity of 400 RPM affects the temperature only during the first fraction of a second of entry time. At the interface no oscillation in temperature is observed for an angular velocity of 400 RPM. Unless there is specific interest in the temperature oscillation at the exposed surface during the initial time of entry for a slowly rotating blade, adequate results are obtained by setting  $\Omega = 0$  (or  $\delta = 0$ ) in the solution. The aerodynamic heat flux must, however, still be adjusted to take into consideration the effect of rotation. In the analytical model used, the factor R is introduced for that purpose.

2. Re-radiation has a significant and favorable effect on the temperature response. Excessively high temperatures result when re-radiation is neglected.

For the entry example considered the maximum surface temperature occurs at approximately the time the aerodynamic heating reaches its maximum value. During the portion of entry where the heat flux is decreasing, the temperature of the exposed surface lags behind that of the interface.

This suggests that the temperature profile throughout the composite structure be monitored during entry.

3. Because re-radiation is important, the analytical solution for case (ii) (entry), which is restricted to a non re-radiating surface, is of limited practical use. The numerical solution, on the other hand, may require excessive computer time depending on stability requirements and angular velocity. Stability considerations limit the maximum value of the time increment used in advancing the numerical solution. Furthermore, in order to obtain sufficient points during a temperature cycle, the time increment must be a fraction of  $\frac{2\pi}{\Omega}$ . This limit may be a more severe than stability requirements.

4. Since the parametric charts of case (i) (constant free stream conditions), figure 5, are for a non re-radiating surface, they may be used only to give trends in temperature behavior as the various governing parameters are changed.

## REFERENCES

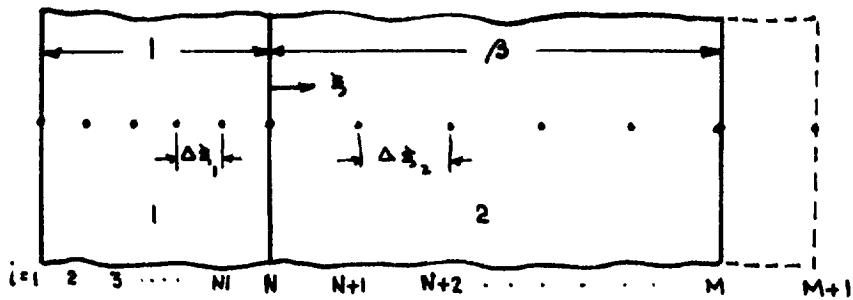
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## APPENDIX A

### FORMULATION OF THE NUMERICAL SOLUTION

#### FINITE DIFFERENCE FORMULATION

##### Governing Equations:



For material 1 ( $i = 1, 2, \dots, N_1$ ), equation (54) is approximated by

$$\frac{\theta'_i - \theta_i}{\Delta\tau} = \frac{\theta_{i-1} - 2\theta_i + \theta_{i+1}}{\Delta\xi_i^2}$$

or

$$\theta'_i = \theta_i + \frac{\Delta\tau}{\Delta\xi_i^2} (\theta_{i-1} - 2\theta_i + \theta_{i+1}) \quad (A1)$$

where

$$\Delta\xi_i = \frac{1}{N_1}$$

$N_1$  being the number of strips in material 1.

For material 2 ( $i = N+1, N+2, \dots, M$ ), equation (55) is approximated by

$$\frac{\theta_i' - \theta_i}{\Delta\tau} = \left(\frac{\beta}{\sigma}\right)^2 \left( \frac{\theta_{i-1} - 2\theta_i + \theta_{i+1}}{\Delta\xi_2^2} \right)$$

or

$$\theta_i' = \theta_i + \left(\frac{\beta}{\sigma}\right)^2 \frac{\Delta\tau}{\Delta\xi_2^2} (\theta_{i-1} - 2\theta_i + \theta_{i+1}) \quad (A2)$$

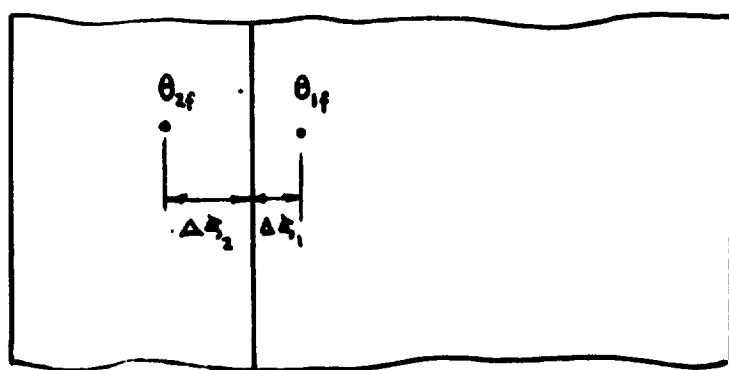
where

$$\Delta\xi_2 = \frac{\beta}{N^2}$$

$N^2$  being the number of strips in material 2.

### Boundary Conditions

To formulate the boundary conditions at the interface ( $i = N1 = n$ ) the fictitious temperatures  $\theta_{if}$  at a distance  $\Delta\xi_1$ , to the right of the interface, and  $\theta_{if}$  at a distance  $\Delta\xi_1$  to the left of interface are introduced. Then, by equation (A1)



$$\theta'_{(1)n} = \theta_n + \frac{\Delta\tau}{\Delta\xi_1^2} (\theta_{n-1} - 2\theta_n + \theta_{1f}) \quad (A3)$$

and by equation (A2)

$$\theta'_{(2)n} = \theta_n + \left(\frac{\beta}{\sigma}\right)^2 \frac{\Delta\tau}{\Delta\xi_2^2} (\theta_{2f} - 2\theta_n + \theta_{n+1}) \quad (A4)$$

To eliminate the fictitious temperatures  $\theta_{1f}$  and  $\theta_{2f}$ , boundary conditions (57) and (58) are used. Equation (57) gives

$$\theta_{(1)n} = \theta_{(2)n} \quad (A5)$$

Boundary condition (58) is approximated by

$$\frac{\theta_{1f} - \theta_{n-1}}{\Delta\xi_1} = \mu \frac{\beta}{\sigma} \left( \frac{\theta_{n+1} - \theta_{2f}}{\Delta\xi_2} \right)$$

or

$$\theta_{1f} = \theta_{n-1} + \frac{\mu\beta}{\sigma} \frac{\Delta\xi_1}{\Delta\xi_2} (\theta_{n+1} - \theta_{2f}) \quad (A6)$$

Equations (A3), (A4), (A5) and (A6) give

$$\theta'_n = \theta_n + C_3 \Delta\tau (\theta_{n-1} - \theta_n) + C_4 \Delta\tau (\theta_{n+1} - \theta_n) \quad (A7)$$

where

$$C_3 = \frac{\frac{2\beta}{\sigma} \frac{1}{\Delta\xi_1^2}}{\frac{\beta}{\sigma} + \mu \frac{\Delta\xi_2}{\Delta\xi_1}} \quad (A8)$$

$$C_4 = \frac{2\mu \left(\frac{\beta}{\sigma}\right)^2 \frac{1}{\Delta\xi_1 \Delta\xi_2}}{\frac{\beta}{\sigma} + \mu \frac{\Delta\xi_2}{\Delta\xi_1}} \quad (A9)$$

For the boundary condition at  $\xi = -1$  ( $i = 1$ ) a fictitious temperature  $\theta_0$  at a distance  $\Delta\xi_1$  to the left of the boundary at  $\xi = -1$  is introduced. Equation (A1) gives

$$\theta'_1 = \theta_1 + \frac{\Delta\tau}{\Delta\xi_1^2} (\theta_0 - 2\theta_1 + \theta_2) \quad (A10)$$

To eliminate the fictitious temperature  $\theta_0$ , boundary condition (60) is employed in finite difference form.

$$-\frac{(\theta_2 - \theta_0)}{2\Delta\xi_1} = Q(\tau) [1 + \delta \sin \Omega\tau] - D \left\{ [1 + E\theta_1]^4 - H \right\}$$

or

$$\theta_0 = \theta_2 + 2\Delta\xi_1 \left\{ Q(\tau) [1 + \delta \sin \Omega\tau] - D [(1 + E\theta_1)^4 - H] \right\} \quad (A11)$$

(A10) and (A11) give

$$\begin{aligned} \theta'_1 &= \theta_1 + \frac{2\Delta\tau}{\Delta\xi_1^2} \left\{ \theta_2 - \theta_1 + \Delta\xi_1 [Q(\tau) (1 + \delta \sin \Omega\tau)] \right. \\ &\quad \left. - D \Delta\xi_1 [(1 + E\theta_1)^4 - H] \right\} \end{aligned} \quad (A12)$$

The adiabatic condition at  $\xi = \beta$  is handled by setting

$$\theta_{m+1} = \theta_{m-1} \quad (A13)$$

where m is node at  $\xi = \beta$ .

### STABILITY

To establish the stability requirement in material 1, equation (A1) is rewritten as

$$\theta_i' = \frac{\Delta\tau}{\Delta\xi_i^2} (\theta_{i-1} + \theta_{i+1}) + \left(1 - 2 \frac{\Delta\tau}{\Delta\xi_i^2}\right) \theta_i \quad (A14)$$

stability consideration requires that

$$1 - 2 \frac{\Delta\tau}{\Delta\xi_i^2} \geq 0$$

or

$$\Delta\tau \leq \frac{\Delta\xi_i^2}{2} \quad (A15)$$

For material 2, equation (A2) is rewritten as

$$\theta_i' = \left(\frac{\beta}{\sigma}\right)^2 \frac{\Delta\tau}{\Delta\xi_i^2} (\theta_{i-1} + \theta_{i+1}) + \left[1 - 2 \left(\frac{\beta}{\sigma}\right)^2 \frac{\Delta\tau}{\Delta\xi_i^2}\right] \theta_i \quad (A16)$$

stability requires that

$$1 - 2 \left(\frac{\beta}{\sigma}\right)^2 \frac{\Delta\tau}{\Delta\zeta_2} \geq 0$$

or

$$\Delta\tau \leq \left(\frac{\sigma}{\beta}\right)^2 \frac{\Delta\zeta_2^2}{2} \quad (\text{A17})$$

To determine the stability condition at the interface, equation (A7) is rewritten as

$$\theta'_n = C_3 \Delta\tau \theta_{n-1} + C_4 \Delta\tau \theta_{n+1} + (1 - C_3 \Delta\tau - C_4 \Delta\tau) \theta_n \quad (\text{A18})$$

stability requires that

$$1 - C_3 \Delta\tau - C_4 \Delta\tau \geq 0$$

or

$$\Delta\tau \leq \frac{1}{C_3 + C_4} \quad (\text{A19})$$

To establish the stability requirement at  $\xi=1$ , equation (A12) is rewritten as

$$\begin{aligned}\theta'_1 &= \frac{2\Delta\tau}{\Delta\xi_1^2} \left\{ \theta_2 + \Delta\xi_1 \left[ Q(\tau) (1 + \delta \sin \Omega\tau) + DH \right] \right\} \\ &\quad + \theta_1 + \frac{2\Delta\tau}{\Delta\xi_1} \left[ -\theta_1 - \Delta\xi_1 D (1 + E\theta_1)^4 \right]\end{aligned}\tag{A20}$$

or

$$\begin{aligned}\theta'_1 &= \frac{2\Delta\tau}{\Delta\xi_1^2} \left\{ \theta_2 + \Delta\xi_1 \left[ Q(\tau) (1 + \delta \sin \Omega\tau) + D(H-1) \right] \right\} \\ &\quad + \left\{ 1 - \frac{2\Delta\tau}{\Delta\xi_1^2} \left[ 1 + \Delta\xi_1 D (4E + 6E^2\theta_1 + 4E^3\theta_1^2 + E^4\theta_1^3) \right] \right\} \theta_1\end{aligned}\tag{A21}$$

stability is insured if

$$1 - \frac{2\Delta\tau}{\Delta\xi_1^2} \left[ 1 + \Delta\xi_1 D (4E + 6E^2\theta_1 + 4E^3\theta_1^2 + E^4\theta_1^3) \right] \leq 0$$

or

$$\Delta\tau \leq \frac{\frac{\Delta\xi_1^2}{2}}{\left[ 1 + \Delta\xi_1 D (4E + 6E^2\theta_1 + 4E^3\theta_1^2 + E^4\theta_1^3) \right]} \tag{A22}$$

## APPENDIX B

**COMPUTER PROGRAM FOR THE NUMERICAL  
SOLUTION OF CASE (i) - CONSTANT  
FREE STREAM CONDITIONS.**

Definitions of Input Quantities

<u>FORTRAN NAME</u>	<u>SYMBOL OR MEANING</u>
NAME (I)	Title of run under consideration. Two cards to be used.
BETA	$\beta$
SIGMA	$\sigma$
U	$u$
DELTA	$\delta$
D	D
E	E
H	H
OMEGA	$\Omega$
N1	N1 (Number of strips in material 1)
N2	N2 (Number of strips in material 2)
STAU	Starting time of solution
DTAU	$\Delta t$
PTAUL	Print out interval in range 1
PTAU2	Print out interval in range 2
CHANGE	Value of $\zeta$ at end of range 1
FTAU	Final dimensionless time
Q	$Q(\zeta) = 1.0$
T(I)	Initial temperature distribution at all nodes, dimensionless

```
$IBJOB KRAMER DECK,MAP  
$IBFTC ROBERT DECK,FULIST
```

```
DIMENSION NAME(32)  
DIMENSION T(1000), TP(1000)  
C  
1 READ(5,97) (NAME(I), I=1,32)  
97 FORMAT(16A5)  
WRITE(6,99) (NAME(I), I=1,32)  
99 FORMAT(1H1,24A5/1X,24A5)  
READ(5,2) BETA,SIGMA,U,DELTA,D,E,H,OMEGA  
2 FORMAT(8E10.0)  
WRITE(6,5) BETA,SIGMA,U,DELTA,D,E,H,OMEGA  
5 FORMAT(///1H , 39X, 8H BETA=E14.7, /  
1 40X, 8H SIGMA=E14.7, /  
2 40X, 8H U=E14.7, /  
3 40X, 8H DELTA=E14.7, /  
4 40X, 8H D=E14.7, /  
5 40X, 8H E=E14.7, /  
6 40X, 8H H=E14.7, /  
7 40X, 8H OMEGA=E14.7 )  
C  
READ(5,10) N1,N2,STAU,DTAU,PTAU1,PTAU2,CHANGE,FTAU,Q  
10 FORMAT(2I5,7E10.0)  
WRITE(6,11) N1,N2,STAU,DTAU,PTAU1,PTAU2,CHANGE,FTAU,Q  
11 FORMAT( 40X, 8H N1=I2 , /  
1 40X, 8H N2=I2 , /  
2 40X, 8H STAU=E14.7, /  
3 40X, 8H DTAU=E14.7, /  
4 40X, 8H PTAU1=E14.7, /  
5 40X, 8H PTAU2=E14.7, /  
6 40X, 8H CHANGE=E14.7, /  
7 40X, 8H FTAU=E14.7, /  
8 40X, 8H Q=E14.7 )  
WRITE(6,99) (NAME(I), I=1,32)  
C  
C....M=TOTAL NO. OF POINTS  
M=N1+N2+1  
C  
IF(STAU.EQ.0.) GO TO 30  
C....READ INITIAL TEMPERATURE DISTRIBUTION  
READ(5,25)(T(I), I=1,M)  
25 FORMAT(8E10.0)  
GO TO 40  
C  
C....INITIALIZE ALL TEMPERATURES TO ZERO  
30 DO 31 I=1,M  
31 T(I)=0.  
C
```

```

C....CALCULATE ALL NECESSARY CONSTANTS
40    FN=N1
      DX1=1./FN
      FN=N2
      DX2=BETA/FN
      C1=1./(DX1**2)
      C12=2.*C1
      BOS=BETA/SIGMA
      C2=(BOS/DX2)**2
      DEN=BOS+(U*DX2)/DX1
      C3=(2.*BOS*C1)/DEN
      C4=(2.*U*BOS**2)/(DEN*DX1*DX2)
      N=N1+1
      NP1=N+1
      MM1=M-1
      MP1=M+1
      PRTIME=STAU-DTAU/10.
      TAU=STAU

C
C....CHECK FOR STABILITY
C....MATERIAL 1
      DTAUP=1./C12
50    IF(DTAU.LE.DTAUP) GO TO 60
      DTAU=DTAU/2.
      GO TO 50
C....MATERIAL 2
60    DTAUP=1./(2.*C2)
65    IF(DTAU.LE.DTAUP) GO TO 70
      DTAU=DTAU/2.
      GO TO 65
C....INTERFACE
70    DTAUP=1./(C3+C4)
75    IF(DTAU.LE.DTAUP) GO TO 80
      DTAU=DTAU/2.
      GO TO 75
C * * * * *
C....BOUNDARY
80    DTAUP=1./(C12*(1.+DX1*D*E*(4.+E*T(1)*(6.+E*T(1)*(4.+E*T(1))))))
85    IF(DTAU.LE.DTAUP) GO TO 90
      DTAU=DTAU/2.
      GO TO 85
C....ADIABATIC BOUNDARY CONDITION
90    T(MP1)=T(MM1)

C
      IF(TAU.LT.PRTIME) GO TO 120
      IF (PRTIME.GT.CHANGE) GO TO 91
      PRTIME=PRTIME+PTAU1
      GO TO 92
91    PRTIME=PRTIME + PTAU2
C....PRINT TEMPERATURE DISTRIBUTION
92    IF (PRINT.LE.4.) GO TO 94
      PRINT = 0.0
      WRITE (6,99) (NAME(I),I=1,32)
94    WRITE(6,100) TAU,DTAU
100   FORMAT(// 36X, 4HTAU=E12.5, 5X,5HDTAU=E12.5)
      WRITE(6,101) (I,T(I),I=1,M)
101   FORMAT( 514X, 2HT(., 12.2H)=, E12.5)
      PRINT =PRINT+1.0

```

```

C
120  IF(TAU.GE.FTAU) GO TO 1
C
      W1=Q*(1.+DELTA*SIN(OMEGA*TAU))
      W2=D*((1.+E*T(1))**4 -H)
C
C....CALCULATE TEMPERATURES AT TAU+DTAU
C....BOUNDARY
      TP(1)=T(1)+C12*DTAU*(T(2)-T(1)+DX1*(W1-W2))
C....MATERIAL 1
      DO 130 I=2,N1
130  TP(I)=T(I)+C1*DTAU*(T(I-1)-2.*T(I)+T(I+1))
C....INTERFACE
      TP(N)=T(N)+DTAU*(C3*(T(N1)-T(N))+C4*(T(NP1)-T(N)))
C....MATERIAL 2
      DO 140 I=NP1,M
140  TP(I)=T(I)+C2*DTAU*(T(I-1)-2.*T(I)+T(I+1))
C
C....INCREMENT TAU
      TAU=TAU+DTAU
C....RESET
      DO 150 I=1,M
150  T(I)=TP(I)
      GO TO 80
C * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * *
      END

$ENTRY

```

## APPENDIX C

COMPUTER PROGRAM FOR THE NUMERICAL  
SOLUTION OF CASE (ii) - VARIABLE FREE  
STREAM CONDITIONS: ENTRY CASE

Definitions of Input Quantities

<u>FORTRAN NAME</u>	<u>SYMBOL</u>
NAME (I)	Title of run under consideration. Two cards are to be used.
BETA	$\beta$
SIGMA	$\sigma$
U	$\mu$
DELTA	$\delta$
D	D
E	E
H	H
OMEGA	$\Omega$
N1	N1 (Number of strips in material 1)
N2	N2 (Number of strips in material 2)
STAU	Starting dimensionless time
DTAU	$\Delta\tau$
PTAU1	Print out dimensionless time interval in range 1
PTAU2	Print out dimensionless time interval in range 2
CHANGE	Vale of $\tau$ at end of range 1
FTAU	Final dimensionless time
DIFFUS	$\alpha_1$ ( $\text{ft}^2/\text{hr}$ )
AA	a (in.)
NOPTS	Number of points in the table of $q_o(t)$ vs. t for entry heating.
J	1 for new table of $q_o(t)$ vs. t 2 for table of $q_o(t)$ vs. t of previous case.

<u>FORTRAN NAME</u>	<u>SYMBOL</u>
TIME (I)	Set of time values $t$ , in seconds, at which values of $q_o(t)$ are tabulated
QQ(I)	Set of entry heat flux, $q_o(t)$ , in $\text{Btu}/\text{ft}^2 - \text{sec}$
T(I)	Initial temperature distribution at all nodes, dimensionless

## ISN SOURCE STATEMENT

```

0 $IBFTC ROBERT DECK
1 DIMENSION NAME(32)
2 DIMENSION T(100), TP(100)
3 DIMENSION TIME(50), QG(50), TTAU(50), QT(50), ZTAU(50)

C
4   1 READ(5,97) (NAME(I), I=1,32)
11  97 FORMAT(16A5)
12    WRITE(6,99) (NAME(I), I=1,32)
17  99 FORMAT(1H1,24A5/1X,24A5)
20    READ(5,2) BETA, SIGMA, U, DELTA, D, E, H, OMEGA
21  2 FORMAT(8E10.0)
22    WRITE(6,5) BETA, SIGMA, U, DELTA, D, E, H, OMEGA
23  5 FORMAT(//1H , 39X, 8H BETA=E14.7, /
1           40X, 8H SIGMA=E14.7, /
2           40X, 8H U=E14.7, /
3           40X, 8H DELTA=E14.7, /
4           40X, 8H D=E14.7, /
5           40X, 8H E=E14.7, /
6           40X, 8H H=E14.7, /
7           40X, 8H OMEGA=E14.7 )

C
24    READ(5,10) N1, N2, STAU, DTAU, PTAU1, PTAU2, CHANGE, FTAU
27  10 FORMAT(2I5, 6E10.0)
30    WRITE(6,11) N1, N2, STAU, DTAU, PTAU1, PTAU2, CHANGE, FTAU
31  11 FORMAT( 40X, 8H N1=I2 , /
1           40X, 8H N2=I2 , /
2           40X, 8H STAU=E14.7, /
3           40X, 8H DTAU=E14.7, /
4           40X, 8H PTAU1=E14.7, /
5           40X, 8H PTAU2=E14.7, /
6           40X, 8H CHANGE=E14.7, /
7           40X, 8H FTAU=E14.7 )

C
32    READ(5,7) DIFFUS, AA, NCPTS, J
35  7 FORMAT(2F10.6, 2I10)
C   DIFFUS= THERMAL DIFFUSIVITY IN FEET SQUARE PER HOUR
C   AA= THICKNESS OF REFRACTORY MATERIAL IN INCHES
C   NOPTS IS THE NUMBER OF DATA POINTS USED FOR TIME(I) OR QG(I)
36    WRITE(6,33) DIFFUS, AA, NCPTS
37  33 FORMAT( 40X, 8H DIFFUS=E14.7, /
1           40X, 8H AA=E14.7, /
2           40X, 8H NCPTS=I3 )

C
40    WRITE(6,34)
41  34 FORMAT(// 25X, 10H D = ,
162HEPSILON * STEFAN * T(I)**4 / (C0(0) * R)
2           25X, 10H E = ,
362HQ(C) * R * AA / (K1 * T(I))
4           25X, 10H H = ,
562H(TE/T(I))**4
6           25X, 10H PTAU1 = ,
762HPRINT INTERVAL UP TO VALUE OF CHANGE
8           25X, 10H PTAU2 = ,
962HPRINT INTERVAL AFTER VALUE OF CHANGE
42    WRITE(6,36)

```

```

43   36 FORMAT (      25X, 1CH DIFFUS = ,
162HTHERMAL DIFFUSIVITY IN FOOT SQUARE PER HOUR
2      25X, 1CH AA = ,
362HTHICKNESS OF REFRactory MATERIAL IN INCHES
4      25X, 1CH NOPTS = ,
562HNNUMBER OF POINTS USED FOR INPUT DATA CF TIME VS CCCOT
C
44   WRITE (6,99) (NAME(I),I=1,32)
C
51   IF (J.EQ.2) GO TO 111
C....IF J=2 USE THE SAME TABLE OF Q VS TAU
C....READ IN TABLE OF Q VS. TAU
54   READ(5,3)(TIME(I),I=1,NOPTS)
61   READ(5,3)           (QQ(I),I=1,NCPTS)
66   3 FORMAT(5E16.8)
C     TIME(I) IS THE SET OF SELECTED VALUES CALLED TIME WHICH ARE USED
C     AS DATA FOR THIS PROGRAM
C     QQ(I) IS THE SET OF SELECTED VALUES CALLED CCCOT WHICH ARE USED
C     AS DATA FOR THIS PROGRAM
C     TIME(1)=0.0
C     QQ(1) =Q(0)
67 111  CAPPA=DIFFUS*144.0/(3600.0*AA-AA)
C     CAPPA=(SQ.FT./HR)(SQ.IN./SQ.FT.)/(SEC/HR)-(SC.IN))=1/SECONDS
C....WRITE OUT TABLE OF Q VS. TAU
70   WRITE(6,9)
71   9 FORMAT(// 36X, 35HTABLE OF TAU VS Q AND TIME VS CCCOT//31X,1FN,
1 7X, 6HTAU(N), 9X, 4HQ(N), 9X, 7HTIME(N), 6X, 8HCCCOT(N)//)
72   DO 6 II=1,NOPTS
73   TTAU(II)=TIME(II)*CAPPA
74   QT(II)=QQ(II)/QQ(1)
75   6 WRITE(6,4)II,TTAU(II),QT(II),TIME(II),QQ(II)
77   4 FORMAT( 29X, I3, 4( 3X, F11.6 ))
C
100  WRITE (6,99) (NAME(I),I=1,32)
C
C....M=TOTAL NO. OF POINTS
105  M=N1+N2+1
C
106  IF(STAL.EQ.0.) GO TO 30
C....READ INITIAL TEMPERATURE DISTRIBUTION
111  READ(5,25)(T(I),I=1,M)
116  25 FORMAT(EE10.0)
117  GO TO 40
C
C....INITIALIZE ALL TEMPERATURES TO ZERO
120  30  DO 31 I=1,M
121  31  T(I)=0.
C
C....CALCULATE ALL NECESSARY CONSTANTS
123  40  FN=N1
124  DX1=1./FN
125  FN=N2
126  CX2=BETA/FN
127  C1=1./(DX1**2)
130  C12=2.*C1

```

```

131      BOS=BETA/SIGMA
132      C2=(BOS/DX2)**2
133      DEN=BOS+(U*DX2)/DX1
134      C3=(2.*BOS*C1)/DEN
135      C4=(2.*U*BOS**2)/(DEN*DX1*DX2)
136      N=N1+1
137      NP1=N+1
140      MM1=M-1
141      MP1=M+1
142      PRTIME=STAU-DTAU/10.
143      TAU=STAU
144      KCOUNT=C
C
C....CHECK FOR STABILITY
C....MATERIAL 1
145      DTAUP=1./C12
146  50  IF(DTAU.LE.DTAUP) GO TO 60
151      DTAU=DTAU/2.
152      GO TO 50
C....MATERIAL 2
153  60  DTAUP=1./(2.*C2)
154  65  IF(DTAU.LE.DTAUP) GO TO 70
157      DTAU=DTAU/2.
160      GO TO 65
C....INTERFACE
161  70  DTAUP=1./(C3+C4)
162  75  IF(DTAU.LE.DTAUP) GO TO 80
165      DTAU=DTAU/2.
166      GO TO 75
C * * * * *
C....BOUNDARY
167  80  DTAUP=1./(C12*(1.+DX1*D+E*(4.+E*T(1)*(6.+E*T(1)*(4.+E*T(1))))))
170  85  IF(DTAU.LE.DTAUP) GO TO 90
173      DTAU=DTAU/2.
174      GO TO 85
C
C....ADIABATIC BOUNDARY CONDITION
175  90  T(MP1)=T(MM1)
C
176      IF(TAU.LT.PRTIME) GO TO 120
201      IF (PRTIME.GE.CHANGE-0.01) GO TO 91
204      PRTIME=PRTIME+PTAU1
205      GO TO 92
206  91  PRTIME=PRTIME + PTAU2
C
C....PRINT TEMPERATURE DISTRIBUTION
207  92  IF (PRINT.LE.4.) GO TO 94
212      PRINT = 0.0
213      WRITE (6,99) (NAME(I),I=1,32)
220  94  WRITE(6,100) TAU,DTAU
221  100  FORMAT(// 36X, 4H TAU=E12.5, 5X, 5H DTAU=E12.5)
222      WRITE(6,101) (I,T(I),I=1,M)
227  101  FORMAT( 5(4X, 2HT(, I2,2H)=, E12.5) )
230      PRINT =PRINT+1.0
C

```

```

231 120 IF(TAU.GE.FTAU) GO TO 1
C
C....LCOK-UP Q
234 DO 8 K=1,NOPTS
235 IF(TAU-TTAU(K))12,13,8
236 8 CONTINUE
240 KCOUNT=KCOUNT+1
241 Q4TAU=QT(NOPTS)+(TAU-TTAU(NOPTS))*(QT(NCPTS)-QT(NCPTS-1))/(TTAU(NO
1PTS)-TTAU(NOPTS-1))
242 IF (KCOUNT.GT.1) GO TO 15
245 WRITE(6,16)
246 16 FORMAT(1X, 27HIN ALL FURTHER CALCULATIONS,
162HTHE LARGEST VALUE OF TAU IN THE TABLE IS SMALLER THAN TAU REQU,
240HIRED. THEREFORE / IX, 10HTHE VALUE ,
362HOF Q USED IS THE RESULT OF A LINEAR EXTRAPCLATION BASEC CN THE,
44CH LAST TWO TABULATED VALUES. )
247 GO TO 15
250 12 IF(K.GT.1) GO TO 14
253 WRITE (6,18)
254 18 FORMAT(//5X,54HRESUBMIT THE DATA WITH THE FIRST ENTRY FOR TIME = 0
1.C.)
255 GO TO 1
256 14 Q4TAU=QT(K-1)+(QT(K)-QT(K-1))*(TAU-TTAU(K-1))/(TTAU(K)-TTAU(K-1))
257 GO TO 15
260 13 Q4TAU=QT(K)
261 15 Q=Q4TAU
C
262 W1=Q*(1.+DELTA*SIN(OMEGA*TAU))
263 W2=D*((1.+E*T(1))*#4 -H)
C
C....CALCULATE TEMPERATURES AT TAU+DTAU
C....BOUNDARY
264 TP(1)=T(1)+C12*DTAU*(T(2)-T(1)+DX1*(W1-W2))
C....MATERIAL 1
265 DO 130 I=2,N1
266 130 TP(I)=T(I)+C1*DTAU*(T(I-1)-2.*T(I)+T(I+1))
C....INTERFACE
270 TP(N)=T(N)+DTAU*(C3*(T(N1)-T(N))+C4*(T(NP1)-T(N)))
C....MATERIAL 2
271 DO 140 I=NP1,M
272 140 TP(I)=T(I)+C2*DTAU*(T(I-1)-2.*T(I)+T(I+1))
C
C....INCREMENT TAU
274 TAU=TAU+DTAU
C....RESET
275 DO 15C I=1,M
276 150 T(I)=TP(I)
300 GO TO 80
C * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * *
301 END

```

## APPENDIX D

### COMPUTER PROGRAM FOR THE EIGEN-VALUES

#### Definitions of Input Quantities

<u>FORTRAN NAME</u>	<u>SYMBOL OR MEANING</u>
U	$\mu$
S	$\sigma$
N	A number greater than or equal to the value of the last Lambda divided by DL
DL	Width of interval checked for change in sign (root)
STOP	Number of $\lambda$ 's desired (value of n)

ISN	SOURCE STATEMENT
0	\$IBFTC VALUES DECK
1	DIMENSION F(3000),ZLAM(3000)
2	COMMON A,B,C,D
3	EXTERNAL FUN
4 1	WRITE(6,2)
5 2	FORMAT(1H1,40X,26HCOMPOSITE SLAB EIGENVALUES////)
6	READ(5,3) U,S,N,DL,STOP
10 3	FORMAT (2E 10.0,I10,2E10.0)
11	WRITE (6,4) S,U,DL
12 4	FORMAT (3X,6HSIGMA=F12.8,6X,3HMU=F12.8,6X,13HDELTA LAMBDA=F12.8///
	1//)
13	WRITE (6,51)
14 51	FORMAT (6X,1HN,8X,9HLAMBDA(N)///
C	
C	....DEFINITONS FOR SYMBOLS
C	
C	U = GREEK LETTER MU
C	S = GREEK LETTER SIGMA
C	DL = WIDTH OF INTERVAL CHECKED FOR CHANGE IN SIGN (ROOT) OF F
C	STOP = NUMBER OF LAMBDA'S DESIRED
C	N = A NUMBER GREATER THAN OR EQUAL TO THE VALUE OF THE LAST
C	LAMBDA DIVIDED BY DL
C	
15	A=1.+U
16	B=1.+S
17	C=1.-U
20	D=1.-S
21	E1=1.0E-6
22	E2=1.0E-6
23	DO 5 I=1,N
24	ZLAM(I)=DL*FLOAT(I)
25	G=A*SIN(B*ZLAM(I))
26	H=C*SIN(D*ZLAM(I))
27 5	F(I)=G+H
31	NCOUNT=0
32 7	DO 11 L=2,N
33	IF ((F(L-1)/F(L)).GT.0.) GO TO 11
36	BL=ZLAM(L-1)
37	BU=ZLAM(L)
40 9	GUESS=0.5*(ZLAM(L-1)+ZLAM(L))
41	CALL ROOT (FUN,T,GUESS,BL,BU,E1,E2,I)
42	IF (I.NE.1) GO TO 13
45	NCOUNT=NCOUNT+1
46	WRITE (6,10) NCOUNT,T
47 10	FORMAT (4X,I3,5X,F13.8)
50	KSTOP=STOP
51	IF(NCOUNT.GT.KSTOP) GO TO 1
54	GO TO 11
55 13	WRITE (6,14)
56 14	FORMAT (6X,34HROOT HAS NOT GIVEN A NORMAL RETURN)
57 11	CCNTINUE
61	WRITE (6,12)
62 12	FORMAT(1H1)
63	GC TO 1
64	END

ISN        SOURCE STATEMENT

```
0 $IBFTC FUNCTN
1   FUNCTION FUN(T)
2   COMMON A,B,C,D
3   FUN=A*SIN(B*T)+C*SIN(D*T)
4   RETURN
5   END
```

## ISN SOURCE STATEMENT

```
0 $IBFTC RCOTSL
1      SUBROUTINE RCOT (FUN,R,A,BL,BU,EP,E2,I)
C
C      SUBROUTINE ROOT IS USED TO APPROXIMATE AND HOME IN ON THE DESIRED
C      RCOT
C
C      ARGUMENT LIST--
C          FUN=FUNCTION SUBPROGRAM NAME
C          R =ARGUMENT OF SUBPROGRAM AND VALUE OF ROOT
C          A =INITIAL GUESS AT ROOT
C          BL =LOWER BOUND ON ROOT
C          BU =UPPER BOUND ON ROOT
C          EP =EPSILON TEST FOR FUNCTION - IF FUN(R)(ABSOLUTE
C              VALUE) IS LESS THAN OR EQUAL TO EP, I=1 AND
C              RETURN
C          E2 =EPSILON TEST ON RCOT APPROXIMATION. IF RATIO OF DIFF-
C             ERENCE OF SUCCESSIVE APPROXIMATIONS TO CURRENT
C              APPROXIMATION IS LESS THAN E2 IN ABSOLUTE VALUE,
C              I=1 AND RETURN.
C          I =ERROR CODE =1 FOR NORMAL RETURN
C
C
2      DIMENSION X(3),FX(3)
3      G=A
4      ISP=0
C      TEST FOR LOWER BOUND ON ROOT LESS THAN UPPER BOUND
5      IF (BL-BU) 1,2,2
C      IF NOT , ERROR CODE I=3. RETURN.
6      2
7      I=3
7      RETURN
C      TEST FOR GUESS OUTSIDE BOUNDS.
10     1
11     8
12     9
13     IF (G-BL) 9,7,8
14     7
15     6
16     1
17     80
18     1
19     2
20     3
21     4
22     10
23     13
24     14
25     17
26     15
27     18
28     16
29     20
30     19
31     21
32     19
33     22
34     20
35     21
      IF (G-BU)6,7,9
C      IF YES, ERROR CODE I=1 AND RETURN
      I=2
      RETURN
C      IF GUESS=LOWER BOUND, COMPUTE GUESS=0.5*(BU+BL)
      G=(BL+BU)/2.0
      GL=BL+0.1*(G-BL)
      GU=BU- 0.1*(BU-G)
      R=G
      FG=FUN(G)
      IF (ABS(FG)-EP) 13,13,32
      IF (ABS (FX(11))-EP) 13,13,17
      I=1
      RETURN
      I1=I1
      IF (FX(I1)) 18,18,19
      IF(FX(I2)) 20,20,21
      IM=1
      GC TO 23
      IF (FX(I2)) 24,24,22
      IM=0
      GC TO 23
      IP=I2
```

```

36      IM=I1
37      GC TO 25
40 24    IP=I1
41      IM=I2
42      GO TO 25
43 23    DO 26 IC1=1,20
        C   ROOT HAS NOT BEEN BRACKETED. USE SUCCESSIVE APPROXIMATIONS.
44      T=FX(I2)-FX(I1)
45      IF (ABS(T)-0.01*EP) 27,27,28
46 27    IF (X(I1)-X(I2)) 14,12,14
47 12    I=4
50      RETURN
51 14    X(IF)=0.5*(X(I1)+X(I2))
52      R=X(IF)
53      GC TO 33
54 28    X(IF)=X(I2)-(X(I2)-X(I1))/T*FX(I2)
55      R=X(IF)
56      IF (X(IF)) 63,64,63
57 63    IF (ABS((X(IF)-X(I2))/X(IF))-E2) 34,34,65
58 64    IF (ABS(X(IF)-X(I2))-E2) 34,34,65
59 34    FX(IF)=FUN(X(IF))
60      GC TO 13
61 65    IF (IB-1) 29,29,33
62 29    IF (BL-X(IF)) 31,31,32
63 31    IF (X(IF)-BU) 33,33,32
64 33    FX(IF)=FUN (X(IF))
65      IF (ABS(FX(IF))-EP) 13,13,35
66 35    IF (FX(IF)) 36,13,37
67 36    IF (IM) 38,38,39
68 38    IP=I2
69      IM=IF
70      IF=I1
71      GC TO 25
72 37    IF (IM) 39,39,40
73 40    IP=IF
74      IM=I2
75      IF =I1
76      GC TO 25
77 39    I1=I1+1
78 41    I2=I2+1
79 42    IF=IF+1
80      GC TO (42,42,43,44),IF
81 42    I2=1
82      GC TO 26
83 43    I1=1
84 44    GC TO 26
85 44    IF=1
86 26    CONTINUE
87 32    ISP=ISP+1
88 41    I1=1
89 42    I2=2
90 43    IF=3
91 44    X(I2)=G
92 45    FX(I2)=FG
93 46    GC TO (47,48,49,50,51,69,70),ISP

```

```

125 47      X(I1)=GL
126      R=GL
127      FGL=FUN(R)
130      FX(I1)=FGL
131      GO TO 10
132 48      X(I1)=GU
133      R=GU
134      FGU=FUN(R)
135      FX(I1)=FGU
136      GO TO 10
137 49      X(I2)=GL
140      FX(I2)=FGL
141      G2=0.5*(G+BL)
142 71      X(I1)=G2
143      R=G2
144      FG2=FUN(R)
145      FX(I1)=FG2
146      GO TO 10
147 50      X(I1)=G2
150      FX(I1)=FG2
151      GO TO 17
152 51      G2=0.5*(G+BU)
153      GO TO 71
154 69      X(I1)=GU
155      FX(I1)=FGU
156      X(I2)=G2
157      FX(I2)=FG2
160      GO TO 17
161 70      I=5
162      RETURN
163 25      DC 52 IC=1,50
C      RCOT HAS BEEN BRACKETED. USE APPROXIMATIONS ON EACH SIDE.
164      X(IF)=X(IP)-(X(IP)-X(IM))/(FX(IP)-FX(IM))*FX(IP)
165      R=X(IF)
166      IF (X(IF)) 61,62,61
167 61      IF (ABS((X(IF)-X(IP))/X(IF))-E2) 34,34,67
170 67      IF (ABS((X(IF)-X(IM))/X(IF))-E2) 34,34,53
171 62      IF (ABS(X(IF)-X(IP)) -E2) 34,34,68
172 68      IF (ABS(X(IF)-X(IM)) -E2) 34,34,53
173 53      IF (IB-1) 54,54,55
174 54      IF (X(IF)-BL) 32,56,56
175 56      IF (X(IF)-BU) 55,55,32
176 55      FX(IF)=FUN(X(IF))
177      IF (ABS(FX(IF))-EP) 13,13,57
200 57      IF (FX(IF)) 58,13,59
201 58      IT=IM
202      IM=IF
203      GO TO 60
204 59      IT=IP
205      IP=IF
206 60      IF=IT
207 52      CCNTINUE
211      GO TO 32
212      END

```

## APPENDIX E

### COMPUTER PROGRAM FOR THE ANALYTICAL SOLUTION OF CASE (i) - CONSTANT FREE STREAM CONDITIONS

#### Definitions of Input Quantities

<u>FORTRAN NAME</u>	<u>SYMBOL OR MEANING</u>
TI	Initial time
TF	Final time
DT	$\Delta t$
OM	$\Omega$
MU	$\mu$
S	$\sigma$
XI	$\xi$
D	$\zeta$
IC	1 for new set of $\lambda_n$ 2 use set of $\lambda_n$ from previous case
N	n, number of $\lambda$ 's
LAM(I)	$\lambda_n$

ISN	SOURCE STATEMENT
0	\$IBFTC SLAB2T DECK
1	REAL MU,LAM,LAM2
2	DIMENSION LAM(100),LAM2(100),E(100),H1(100),H2(100),H3(100)
3 15	READ (5,2) TI,TF,DT,OM,MU,S,XI,D
4 2	FORMAT (8E10.0)
5	READ (5,3) IC,N
10 3	FORMAT (2I5)
11	IF (IC.EQ.2) GO TO 19
14	READ (5,4) (LAM(I),I=1,N)
21 4	FORMAT (5E16.8)
22 19	WRITE (6,1)
23 1	FORMAT (1H1,20X,78HNO RADIATION COMPOSITE SLAB TEMPERATURE----FOR 1CONSTANT FREE STREAM CONDITIONS///)
24 16	WRITE (6,5)
25 5	FORMAT (45X,37HINPUT PARAMETERS FOR THIS CASE ARE )
26	WRITE (6,6) TI,TF,DT,S,D,OM,XI,MU,N
27 6	FORMAT (/// 45X, 15H TAU INITIAL = F12.8,/
1	45X, 15H TAU FINAL = F12.8,/
2	45X, 15H DELTA TAU = F12.8,/
3	45X, 15H SIGMA = F12.8,/
4	45X, 15H DELTA = F12.8,/
5	45X, 15H OMEGA = F12.8,/
6	45X, 15H XI = F12.8,/
7	45X, 15H MU = F12.8,/
8	45X, 15H N = I3 ,/)
30	WRITE(6,7)
31 7	FORMAT (1H0,40X,52HTHE VALUES OF LAMBDA ARE, READING ACROSS FROM 1 1 TO N///)
32	WRITE (6,8) (LAM(I),I=1,N)
37 8	FORMAT ( 5 (1X,F20.8))
40	WRITE (6,12)
41 12	FORMAT(1H0,14X,3HTAU,30X,13HTHETA/(ARQ/K),25X,20HABS(SUM N/SUM (N- 11)))
C	C....DEFINITONS FOR SYMBOLS
C	TF = TAU FINAL
C	TI = TAU INITIAL
C	DT = DELTA TAU
C	OM = GREEK LETTER CAPITAL OMEGA
C	S = GREEK LETTER SIGMA
C	MU = GREEK LETTER MU
C	XI = GREEK LETTER XI
C	D = GREEK LETTER DELTA
C	IC = CYCLE CHECK--READ IN 1 FOR NEW SET OF LAMBdas---
C	READ IN 2 TO USE SET OF LAMBdas FROM PREVIOUS CASE
C	N = NUMBER OF LAMBdas READ IN
C	
42	A=1.+MU
43	B=1.+S
44	C=1.-MU
45	P=1.-S
46	F=1.+MU*S
47	G=S+XI
50	H=S-XI

```

51      IF (IC.EQ.2) GO TO 17
54      DO 18 I=1,N
55 18    LAM2(I)=LAM(I)*LAM(I)
57 17    DO 9 I=1,N
60      E1=A*B*COS(B*LAM(I))
61      E2=C*P*COS(P*LAM(I))
62      E(I)=E1+E2
63      H2(I)=(LAM2(I)/OM)**2+1.
64      H3(I)=1./LAM2(I)-(D/OM)/H2(I)
65 9     H1(I)=(A*COS(LAM(I)*H)+C*COS(LAM(I)*G))/E(I)
67      TAU=TI
70 10    G1=TAU+(D/OM)*(1.-COS(OM*TAU))
71      G2=3.*XI*XI+2.*S*S-6.*MU*S*XI-1.-2.*S*(S+MU)/F
72      G3=G2*(1.+D*SIN(OM*TAU))/6.
73      G4=(G1+G3)/F
74      SUM=0.0
75      DO 11 K=1,N
76      IF (LAM2(K)*TAU.GE.86.) GO TO 20
101     H4=H3(K)*EXP(-LAM2(K)*TAU)
102     GO TO 21
103 20    H4=0.0
104 21    H5=(COS(OM*TAU)/OM+SIN(OM*TAU)/LAM2(K))*D/H2(K)
105     SUM=SUM+H1(K)*(H4+H5)
106     IF ((N-K).EQ.1) ZI=SUM
111 11    CONTINUE
113     THETA=G4-2.*SUM
114     Z2=ABS(SUM/ZI)
115     WRITE (6,13) TAU,THETA,Z2
116 13    FORMAT (1H ,6X,F15.8,8X,F20.8, 20X,F20.8)
117     TAU=TAU+DT
120     IF (TAU.LE.TF) GO TO 10
123 14    GO TO 15
124     END

```

## APPENDIX F

COMPUTER PROGRAM FOR THE ANALYTICAL  
SOLUTION OF CASE (ii) - VARIABLE FREE  
STREAM CONDITIONS: ENTRY CASE

Definitions of Input Quantities

<u>FORTRAN NAME</u>	<u>SYMBOL OR MEANING</u>							
TITLE (I)	Title of run under consideration. Two cards are to be used.							
U	$\mu$							
S	$\sigma$							
D	$\delta$							
OM	$\Omega$							
XI	$\xi$							
LC	$\Lambda$							
GC	$\Gamma$							
GL	$\Upsilon$							
R1	Limit of $\tau$ in print out of range 1							
R2	"	"	"	"	"	"	"	2
R3	"	"	"	"	"	"	"	3
R4	"	"	"	"	"	"	"	4
DT1	$\Delta\tau$ in print out of range 1							
DT2	"	"	"	"	"	"	"	2
DT3	"	"	"	"	"	"	"	3
DT4	"	"	"	"	"	"	"	4
TIMEA	$t_a$ , in seconds							
TIMEB	$t_b$ ,	"	"					
TIMEC	$t_c$ ,	"	"					
TIMED	$t_d$ ,	"	"					
TIMEM	$t_m$ ,	"	"					

<u>FORTRAN NAME</u>	<u>SYMBOL OR MEANING</u>
TIMEI	Initial $\tau$
TIMEF	Final $\tau$
TEMPI	Initial temperature
ASMALL	a, ft.
ABAR	$\bar{A}$ , $1/\text{sec}^2$
R	R
ALPHA	$\alpha_1$ , $\text{ft}^2/\text{sec}$
PHI	$\Psi$ , $1/\text{sec}$
CAPPA	$K_1$ Btu/ $\text{ft}\cdot\text{sec}\cdot{}^\circ\text{F}$
QO	$q_O$ ( $\circ$ ) Btu/ $\text{ft}^2\cdot\text{sec}$
B	$B = \bar{B}$
N	n, number of $\lambda$ 's
J	1 for new set of $\lambda$ 's 2 use set of $\lambda$ 's from previous case
L(I)	$\lambda_n$

## ISN SOURCE STATEMENT

```

0 $IBFTC ROBERT DECK
1      REAL L,LL,LC,LCM1,LLDM,LLOM2
2      DIMENSION L(100),LL(100),LLDM(100),LLOM2(100),E(100),G(100)
3      DIMENSION EMBMA(100),EMTB(100),EPPTA(100),GP(100),TITLE(32)
4      DIMENSION EMTTC(100),EMCMB(100),EMTTA(100),EMTA(100)
5 1    READ (5,2) (TITLE(I),I=1,32)
12 2   FORMAT(16A5)
13     READ (5,3) U,S,D,OM,XI,LC,GL
14     READ (5,3) R1,R2,R3,R4,DT1,DT2,DT3,DT4
15     READ (5,3) TIMEA,TIMEB,TIMEC,TIMED,TIMEH,TIMEI,TIMEF,TEMPI
16     READ (5,3) ASMALL,ABAR,R,ALPHA,PHI,CAPPA,QO,B
17     READ (5,4) N,J
22 3   FORMAT (8 E 10.0)
23 4   FORMAT (2I5)
24 6   WRITE (6,7) (TITLE(I),I=1,32)
31     WRITE (6,8) U,TIMEA,R1,ASMALL,S,TIMEB,R2,ABAR,D,TIMEC,R3,ALPHA,OM,
1TIMED,R4,PHI,XI,TIMEH,DT1,CAPPA,LC,TIMEI,DT2,TEMPI,GL,TIMEF,DT3,B,
2GL,N,DT4,QO,J,R
32     WRITE (6,9)
33     WRITE (6,10)
34     WRITE (6,11)
35     WRITE (6,18)
36     WRITE (6,19)

C
C....FORMAT STATEMENTS
C
37 7   FORMAT(1H1,24X,16A5/25X,16A5)
40 8   FORMAT(/50X,20H* INPUT PARAMETERS */
A12X4H U =E14.8,9X7HTIMEA =E14.8,IIX5H RI =E14.8,8X8HASMALL =E14.87
B12X4H S =E14.8,9X7HTIMEB =E14.8,11X5H R2 =E14.8,8X8H ABAR =E14.8/
C12X4H D =E14.8,9X7HTIMEC =E14.8,IIX5H R3 =E14.8,8X8H ALPHA =E14.8/
D12X4HOM =E14.8,9X7HTIMED =E14.8,11X5H R4 =E14.8,8X8H PHI =E14.8/
E12X4HXI =E14.8,9X7HTIMEH =E14.8,IIX5HDT1 =E14.8,8X8H CAPPA =E14.87
F12X4HLC =E14.8,9X7HTIMEI =E14.8,11X5HDT2 =E14.8,8X8H TEMPI =E14.8/
G12X4HGC =E14.8,9X7HTIMEF =E14.8,IIX5HDT3 =E14.8,8X8H B =E14.87
H12X4HGL =E14.8,9X7H N =I4, 21X5HDT4 =E14.8/
I12X4HQO =E14.8,9X7H J =I3, 22X5H R =E14.8)
41 9   FORMAT(/52X,15H* DEFINITIONS */
11X15HGREEK FORTRAN,13X7HFORTRA
1N,40X7HFORTTRAN/10X13HLETTER NAME,I9X,I4HNAME MEANING,33X,I4HNA
2ME MEANING//)
42 10  FORMAT(
A6X18H ALPHA ALPHA,17X,32HTIMEA STAGE 1 UPPER LIMIT ,
B17X,35H RI LIMIT OF TAU IN PRINT RANGE 17 ,
C6X18H GAMMA GL ,17X,32HTIMEB STAGE 2 UPPER LIMIT ,
D17X,35H RZ LIMIT OF TAU IN PRINT RANGE 27 ,
E6X18H CAP GAMMA GC ,17X,32HTIMEC STAGE 3 UPPER LIMIT ,
F17X,35H R3 LIMIT OF TAU IN PRINT RANGE 37 ,
G6X18H DELTA D ,17X,32HTIMED STAGE 4 UPPER LIMIT ,
H17X,35H R4 LIMIT OF TAU IN PRINT RANGE 4)
43 11  FORMAT(
I6X18H KAPPA CAPPA,I7X,32HTIMEM TIME OF MAX HEAT LOAD ,
L17X,35HDT1 DELTA TAU IN PRINT RANGE 1 /
K6X18H LAMBDA LIT ,I7X,32HTIMET INITIAL TIME ,
L17X,35HDT2 DELTA TAU IN PRINT RANGE 2 /
M6X18HCAP LAMBDA LC ,I7X,32HTIMEF FINAL TIME ,

```

```

L17X,35HDT3    DELTA TAU IN PRINT RANGE 3   /
06X18H          MU U ,17X,32HTEMPI  INITIAL TEMPERATURE ,
L17X,35HDT4    DELTA TAU IN PRINT RANGE 4  )

44 18  FORMAT(
Q6X18H CAP OMEGA OM ,17X,32H TEMP  TEMPERATURE, DEG R ,
R17X,35H R SCALE FACTOR           /
A6X18H PHI PHI ,17X,34H N NUMBER OF LAMBdas READ IN ,
B12X,38HASMALL CHARACTERISTIC LENGTH      /
C6X18H CAP PHI P ,17X,34H J CONTROL-1-USE NEW LAMBdas ,
D12X,38H ABAR GROUPED TERMS-SEE REPORT   /
E6X18H SIGMA S ,17X,34H                2-USE LAST LAMBdas,
212X,38H B CONSTANT TERM-SEE REPORT     )

45 19  FORMAT(
G6X18H THETA THETA/
H6X18H XI XI //)

C
46  IF (J.EQ.1) GO TO 12
51  WRITE(6,13)
52 13 FORMAT(/30X49HTHE LAMBdas FROM THE PREVIOUS CASE ARE SPECIFIED.)
53  GO TO 15
54 12 READ(5,16) (L(I),I=1,N)
61 16 FORMAT(5E16.8)
62 15 WRITE(6,14) (I,L(I),I=1,N)
67 14 FORMAT(40X,29HTHE EIGENVALUES (LAMBdas) ARE//5(3X,2HL(,I2,2H)=,
1E14.8))

C
C....CALCULATION OF CONSTANTS FOR INTERNAL USE
70  P=ASMALL*ASMALL*PHI/ALPHA
71  TA=ALPHA*TIMEA/(ASMALL*ASMALL)
72  TB=ALPHA*TIMEB/(ASMALL*ASMALL)
73  TC=ALPHA*TIMEC/(ASMALL*ASMALL)
74  TD=ALPHA*TIMED/(ASMALL*ASMALL)
75  TM=ALPHA*TIMEM/(ASMALL*ASMALL)
76  TI=ALPHA*TIMEI/(ASMALL*ASMALL)
77  TF=ALPHA*TIMEF/(ASMALL*ASMALL)
100 SOTA = SIN(DM*TA)
101 SOTB = SIN(DM*TB)
102 SOTC = SIN(DM*TC)
103 SOTD = SIN(DM*TD)
104 COTA = COS(DM*TA)
105 COTB = COS(DM*TB)
106 COTC = COS(DM*TC)
107 COTD = COS(DM*TD)
110 LCM1 = LC-1.
111 GLM1=GL-1.
112 DOM = D/OM
113 POM = P/OM
114 EPA = EXP(P*TA)
115 EPB = EXP(P*TB)
116 EPC = EXP(P*TC)
117 EPD = EXP(P*TD)
120 EMA = EXP(-P*TA)
121 EMB = EXP(-P*TB)
122 EMC = EXP(-P*TC)
123 EMD = EXP(-P*TD)

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124      TBMTA = TB-TA
125      TCMTB = TC-TB
126      TDMTC = TD-TC
127      C = 1. / (1.+U*S)
130      F = (C/6.)*(3.*XI*XI+2.*S*S-6.*U*S*XI-1.-2.*S*(S+U)*C)
131      DO 20 I=1,N
132      C      L(I) = THE ITH EIGENVALUE (LAMBDA)
133      LL(I) = L(I)*L(I)
134      LLOM(I) = LL(I)/OM
135      LLOM2(I) = LLOM(I)*LLOM(I)
136      E(I) = .0.25*LL(I)*((1.+U)*(1.+S)*COS(L(I)*(1.+S))+(1.-U)*(1.-S)*
137      C      COS(L(I)*(1.-S)))
138      G(I)= (0.5/E(I))*((1.+U)*COS(L(I)*(S-XI))+(1.-U)*COS(L(I)*(S+XI)))
139      IF (LL(I)*TA.GE.86.) GO TO 17
140      EMTA(I)=EXP(-LL(I)*TA)
141      GO TO 31
142      EMTA(I)=0.0
143      IF (LL(I)*TBMTA.GE.86.) GO TO 32
144      17     EMBMA(I)=EXP(-LL(I)*TBMTA)
145      31     GO TO 21
146      151    EMBMA(I)=0.0
147      21     IF (LL(I)*TCMTB.GE.86.) GO TO 22
148      156    EMCMB(I)= EXP(-LL(I)*TCMTB)
149      22     GO TO 20
150      20     EMCMB(I)=0.0
151      CONTINUE
152      163    ARQK=ASMALL*R*Q0/CAPPA
153      C      DIMENSIONLESS TEMP=CAP THETA=(TEMP-TEMP INITIAL)/ARQK
154      A=ABAR*(ASMALL*ASMALL/ALPHA)**2
155      T = TI
156      PT =TI
157      SUM = 0.0
158      THETA = 0.0
159      J1 = 1
160      J2 = 2
161      J3 = 3
162      J4 = 4
163      C
164      C * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * *
165      C
166      175    WRITE (6,101) (TITLE(I),I=1,32)
167      101    FORMAT(1H1,24X,16A5/25X,16A5//)
168      202    IF (T.LE.TA) GO TO 100
169      203    IF (T.LE.TB) GO TO 200
170      206    IF (T.LE.TC) GO TO 300
171      211    IF (T.LE.TD) GO TO 400
172      C
173      C ** STAGE 1 *****
174      C
175      217    100   WRITE (6,102) J1, TI, TA
176      102   FORMAT(/30X,36HTHE FOLLOWING RESULTS ARE FOR STAGE ,I1,12H,TAU BET
177      1WEEN,F8.3,1X,3HAND,F8.3//22X13HDIMENSIONLESS,12X13HDIMENSIONLESS,
178      216X4HTIME,19X11HTEMPERATURE/23X10HTIME (TAU),15X11HTEMPERATURE,17X
179      35H(SEC),18X11H(DEGREES R)//)
180      105   THETA = 0.0

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222      EP = EXP( P*T)
223      EM = EXP(-P*T)
224      SOT = SIN(DM*T)
225      COT = COS(DM*T)
226      DO 106 I=1,4
227 106    GP(I) = 0.0
231      GP(1)=C/P*(EP-1.)+F*EP*(1.+D*SOT)
232      DO 109 I=1,N
233      IF (LL(I)*T.GE.86.) GO TO 107
236      EX=EXP(-LL(I)*T)
237      GO TO 108
240 107    EX=0.0
241 108    SUM=G(I)*(EX+P/(LL(I)+P)*(EP-EX))
242 109    GP(2)=GP(2)-SUM
244      GP(3)=C*EP/(POM*POM+1.)*DOM*(POM*SOT-COT+EM)
245      DO 111 I=1,N
246      IF ((LL(I)+P)*T.GE.86.) GO TO 131
251      EZ = EXP(-(LL(I)+P)*T)
252      GO TO 132
253 131    EZ = 0.0
254 132    SUM=G(I)*D*EP/((LLOM(I)+POM)**2+1.)*((POM*(LLOM(I)+POM)+1.)*SOT
1      +LLOM(I)*COT-LLOM(I)*EZ)
255 111    GP(4)=GP(4)-SUM
257      DO 112 I=1,4
260 112    THETA=THETA+GP(I)
262      TIME=ASMALL*ASMALL*ALPHA
263      TEMP=TEMPI+ARQK*THETA
264      C....PRINT OUT TIME
265 120    WRITE (6,120) T,THETA,TIME,TEMP
266      FORMAT(10X,4(10X,F15.8))
267      IF (T.LE.R1) GO TO 125
268      IF (T.LE.R2), GO TO 130
269      IF (T.LE.R3) GO TO 135
270      IF (T.LE.R4) GO TO 140
271      WRITE (6,124)
272      GO TO 1
273 125    T = T + DT1
274      GO TO 110
275 130    T = T + DT2
276      GO TO 110
277 135    T = T + DT3
278      GO TO 110
279 140    T = T + DT4
280      IF (T.LE.TA) GO TO 105
281      IF (T.LE.TB) GO TO 200
282      WRITE (6,121)
283      IF (T.LE.TC) GO TO 300
284      WRITE (6,122)
285      IF (T.LE.TD) GO TO 400
286      WRITE (6,123)
287      GO TO 1
288 121    FORMAT(/1X,49H DT IS GREATER THAN (TB-TA). HENCE SKIP STAGE 2.//)
289 122    FORMAT(/1X,49H DT IS GREATER THAN (TC-TA). HENCE SKIP STAGE 3.//)
290 123    FORMAT(/1X,49H DT IS GREATER THAN (TD-TA). HENCE SKIP STAGE 4.//)
291 124    FORMAT(/1X,49H TA IS GREATER THAN R4. HENCE SKIP STAGES 2,3,4.//)

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C
C ** STAGE 2 *****
C
337 200  WRITE (6,102) J2,TA,TB
340 205  THETA = 0.0
341  SOT=SIN(OM*T)
342  COT=COS(OM*T)
343  TMTB=T-TB
344  TMTA=T-TA
345  DO 206 I=1,100
346 206  GP(I)=0.0
350  GP(1)=C*(TMTA*EPA+(EPA-1.)/P)
351  GP(2)=C*DOM*EPA/(POM*POM+1.)*(POM*SOTA-COTA+EMA)
352  DO 209 I=1,N
353  IF (LL(I)*TMTA.GE.86.) GO TO 207
356  EMTTA(I)=EXP(-LL(I)*TMTA)
357  GO TO 208
360 207  EMTTA(I) =0.0
361 208  SUM=G(I)/(LL(I)/P+1.)*EMTTA(I)*(EPA+LL(I)/P*EMTA(I))
362 209  GP(3)=GP(3)-SUM
364  DO 211 I=1,N
365  SUM=G(I)*EMTTA(I)/((POM+LLOM(I))**2+1.)*((POM*(POM+LLOM(I))*SOTA
      A +SOTA+LLOM(I)*COTA)*EPA-LLOM(I)*EMTA(I))
366 211  GP(4)=GP(4)-D*SUM
370  GP(5)=C*EPA*(DOM*(COTA-COT)+DOM/OM*LCM1/TBMTA*(-OM*TMTA*COT+SOT
      1 -SOTA)+LCM1/TBMTA*TMTA*TMTA/2.)
371  GP(6)=EPA*F*(1.+D*SOT)*(1.+LCM1/TBMTA*TMTA)
372  DO 212 I=1,N
373  Z=LLOM(I)
374  ZZ=LLOM2(I)
375  EML=EMTTA(I)
376 218  SUM=G(I)*(D/(ZZ+1.)*(Z*COT+SOT-(Z*COTA+SOTA)*EML)+LCM1/TBMTA*D
      1 *(TMTA/(ZZ+1.)*(Z*COT+SOT)-1./(OM*(Z+1.)*2)*(ZZ*COT+2.*Z
      2 *SOT-COT-(ZZ*COTA+2.*Z*SOTA-COTA)*EML))+LCM1/(TBMTA*LL(I))
      3 *(1.-EML)+LCM1/TBMTA*DOM/(ZZ+1.)*(Z*SOT-COT-(Z*SOTA-COTA)*EML
      4 ))
377 212  GP(7)=GP(7)-EPA*SUM
401  DO 213 I=1,7
402 213  THETA=THETA+GP(I)
404  TIME=ASMALL*ASMALL*T/ALPHA
405  TEMP=TEMP1+ARQK*THETA
C....PRINT OUT TIME
406  WRITE (6,120) T,THETA,TIME,TEMP
407  IF (T.LE.R1) GO TO 225
412  IF (T.LE.R2) GO TO 230
415  IF (T.LE.R3) GO TO 235
420  IF (T.LE.R4) GO TO 240
423  WRITE (6,224)
424  GO TO 1
425 225  T = T + DT1
426  GO TO 210
427 230  T = T + DT2
430  GO TO 210
431 235  T = T + DT3
432  GO TO 210

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433 240 T = T + DT4
434 210 IF(T.LE.TB) GO TO 205
437 IF(T.LE.TC) GO TO 300
442 WRITE(6,222)
443 IF(T.LE.TD) GO TO 400
446 WRITE(6,223)
447 GO TO 1
450 222 FORMAT(/1X,49H DT IS GREATER THAN (TC-TB). HENCE SKIP STAGE 3.//)
451 223 FORMAT(/1X,49H DT IS GREATER THAN (TD-TB). HENCE SKIP STAGE 4.//)
452 224 FORMAT(/1X,49H TB IS GREATER THAN R4. HENCE SKIP STAGES 3, 4. //)
C
C ** STAGE 3 *****
C
453 300 WRITE (6,102) J3,TB,TC
454 305 THETA = 0.0
455 SOT=SIN(DM*T)
456 COT=COS(DM*T)
457 TMTA=T-TA
460 TMTB=T-TB
461 DO 304 I=1,N
462 304 GP(I)=0.0
464 DO 306 I=1,N
465 IF (LL(I)*TMTA.GE.86.) GO TO 317
470 EMTTA(I)=EXP(-LL(I)*TMTA)
471 GO TO 318
472 317 EMTTA(I)=0.0
473 318 IF (LL(I)*TMTB.GE.86.) GO TO 315
476 EMTTB(I)=EXP(-LL(I)*TMTB)
477 GO TO 306
500 315 EMTTB(I)=0.0
501 306 CONTINUE
C
503 EMBMA(I)=EXP(-LL(I)*TBMTA) WAS CALCULATED PREVIOUSLY
504 GP(1)=C*(TMTA*(1.+D*SOTA)*EPA+(EPA-1.)/P)
505 GP(2)=C*DOM*EPA/(POM*POM+1.)*(POM*SOTA-COTA+1./EPA)
506 DO 307 I=1,N
507 SUM=G(I)/(LL(I)/P+1.)*EMTTA(I)*(EPA+LL(I)/P*EMTA(I))
510 307 GP(4)=GP(4)-SUM
512 DO 308 I=1,N
513 SUM=G(I)*EMTTA(I)/((POM+LLOM(I))**2+1.)*((PDM*(POM+LLOM(I))*SOTA
      A +SOTA+LLOM(I)*COTA)*EPA-LLOM(I)*EMTA(I))
514 308 GP(5)=GP(5)-D*SUM
516 GP(6)=EPA*C*(DOM*(OM*T*SOTB-COTB-DM*TB*SOTB-DM*T*SOTA+COTA+DM*TA*
      1*SOTA)+LCM1/TBMTA*DOM/OM*(SOTB-SOTA)-LCM1*DOM*(COTB+DM*TB*SOTB-DM*
      2*T*SOTB)+LCM1*(T-0.5*(TB+TA)))
517 GP(7)=EPA*F*(D*(SOTB-SOTA)+LCM1*(1.+D*SOTB))
520 DO 309 I=1,N
521 SUM=G(I)*EMTTB(I)*(D/(LLOM2(I)+1.)*(LLOM(I)*COTB+SOTB-(LLOM(I)*
      1*COTA+SOTA)*EMBMA(I))+LCM1/TBMTA*D*(TBMTA/(LLOM2(I)+1.)*(LLOM(I)*
      2*COTB+SOTB)-1./{OM*(LLOM2(I)+1.)*2}*(LLOM2(I)*COTB+2.*LLOM(I)*
      3*SOTB-COTB-(LLOM2(I)*COTA+2.*LLOM(I)*SOTA-COTA)*EMBMA(I))+
      4LCM1/(TBMTA*LL(I))*(1.-EMBMA(I))+LCM1/TBMTA*DOM/(LLOM2(I)+1.)*
      5(LLOM(I)*SOTB-COTB-(LLOM(I)*SOTA-COTA)*EMBMA(I)))
522 309 GP(8)=GP(8)-EPA*SUM
524 GP(9)=C*(-A*(T*T*T/3.-T*TB*TB+2.73.*TB*TB*TB-TM*TMTB*TMTB)+DOM*-

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1(GC-A*TM*TM)*(-COT-OM*T*SOTB+COTB+OM*TB*SOTB)-2.*A*DOM/(OM*OM)*
2(-OM*T*SOT-2.*COT-OM*T*SOTB+OM*OM*T*TB*COTB+2.*OM*TB*SOTB-COTB*
3((OM*TB)**2-2.))+2.*A*TM*DOM/OM*(-SOT+SOTB+OM*TMTB*COTB)+2.*A*TM*
4DOM/OM*(-OM*T*COT+2.*SOT-OM*T*COTB-OM*OM*T*TB*SOTB+2.*OM*TB*COTB
5+OM*OM*TB*TB*SOTB-2.*SOTB) - A*DOM/OM/OM*(-OM*OM*T*T*COT-2.*OM*T*
6SOT+6.*COT+6.*OM*T*SOT-2.*OM*OM*T*TB*COTB-OM*T*(OM*OM*T*TB*TB-2.)*
7SOTB+(3.*OM*OM*T*TB*TB-6.)*COTB+(OM*TB)*3*SOTB-6.*OM*TB*SOTB))
525 GP(10)=F*(-A*(T*T-TB*TB)+2.*A*TM* TMTB +D*(GC-A*TM*TM)*(SOT-SOTB)
1-2.*A*DOM/OM*(SOT-OM*T*COT-SOTB+OM*TB*COTB)+2.*A*TM*DOM*(COTB+OM*
2T*SOT-COTB-OM*TB*SOTB)-A*DOM/OM*(2.*OM*T*COT+OM*OM*T*T*SOT-2.*SOT
3-2.*OM*TB*COTB-OM*OM*T*TB*SOTB+2.*SOTB))

526 DO 311 I=1,N
527 X1= 2.*A/(LL(I)*LL(I)) *( (LL(I)*T-1.)-(LL(I)*TB-1.)*EMTTB(I))
530 X2=-2.*A*TM/LL(I)*(1.-EMTTB(I))-D*(GC-A*TM*TM)/(LLOM2(I)+1.)
8 * (LLOM(I)*COT+SOT-(LLOM(I)*COTB+SOTB)*EMTTB(I))
531 X3= 2.*A*D*(1./OM
C /(LLOM2(I)+1.)*(T*(LLOM(I)*SOT-COT)-TB*(LLOM(I)*SOTB-COTB)
D *EMTTB(I))-1./(OM*(LLOM2(I)+1.))*2*(LLOM2(I)*SOT-2.*LLOM(I)
E *COT-SOT-(LLOM2(I)*SOTB-2.*LLOM(I)*COTB-SOTB)*EMTTB(I)))
532 Z=1./(LLOM2(I)+1.)
533 X4= -2.*A*D*TM*(Z/OM*(LLOM(I)*SOT-COT-(LLOM(I)*SOTB-COTB)
A *EMTTB(I)))
534 X5= -2.*A*D*TM*(Z*(T*(LLOM(I)*COT+SOT)-TB*(LLOM(I)*COTB+SOTB)
A *EMTTB(I))-Z*Z/OM*(LLOM2(I)*COT+2.*LLOM(I)*SOT-COT-(LLOM2(I)
B *COTB+2.*LLOM(I)*SOTB-COTB)*EMTTB(I)))
535 X6= Z*(T*T*(LLOM(I)*COT+SOT)-TB*TB*(LLOM(I)*COTB+SOTB)*EMTTB(I))
536 X7=-Z*Z/OM*(T*(2.*LLOM2(I)*COT+4.*LLOM(I)*SOT-2.*COT)-TB*(2.
A *LLOM2(I)*COTB+4.*LLOM(I)*SOTB-2.*COTB)*EMTTB(I))
537 X8= 2.*Z*3/OM/OM*(LLOM2(I)*LLOM(I)*COT+3.*LLOM2(I)*SOT-3.*LLOM(I)
A *COT-SOT-(LLOM2(I)*LLOM(I)*COTB+3.*LLOM2(I)*SOTB-3.*LLOM(I)
B *COTB-SOTB)*EMTTB(I))
540 SUM=X1+X2+X3+X4+X5+A*D*(X6+X7+X8)
541 311 GP(11)=GP(11)+G(I)*SUM
543 DO 312 I=1,11
544 312 THETA=THETA+GP(I)
546 TIME=ASMALL*ASMALL*T/ALPHA
547 TEMP=TEMPI+ARQK*THETA
C....PRINT OUT TIME
550 WRITE (6,120) T,THETA,TIME,TEMP
551 IF (T.LE.R1) GO TO 325
554 IF (T.LE.R2) GO TO 330
557 IF (T.LE.R3) GO TO 335
562 IF (T.LE.R4) GO TO 340
565 WRITE (6,324)
566 GO TO 1
567 325 T = T + DT1
570 GO TO 310
571 330 T = T + DT2
572 GO TO 310
573 335 T = T + DT3
574 GO TO 310
575 340 T = T + DT4
576 310 IF (T.LE.TC) GO TO 305
601 IF (T.LE.TD) GO TO 400
604 WRITE (6,323)

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605      GO TO 1
606 323  FORMAT(1X,49H DT IS GREATER THAN (TD-TC). HENCE SKIP STAGE 4.//)
607 324  FORMAT(1X,49H TC IS GREATER THAN R4. HENCE SKIP STAGE 4.    //)
C
C ** STAGE 4 ****
C
610 400  WRITE (6,102) J4,TC,TD
611 405  THETA = 0.0
612      SOT=SIN(DM*T)
613      COT=COS(DM*T)
614      TMTA=T-TA
615      TMTB=T-TB
616      TMTC=T-TC
617      TMTD=T-TD
620      OT=DM*T
621      OTA=DM*TA
622      OTB=DM*TB
623      OTC=DM*TC
624      OTD=DM*TD
625      DO 406 I=1,N
626      IF (LL(I)*TMTA.GE.86.) GO TO 417
631      EMTTA(I)=EXP(-LL(I)*TMTA)
632      GO TO 418
633 417  EMTTA(I)=0.0
634 418  IF (LL(I)*TMTB.GE.86.) GO TO 407
637      EMTTB(I)= EXP(-LL(I)*TMTB)
640      GO TO 408
641 407  EMTTB(I)=0.0
642 408  IF (LL(I)*TMTC.GE.86.) GO TO 409
645      EMTTC(I)=EXP(-LL(I)*TMTC)
646      GO TO 406
647 409  EMTTC(I)=0.0
650 406  CONTINUE
C
652      DO 450 I=1,100
653 450  GP(I)=0.0
655      GP(1)=C*(TMTA*(1.+D*SOTA)*EPA+(EPA-1.)/P)
656      GP(2)=C*DOM*EPA/(POM*POM+1.)*(POM*SOTA-COTA+1./EPA)
657      GP(3)=F*(1.+D*SOTA)*EPA
660      DO 451 I=1,N
661      SUM=G(I)*EMTTA(I)/(LL(I)/P+1.)*(EPA+LC(I)/P*EMTA(I))
662 451  GP(4)=GP(4)-SUM
664      DO 452 I=1,N
665      SUM=G(I)*EMTTA(I)/((POM+LLOM(I))**2+1.)*((POM*(POM+LLOM(I))*SOTA
1      +SOTA+LLOM(I)*COTA)*EPA-LLOM(I)*EMTA(I))
666 452  GP(5)=GP(5)-D*SUM
670      GP(6)=EPA*C*(DOM*(OT*SOTB-COTB-OTB*SOTB-OT*SOTA+COTA+OTA*SOTA)
A      +LCM1/TBMTA*DOM/OM*(SOTB-SOTA)-LCM1*DOM*(COTB+OTB*SOTB-OT
B      *SOTB)+LCM1*(T-0.5*(TB+TA)))
671      GP(7)=EPA*F*(D*(SOTB-SOTA)+LCM1*(1.+D*SOTB))
672      DO 453 I=1,N
673      SUM=G(I)*EMTTB(I)*(D/(LLOM2(I)+1.)*(LLOM(I)*COTB+SOTB-(LLOM(I)
1      *COTA+SOTA)*EMBMA(I))+LCM1/TBMTA*D*(TBMTA/(LLOM2(I)+1.)
2      *(LLOM(I)*COTB+SOTB)-1./{OM*((LLOM2(I)+1.)**2)}*(LLOM2(I)*COTB
3      +2.*LLOM(I)*SOTB-COTB-(LLOM2(I)*COTA+2.*LLOM(I)*SOTA-COTA)

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4   *EMBMA(I))) + LCM1/TBMTA/LL(I)*(1.-EMBMA(I)) + LCM1/TBMTA
5   *DOM/(LLOM2(I)+1.)*(LLOM(I)*SOTB-COTB-(LLOM(I)*SOTA-COTA)
6   *EMBMA(I)))
674 453 GP(8)=GP(8)-EPA*SUM
676   X1= -A*T*TC*TC+2./3.*A*TC*TC*TC+A*T*TB*TB-2./3.*A*TB*TB*TB
      A   +2.*A*TM*(T*TC-TC*TC/2.-T*TB*TB*TB/2.)+DOM*(GC-A*TM*TM)
      B   +(OT*SOTC-COTC-OTC*SOTC-OT*SOTB+COTB+OTB*SOTB)-2.*A*DOM
      C   /(OM*OM)*(OT*SOTC-OTC*COTC-2.*OTC*SOTC+(OTC*OTC-2.)*COTC
      D   -OT*SOTB+OT*OTB*COTB+2.*OTB*SOTB-(OTB*OTB-2.)*COTB)+2.*A
      E   *DOM/DM*TM*(-OT*COTC-SOTC+OTC*COTC+OT*COTB+SOTB-OTB*COTB)
677   X2= 2.*A*TM*DOM/OM*(OT*COTC+OTC*SOTC-2.*OTC*COTC-(OTC*OTC-2.))
      A   *SOTC-OT*COTB-OT*OTB*SOTB+2.*OTB*COTB+(OTB*OTB-2.)*SOTB)
      B   -A*DOM/(OM*OM)*(2.*OT*OTC*COTC+OT*(OTC*OTC-2.)*SOTC-(3.*OTC
      C   *OTC-6.)*COTC-(OTC**3   -6.*OTC)*SOTC-2.*OT*OTB*COTB-OT*
      D   (OTB*OTB-2.)*SOTB+(3.*OTB*OTB-6.)*COTB+(OTB**3-6.*OTB)*SOTB)
700   GP(9)=C*(X1+X2)
701   GP(10)=F*(-A*(TC*TC-TB*TB)+2.*A*TM*TCMTB+D*(GC-A*TM*TM)*(SOTC-
      A   SOTB)-2.*A*DOM/OM*(SOTC-OTC*COTC-SOTB+OTB*COTB)+2.*A*TM*DOM
      B   *(COTB-COTC)+2.*A*TM*DOM*(COTC+OTC*SOTC-COTB-OTB*SOTB)
      C   -A*DOM/OM*(2.*OTC*COTC+OTC*SOTC-2.*SOTC-2.*OTB*COTB
      D   -OTB*OTB*SOTB+2.*SOTB))
C
702   DO 454 I=1,N
703   X1=2.*A/(LL(I)*LL(I))*((LL(I)*TC-1.)-(LL(I)*TB-1.)*EMCMB(I))
1   -2.*A*TM/LL(I)*(1.-EMCMB(I))
704   Y=1./(LLOM2(I)+1.)
705   X2=-D*(GC-A*TM*TM)*Y*(TLLOM(I)*COTC+SOTC-TLLOM(I)*COTB+SOTB)
1   *EMCMB(I))
706   X3=2.*A*D*(Y/OM*(TC*(TLLOM(I)*SOTC-COTC)-TB*(TLLOM(I)*SOTB-COTB)
1   *EMCMB(I))-Y*Y/(OM*OM)*(LLOM2(I)*SOTC-2.*LLOM(I)*COTC-SOTC
2   -(LLOM2(I)*SOTB-2.*LLOM(I)*COTB-SOTB)*EMCMB(I)))
707   X4=-2.*A*D*TM*(Y/OM*(LLOM(I)*SOTC-COTC-(LLOM(I)*SOTB-COTB)
1   *EMCMB(I)))
710   X5=-2.*A*D*TM*(Y*(TC*(LLOM(I)*COTC+SOTC)-TB*(LLOM(I)*COTB+SOTB)
A   *EMCMB(I))-Y*Y/OM*(LLOM2(I)*COTC+2.*LLOM(I)*SOTC-COTC-(LLOM2(I)
B   *COTB+2.*LLOM(I)*SOTB-COTB)*EMCMB(I)))
711   X6=Y*(TC*TC*(LLOM(I)*COTC+SOTC)-TB*TB*TLLOM(I)*COTB+SOTB)
1   *EMCMB(I))
712   W=Y*Y
713   X7=-W/OM*(TC*(2.*LLOM2(I)*COTC+4.*LLOM(I)*SOTC-2.*COTC)-TB*(2.
1   *LLOM2(I)*COTB+4.*LLOM(I)*SOTB-2.*COTB)*EMCMB(I))
714   X8=2.*Y*Y*Y/(OM*OM)*(LLOM2(I)*LLOM(I)*COTC+3.*LLOM2(I)*SOTC
1   -3.*LLOM(I)*COTC-SOTC-(LLOM2(I)*LLOM(I)*COTB+3.*LLOM2(I)*SOTB
2   -3.*LLOM(I)*COTB-SOTB)*EMCMB(I))
715   SUM=X1+X2+X3+X4+X5+A*D*(X6+X7+X8)
716 454 GP(11)=GP(11)+G(I)*EMTTC(I)*SUM
720   GP(12)=C*B*(GLM1/(2.*TDMTC)*TMTTC*TMTTC+D*GLM1/TDMTC*(1./(OM*OM)
1   *(SOTC-SOT)+COTC*TMTTC/OM)+D*((COTC-COT)/OM-TMTTC*SOTC)
2   +GLM1/TDMTC*DOM/OM*(OM*(T+TC)*(COT+COT*SOTC-COTC*SOTC)
3   -2.*OT*COT-(OT*OT-2.)*SOT+2.*OTC*COTC+(OTC*OTC-2.)*SOTC
4   -OT*OTC*(SOT-SOTC)))
721   GP(13)=F*B*(GLM1/TDMTC*TMTTC*(1.+D*SOT)+D*(SOT-SOTC))
722   DO 455 I=1,N
723   Y=1./(LLOM2(I)+1.)
724   X1=GLM1/TDMTC/LL(I)*(1.-EMTTC(I))+DOM*GLM1/TDMTC*Y*(TLLOM(I)*SOT

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1   -COT-(LLOM(I)*SOTC-COTC)*EMTTC(I))
725   X2=D*Y*(LLOM(I)*COT+SOT-(LLOM(I)*COTC+SOTC)*EMTTC(I))
726   X3=GLM1/TDMTC*D*(TMTC*Y*(LLOM(I)*COT+SOT)-Y*Y/OM*(LLOM2(I)*COT
1   +2.*LLOM(I)*SOT-COT-(LLOM2(I)*COTC+2.*LLOM(I)*SOTC-COTC)
2   *EMTTC(I)))
727   SUM=X1+X2+X3
730 455   GP(14)=GP(14)-G(I)*B*SUM
732   DO 456 I=1,14
733 456   THETA=THETA+GP(I)
735   TIME=ASMALL*ASMALL*T/ALPHA
736   TEMP=TEMP1+ARQK*THETA
C....PRINT OUT TIME
737   WRITE (6,120) T,THETA,TIME,TEMP
740   IF (T.LE.R1) GO TO 425
743   IF (T.LE.R2) GO TO 430
746   IF (T.LE.R3) GO TO 435
751   IF (T.LE.R4) GO TO 440
754   WRITE (6,424)
755   GO TO 1
756 425   T = T + DT1
757   GO TO 410
760 430   T = T + DT2
761   GO TO 410
762 435   T = T + DT3
763   GO TO 410
764 440   T = T + DT4
765 410   IF (T.LE.TD) GO TO 405
770   WRITE (6,423)
771   GO TO 1
772 423   FORMAT(/1X,49H* T IS GREATER THAN TD. THIS CASE IS COMPLETE. *//)
773 424   FORMAT(/1X,49H* T IS GREATER THAN R4. THIS CASE IS COMPLETE. *//)
774   END

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